

Lecture 22: Copositive Programming

(1)

The following claim was used in the proof of the Motzkin-Straus theorem.

Claim: $\sum_{i=1}^k x_i^2$ is minimized subject to $\sum_{i=1}^k x_i = 1$

when all the x_i -values are equal to $\frac{1}{k}$.

Proof: Minimizing $\sum_{i=1}^k x_i^2$ subject to $\sum_{i=1}^k x_i = 1$ is equivalent to minimizing $\sum_{i=1}^{k-1} x_i^2 + (1 - \sum_{i=1}^{k-1} x_i)^2$.

$$\text{Let } h(x_1, \dots, x_{k-1}) = \sum_{i=1}^{k-1} x_i^2 + (1 - \sum_{i=1}^{k-1} x_i)^2$$

$$= 2(x_1^2 + \dots + x_{k-1}^2) + 2 \sum_{i < j} x_i x_j - 2(x_1 + \dots + x_{k-1}) + 1$$

∇h = $(\frac{\partial h}{\partial x_1}, \frac{\partial h}{\partial x_2}, \dots, \frac{\partial h}{\partial x_{k-1}})$.

the gradient of h

$$\text{Observe that } \frac{\partial h}{\partial x_i} = 4x_i + 2 \sum_{j \neq i} x_j - 2 = 2(x_i - x_k).$$

To find the minimizer, we need to solve for

$$\nabla h = 0. \text{ So } x_i = x_k \text{ for } 1 \leq i \leq k-1.$$

So the only critical point for h is $(\frac{1}{k}, \frac{1}{k}, \dots, \frac{1}{k})$.

Easy to check that this point is a minimizer.

Thus $\sum_{i=1}^k x_i^2$ is minimized subject to $\sum_{i=1}^k x_i = 1$

when all the x_i -values are equal to $\frac{1}{k}$. \square

(2)

This finishes the proof of the Motzkin-Straus Thm.
We'll now see a complexity result that follows
from the ~~proof~~ of the Motzkin-Straus Theorem.

Theorem. Given an integer matrix $M \in \text{SYM}_n$,
it is coNP-complete to decide whether $M \in \text{COP}_n$.

Proof. If $M \notin \text{COP}_n$ then there exists $x \in \mathbb{R}_+^n$ such
that $x^T M x < 0$. However we should be careful
here - we need to show there exists such an
 $x \in \mathbb{R}_+^n$ whose binary encoding length is polynomial
in the binary encoding length of M . In other words,
we need to show a compact certificate of M 's
non-membership in COP_n . (Please do this as an exercise.)

To show this problem $M \notin \text{COP}_n$ is NP-hard,
we'll show a reduction from the independent set
problem: given a graph G and an integer k ,
does G have an independent set of size $> k$?

Claim: The matrix $kI_n + kA_G - J_n \notin \text{COP}_n$
if and only if $\alpha_G > k$.

So G has an independent set of size larger
than $k \iff$ the above matrix is not in COP_n . \square

Proof of the claim. Let $M = kI_n + kA_G - J_n$.

If $M \in \text{COP}_n$ then $x^T (kI_n + kA_G - J_n) x \geq 0$ for
all $x \in \mathbb{R}_+^n$. Thus $k \cdot x^T (I_n + A_G) x \geq x^T J_n x = 1$
for all $x \in \mathbb{R}_+^n$ and $\sum_{i=1}^n x_i = 1$.

That is, $\min \{ x^T (I_n + A_G) x : x \in \mathbb{R}_+^n, \sum_{i=1}^n x_i = 1 \} \geq 1/k$.

Since the value on the left equals $\frac{1}{\alpha_G}$ (by Motzkin-Straus theorem), we have $k \geq \alpha_G$.

Thus $M \in \text{COP}_n \Rightarrow k \geq \alpha_G$.

Conversely, if $k \geq \alpha_G$ then
 As seen in the previous lecture, this implies that $x^T M x \geq 0$ for $x \in \mathbb{R}_+^n$.

$$\min \left\{ x^T (\mathbb{I}_n + A_G) x : x \in \mathbb{R}_+^n \text{ and } \sum_{i=1}^n x_i = 1 \right\} = \frac{1}{\alpha_G} \geq \frac{1}{k}$$

Thus $M \in \text{COP}_n$.

Hence $M \notin \text{COP}_n \Leftrightarrow G$ has an independent set of size larger than k . (since $\alpha_G > k$) \square

Colorings with Low Discrepancy

Let $V = \{1, 2, \dots, n\}$ and let $\mathcal{F} = \{S_1, \dots, S_m\}$ be a family of subsets of V .

The basic problem in combinatorial discrepancy theory is to color each $i \in V$ either red or blue so that each of the sets in \mathcal{F} has roughly the same number of red elements and blue elements.

Suppose $\mathcal{F} = 2^V$, i.e., \mathcal{F} consists of all subsets of V . Then no matter how we color the elements of V , there is always a completely monochromatic set of size $\geq n/2$.

Definition. Let $\chi : V \rightarrow \{-1, +1\}$ be a coloring and for any $S \subseteq V$, let $\chi(S) = \sum_{i \in S} \chi(i)$. For $\mathcal{F} \subseteq 2^V$, let $\text{disc}(\mathcal{F}, \chi) = \max_{S \in \mathcal{F}} |\chi(S)|$. The discrepancy of \mathcal{F} is $\text{disc}(\mathcal{F}) = \min_{\chi} \text{disc}(\mathcal{F}, \chi)$.

If +1's are red and -1's are blue, then $\chi(S)$ is the number of red elements in S minus the number of blue elements in S — we will call this the imbalance of S under χ .

We will consider the algorithmic problem of computing a low-discrepancy coloring for a given set system. Discrepancy can be regarded as a measure of how complex a set system is. But it is not very well-behaved.

For example, let $F = 2^V$ and let V' be a disjoint copy of V and let $F' = 2^{V'}$. The set system $(V \cup V', \{S \cup S' : S \in F\})$ has discrepancy 0, yet we feel that it is as complex as F .

A better behaved measure is the hereditary discrepancy:

$$\text{herdisc}(F) = \max_{A \subseteq V} \text{disc}(F|_A),$$

where $F|_A$ is the restriction of the set system F to the ground set A , i.e., $F|_A = \{A \cap S : S \in F\}$.

In other words, the adversary selects a subset $A \subseteq V$ and we must color its elements red or blue so that each set in F is balanced; the elements outside A do not count.

We'll see the following result here.
Theorem. There is a randomized polynomial-time algorithm which, for an input set system F on n elements, with m sets, and with hereditary discrepancy at most H , computes a coloring χ with $\text{disc}(F, \chi) = O(H \cdot \log(mn))$.

The above algorithm, which will be called Bansal's algorithm, is based on SDP.

Bansal's algorithm. The desired coloring will be obtained through a sequence of semicolorings.

A semicoloring is a mapping $c: V \rightarrow [-1, 1]$. So a semicoloring is like a coloring but by real numbers in $[-1, 1]$. We define $\text{disc}(F, c)$ as $\max_{S \in F} \left| \sum_{j \in S} c(j) \right|$.

- The algorithm starts with the semicoloring $x_0 = 0$.
- Then it produces a sequence $x_0, x_1, \dots, x_\ell \in [-1, 1]^n$ of semicolorings. We'll see later what ℓ should be.
- With probability close to 1, the final semicoloring x_ℓ is actually a coloring, i.e., all coordinates are ± 1 's. This will be the output of the algorithm.
- If x_ℓ is not a coloring then we run the algorithm all over again.

The t-th step. Here x_{t-1} is updated to x_t as follows. First we generate an increment $\Delta_t \in \mathbb{R}^n$.

A "tentative value" of x_t is $\tilde{x}_t = x_{t-1} + \Delta_t$. However we need to ensure that each coordinate is in $[-1, 1]$. So we do the following:

$$(x_t)_j = \begin{cases} +1 & \text{if } (\tilde{x}_t)_j \geq 1, \\ -1 & \text{if } (\tilde{x}_t)_j \leq -1, \text{ and} \\ (\tilde{x}_t)_j & \text{otherwise.} \end{cases}$$

How do we generate the increment Δ_t ? Let $A_t = \{j \in V : (x_{t-1})_j \neq \pm 1\}$ be the set of coordinates that are still active in the t -th step. We will make sure that $(\Delta_t)_j = 0$ for all $j \notin A_t$.

- Via semidefinite programming, we compute a coloring of the elements in A_t by unit vectors (rather than ± 1 's).

More explicitly, we compute $u_{t,j}$ where $j \in A_t$ so that $\| \sum_{j \in S_i \cap A_t} u_{t,j} \|^2 \leq D^2$ for $i=1, \dots, m$

and $\| u_{t,j} \|^2 = 1,$

with $D \geq 0$ as small as possible.

Note that $u_{t,j} = 0$ for $j \notin A_t$.

- Similar to the Goemans-Williamson algorithm, we generate a random vector x_t from the n -dimensional normal distribution. That is, the coordinates of x_t are independent $N(0,1)$ random variables.

- Then we set $(\Delta_t)_j = s \cdot x_t^T u_{t,j}$ for $j=1, \dots, m$.

Here s is a small parameter. can be regarded as a random walk in the cube $[-1,1]^n$

- The length l of the sequence of semicolorings x_0, x_1, \dots, x_l will be set to $\frac{C \cdot \log n}{s^2}$ for a suitable constant C . (Note that $s = \Theta\left(\frac{1}{n \sqrt{\log n}}\right)$)

This concludes the description of Bansal's algorithm.