

Interlacing Families II: Mixed Characteristic Polynomials and the Kadison-Singer Problem

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Discrepancy Theory

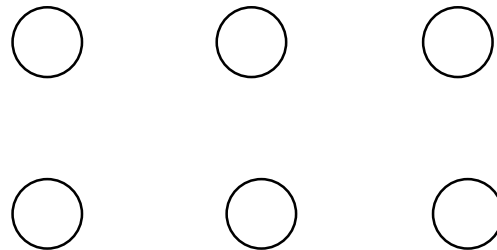
“How well can you approximate a discrete object by a continuous one.”

e.g. Given a set family $S_1, \dots, S_m \subset [n]$, find a red-blue coloring $[n] = R \cup B$ such that every set is half red and half blue.

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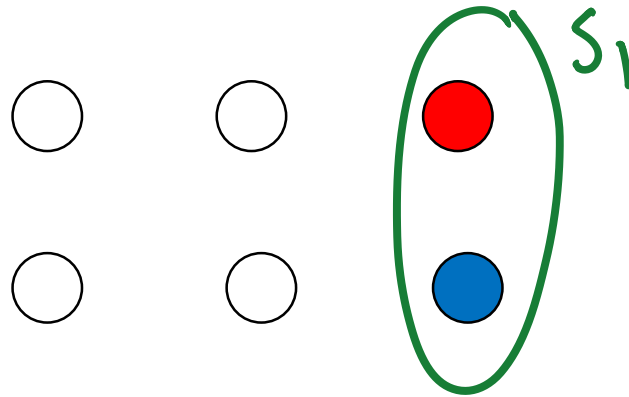
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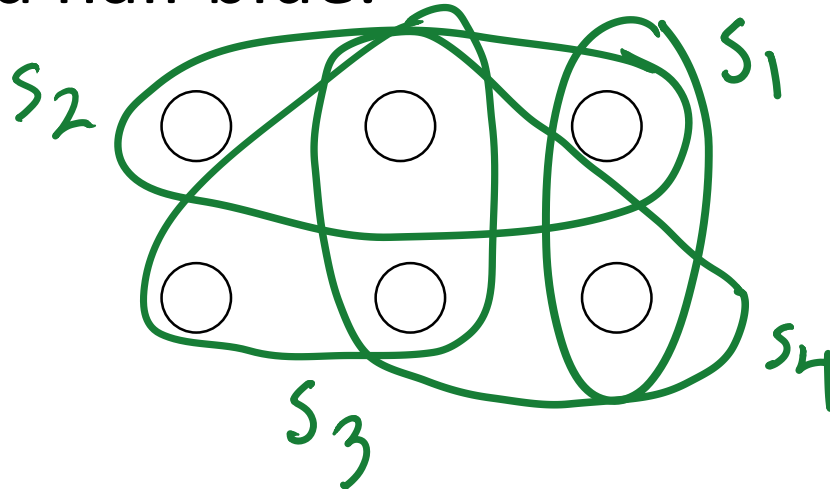
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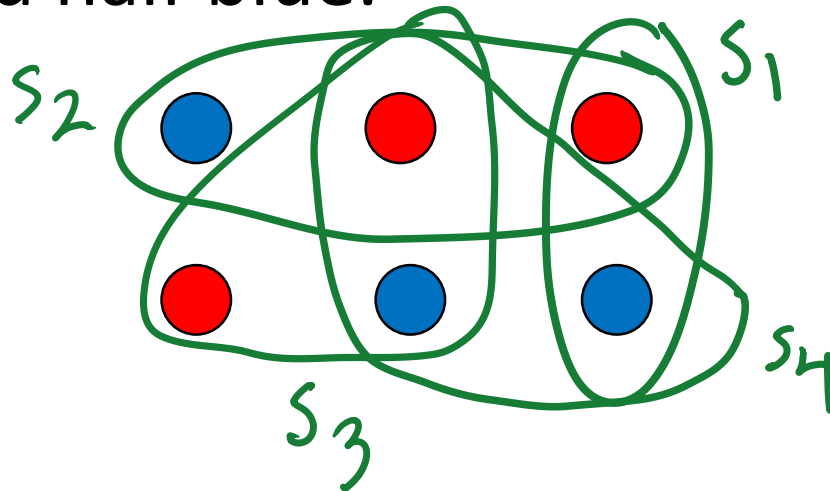
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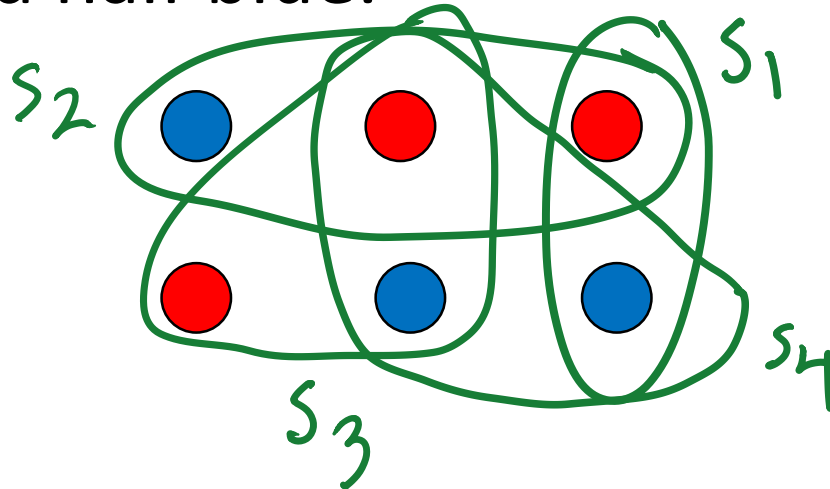


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disc = 1



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How well can you do in general?

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In general, a random coloring gives

$$\text{disc} := \max_i \left| |S_i \cap R| - \frac{|S_i|}{2} \right| \leq O(\sqrt{n \log m}).$$

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Spencer: There exists a coloring with

$$disc := \max_i \left| |S_i \cap R| - \frac{|S_i|}{2} \right| \leq 3 \sqrt{n \log\left(\frac{m}{n}\right)}.$$

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A Spectral Discrepancy Theorem

Quadratic Forms and Energy

Given vectors $v_1, \dots, v_m \in \mathbf{R}^n$, their **energy** in a test direction $u \in \mathbf{R}^n$, $\|u\| = 1$, is the quadratic form

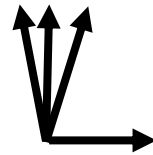
$$Q(u) := \sum_i \langle u, v_i \rangle^2$$

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Example.



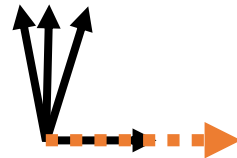
$$v_1, v_2, v_3, v_4 \in \mathbf{R}^2$$

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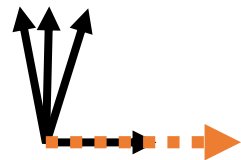
$$u = (1, 0)$$

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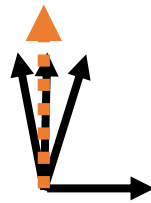
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$$\begin{aligned} &\langle u, v_1 \rangle^2 + \langle u, v_2 \rangle^2 \\ &+ \langle u, v_3 \rangle^2 + \langle u, v_4 \rangle^2 \\ &= 1 + 0 + \frac{1}{4} + \frac{1}{4} \\ &= 1.5 \end{aligned}$$

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Example.

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$$\begin{aligned} & \langle u, v_1 \rangle^2 + \langle u, v_2 \rangle^2 \\ & + \langle u, v_3 \rangle^2 + \langle u, v_4 \rangle^2 \\ & = 0 + 1 + \frac{3}{4} + \frac{3}{4} \\ & = 2.5 \end{aligned}$$

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$$\begin{aligned} &\langle u, v_1 \rangle^2 + \langle u, v_2 \rangle^2 \\ &+ \langle u, v_3 \rangle^2 + \langle u, v_4 \rangle^2 \\ &\quad \frac{1}{2} + \frac{1}{2} + \frac{3}{4} + \frac{1}{4} \\ &= 2 \end{aligned}$$

Example.

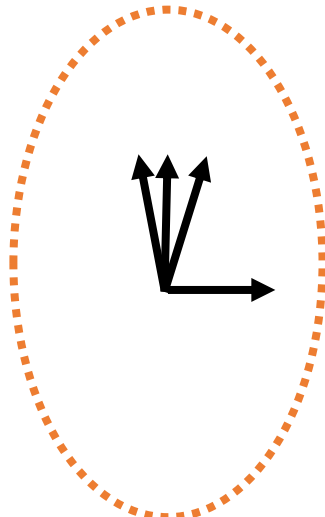
$$u = (1/\sqrt{2}, 1/\sqrt{2})$$

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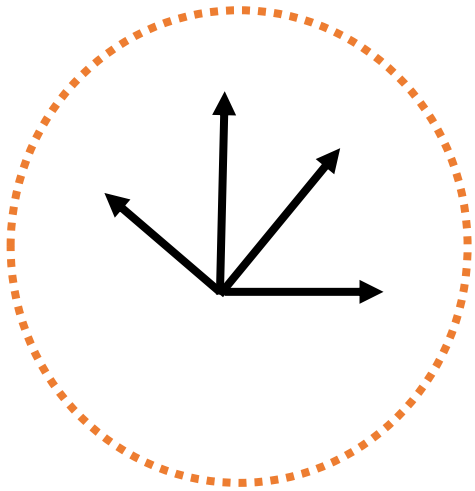
Example.



Splitting A Quadratic Form in Half

Main Theorem. Suppose $v_1, \dots, v_m \in \mathbf{R}^n$ are vectors $\|v_i\| \leq \epsilon$ and energy one in each direction:

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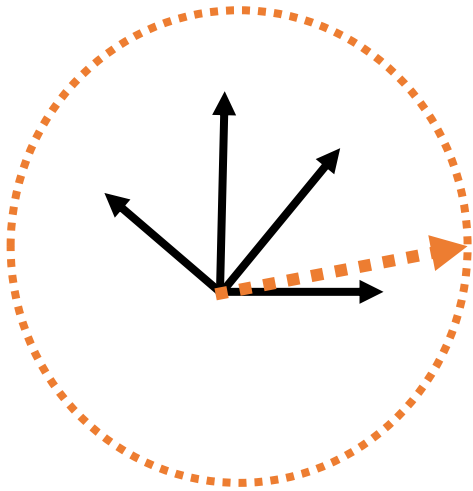
“isotropic”

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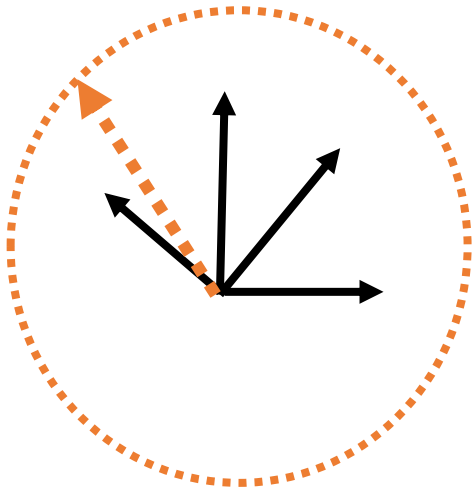


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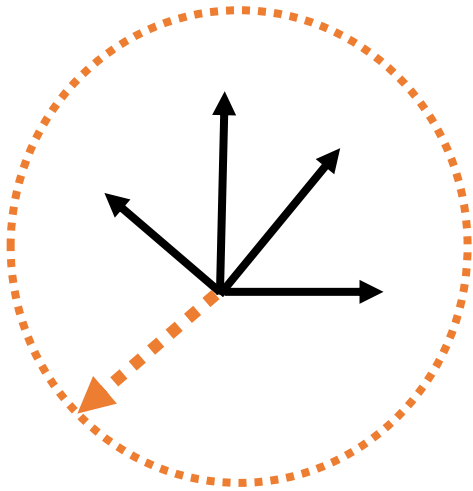


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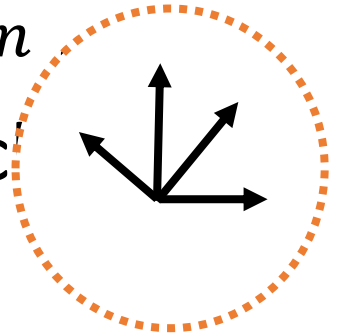


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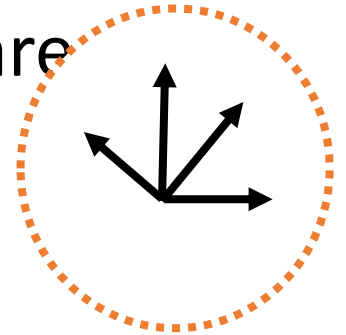
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Then there is a partition $T_1 \cup T_2$ such that **each part** has energy close to half in each direction:

$$\forall \|u\| = 1 \quad \sum_{i \in T_j} \langle u, v_i \rangle^2 = \frac{1}{2} \pm 5\epsilon$$

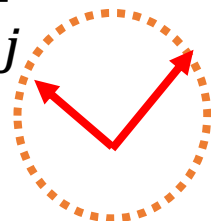
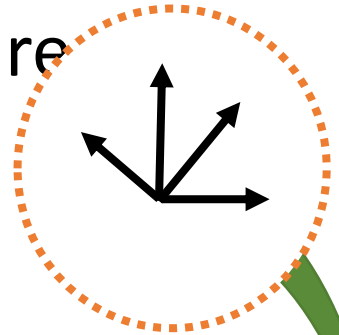
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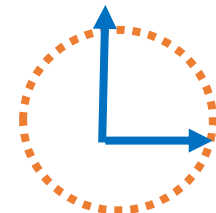
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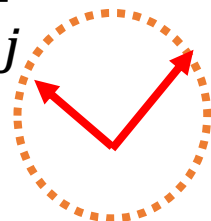
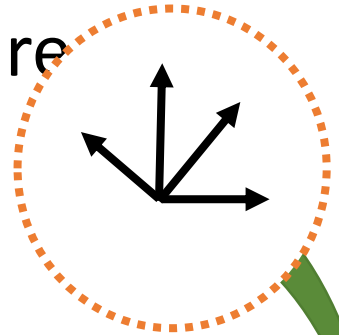
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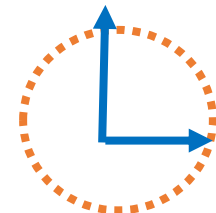
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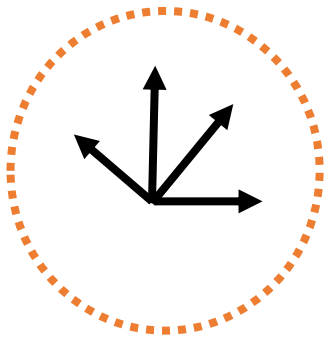
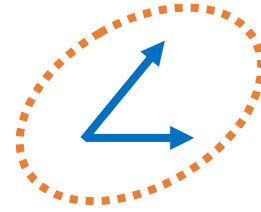
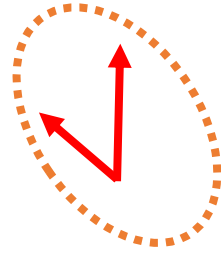
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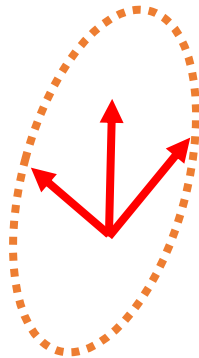
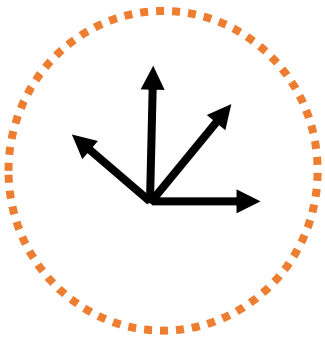
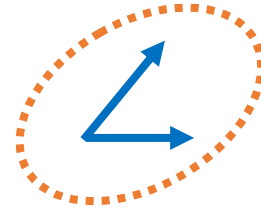
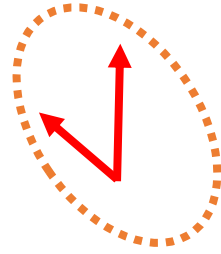
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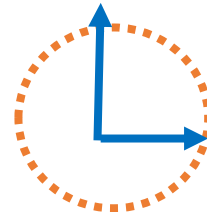
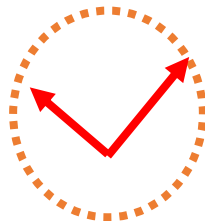
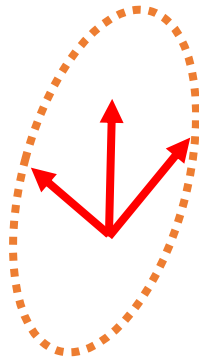
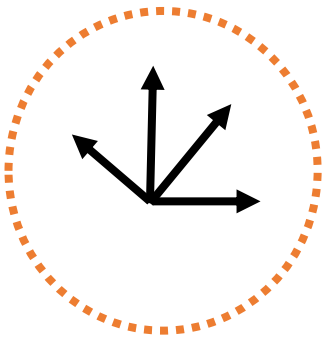
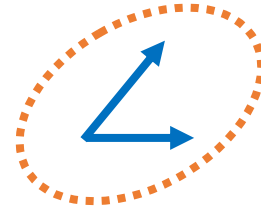
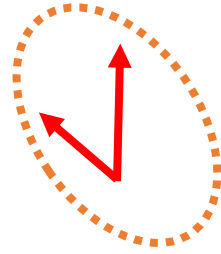
Many Possible Partitions



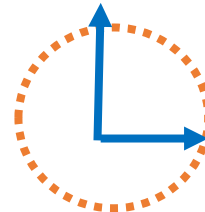
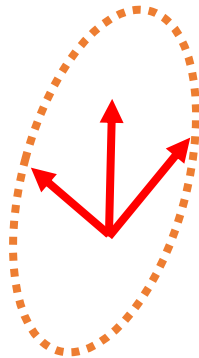
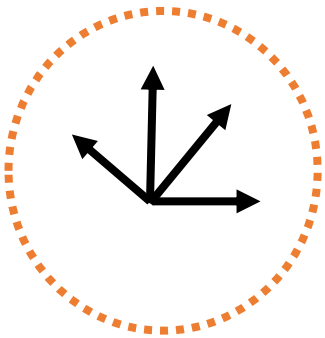
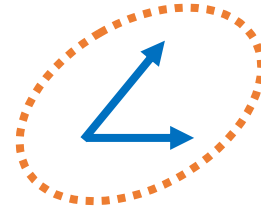
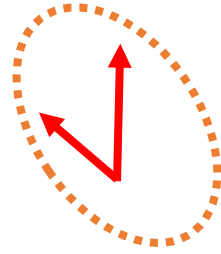
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Theorem: Good partition always exists.

The norm condition

Main Theorem. Suppose $v_1, \dots, v_m \in \mathbf{R}^n$ are vectors $\|v_i\| \leq \epsilon$ and energy one in each direction:

$$\forall \|u\| = 1 \quad \sum_i \langle u, v_i \rangle^2 = 1$$

Then there is a partition $T_1 \cup T_2$ such that **each part** has energy close to half in each direction:

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Main Theorem. Suppose $v_1, \dots, v_m \in \mathbf{R}^1$ are numbers with $|v_i| \leq \epsilon$ and energy one

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greedy bin
packing

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Optimal in high dim

Matrix Notation

Given vectors v_1, \dots, v_m write quadratic form as

$$Q(u) = \sum_i \langle v_i, u \rangle^2 = u^T \left(\sum_i v_i v_i^T \right) u$$

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Isotropy:

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Comparison:

$$A \preceq B \iff u^T A u \leq u^T B u \quad \forall u$$

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Unnormalized Version

Suppose I get some vectors w_1, \dots, w_m which are **not** isotropic:

$$\sum_i w_i w_i^T = W \succcurlyeq 0$$

Consider $v_i := W^{-\frac{1}{2}} w_i$ and apply theorem to v_i .

Normalized vectors have $\|v_i\|^2 = \|W^{-\frac{1}{2}} w_i\|^2 = \epsilon$

Thm. gives

$$\left(\frac{1}{2} - 5\sqrt{\epsilon}\right) I \preccurlyeq \sum_{i \in T_j} v_i v_i^T \preccurlyeq \left(\frac{1}{2} + 5\sqrt{\epsilon}\right) I$$

Unnormalized Version

Suppose I get some vectors w_1, \dots, w_m which are **not** isotropic:

$$\sum_i w_i w_i^T = W \succcurlyeq 0$$

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$$\text{Fact: } A \preceq B \iff CAC \preceq CBC \text{ for invertible } C$$

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Unnormalized Theorem

Given arbitrary vectors $w_1, \dots, w_m \in \mathbb{R}^n$ there is a partition $[m] = T_1 \cup T_2$ with

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Where $\epsilon := \max_i \|W^{-\frac{1}{2}} w_i\|^2$

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Where $\epsilon := \max_i \|W^{-\frac{1}{2}} w_i\|^2$

Any quadratic form in which no vector has too much influence can be split into two representative pieces.

Applications

1. Graph Theory

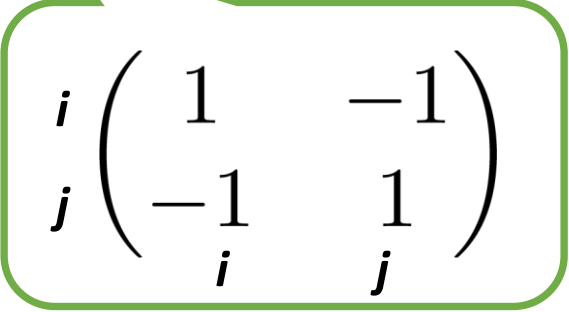
Given an undirected graph $G = (V, E)$, consider its Laplacian matrix:

$$L_G = \sum_{ij \in E} (\delta_i - \delta_j)(\delta_i - \delta_j)^T$$

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$$\begin{matrix} i \\ j \end{matrix} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \begin{matrix} i \\ j \end{matrix}$$

1. Graph Theory

Given an undirected graph $G = (V, E)$, consider its Laplacian matrix:

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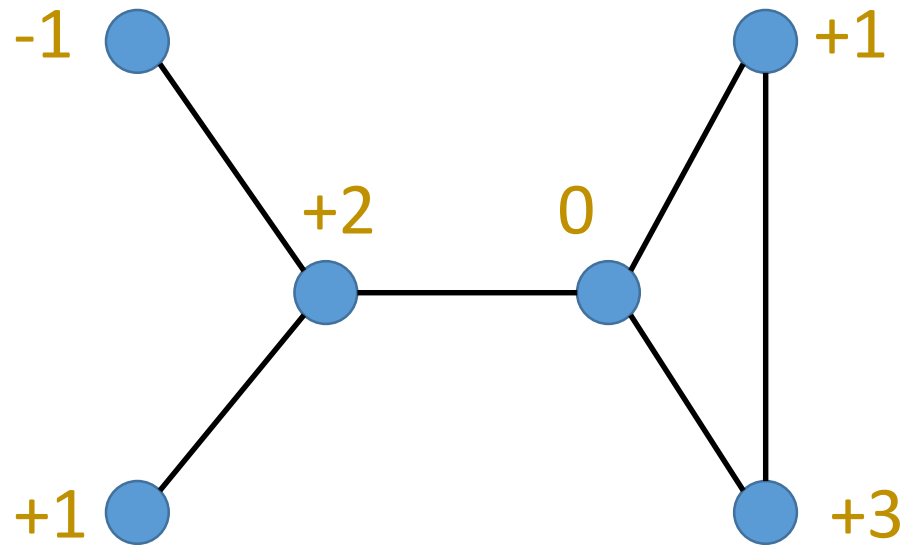
$$L_G = \sum_{ij \in E} (\delta_i - \delta_j)(\delta_i - \delta_j)^T = D - A$$

Quadratic form:

$$x^T L x = \sum_{ij \in E} (x_i - x_j)^2 \text{ for } x \in \mathbf{R}^n$$

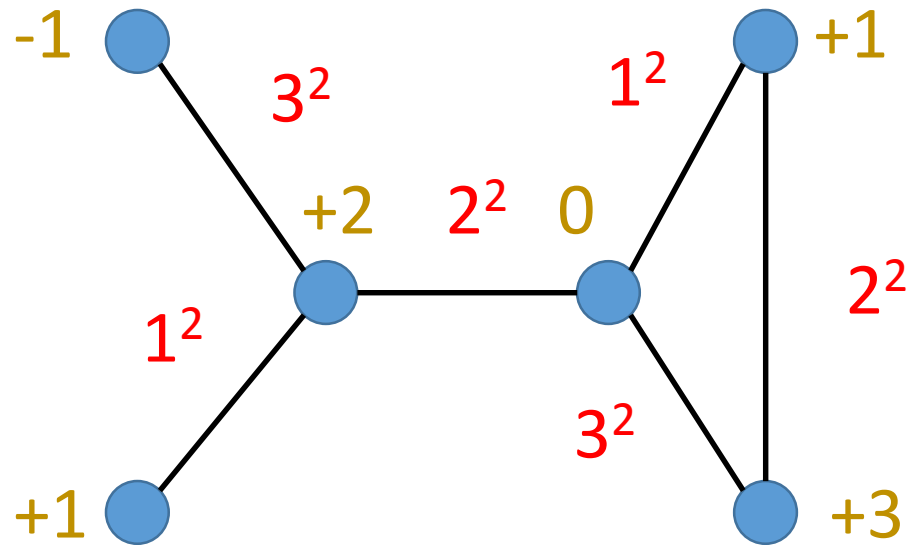
The Laplacian Quadratic Form

An example:



The Laplacian Quadratic Form

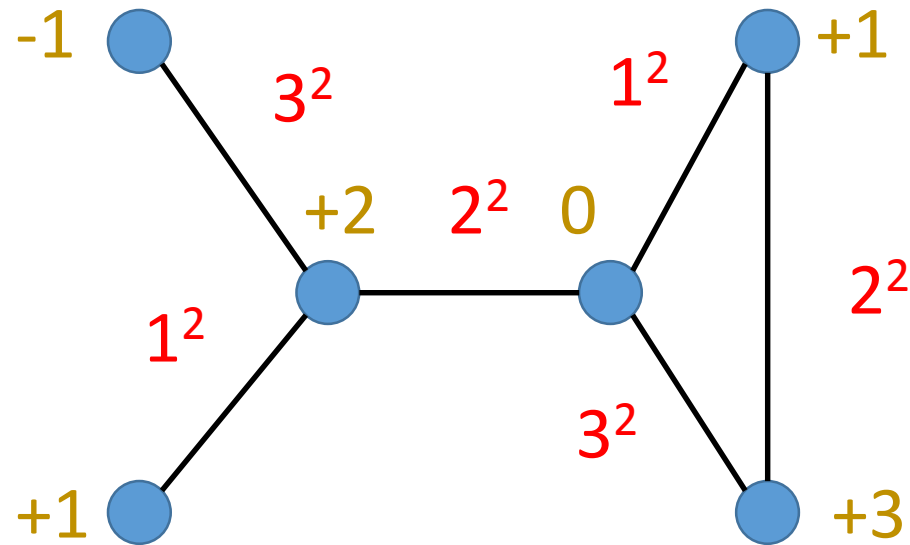
An example:



$$\mathbf{x}^T \mathbf{L} \mathbf{x} = \sum_{i,j \in E} (\mathbf{x}(i) - \mathbf{x}(j))^2$$

The Laplacian Quadratic Form

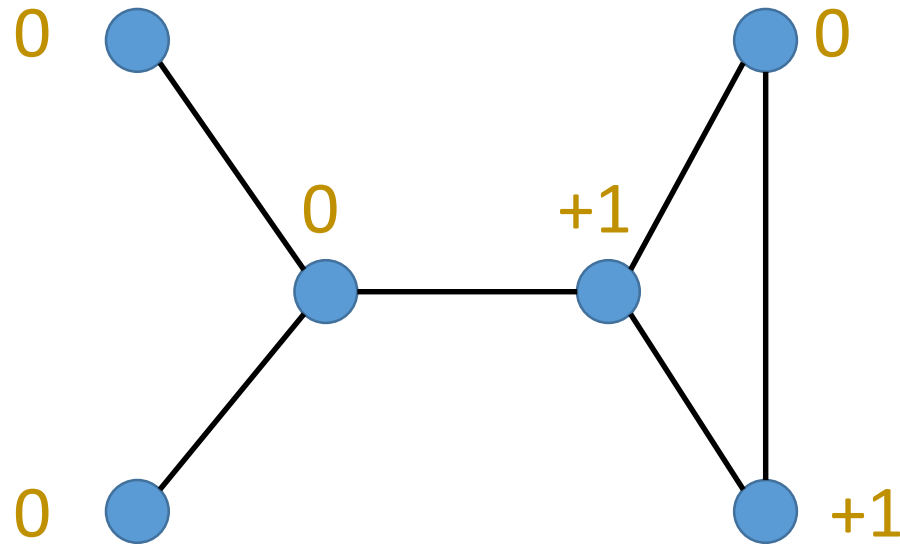
An example:



$$\mathbf{x}^T \mathbf{L} \mathbf{x} = \sum_{i,j \in E} (\mathbf{x}(i) - \mathbf{x}(j))^2 = 28$$

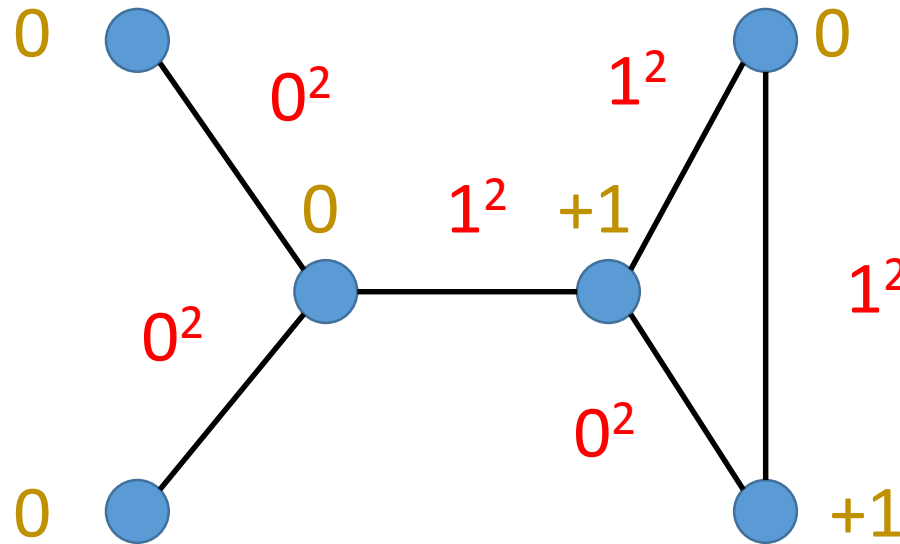
The Laplacian Quadratic Form

Another example:



The Laplacian Quadratic Form

Another example:



$$\mathbf{x}^T L_G \mathbf{x} = 3$$

Cuts and the Quadratic Form

For characteristic vector $x_S \in \{0, 1\}^n$ of $S \subseteq V$

$$\begin{aligned}x_S^T L_G x_S &= \sum_{ij \in E} w_{ij} (x(i) - x(j))^2 \\ &= \sum_{ij \in (S, \bar{S})} w_{ij} \\ &= wt_G(S, \bar{S})\end{aligned}$$

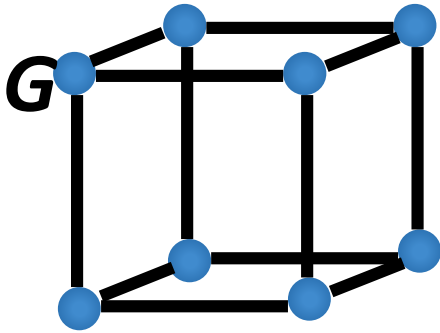
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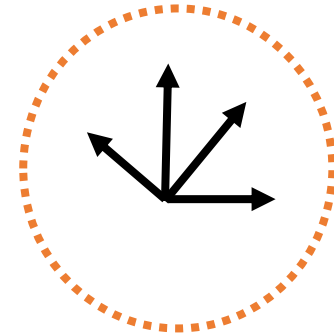
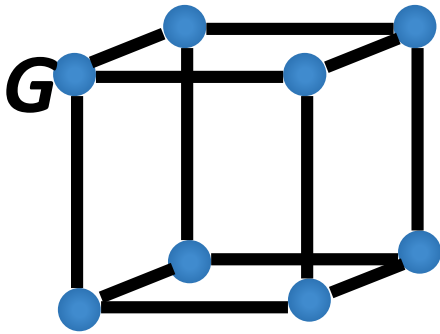
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The Laplacian Quadratic form encodes the entire cut structure of the graph.

Application to Graphs

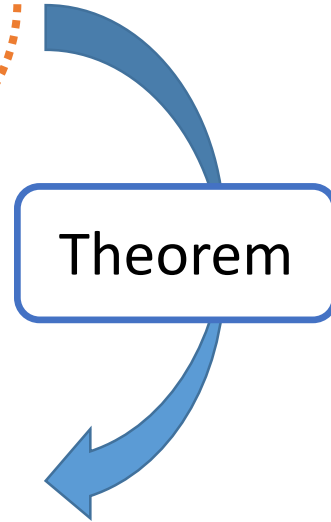
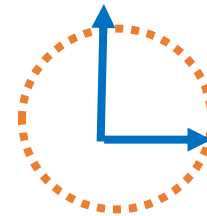
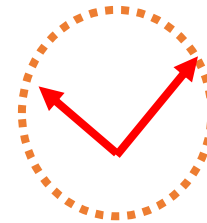
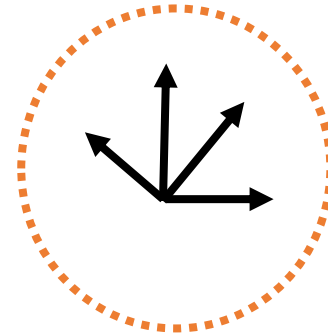
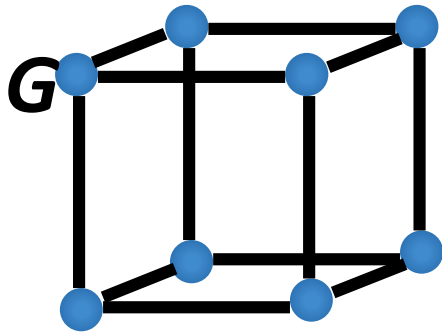


Application to Graphs

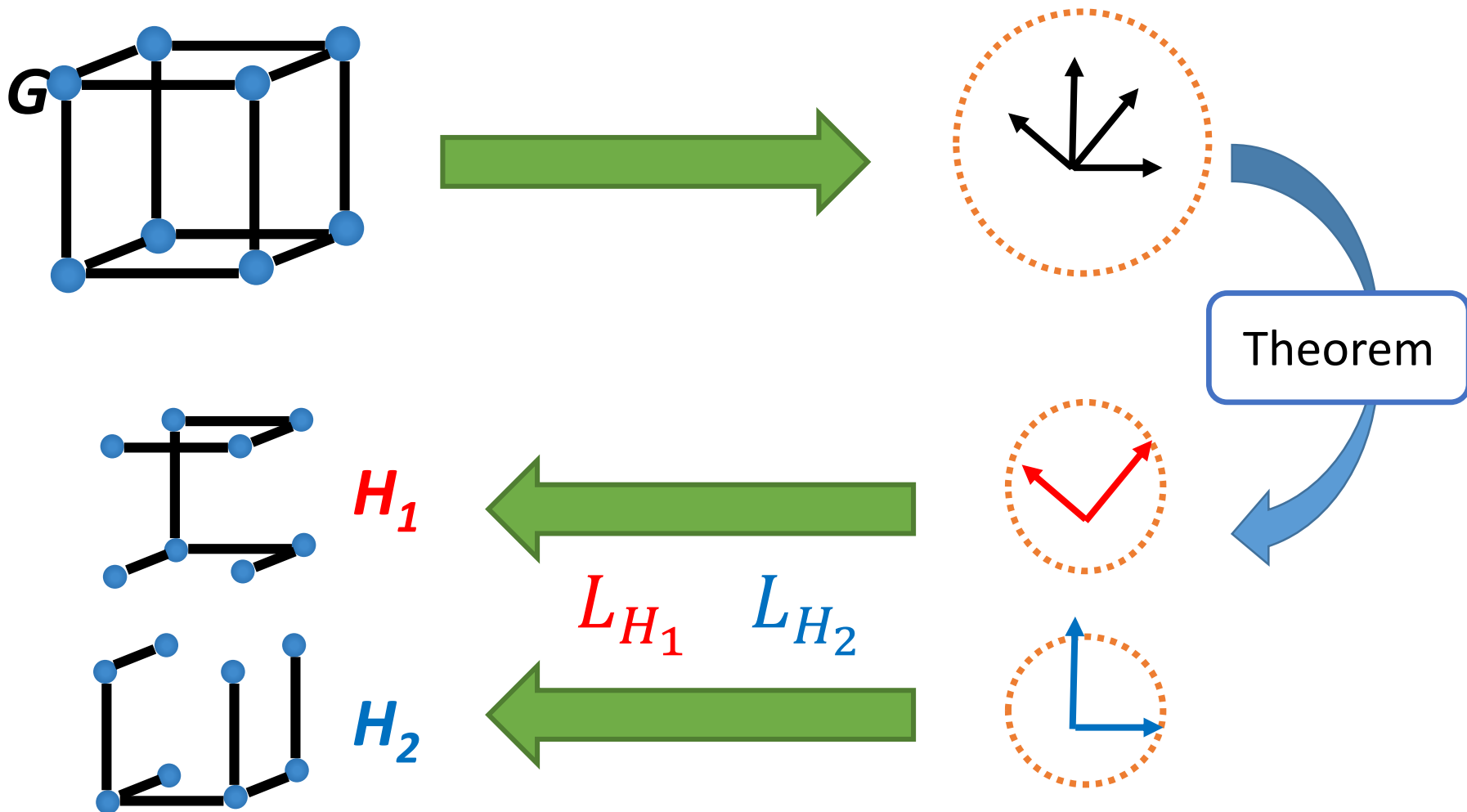


$$L_G = \sum_{ij \in E} (\delta_i - \delta_j)(\delta_i - \delta_j)^T$$

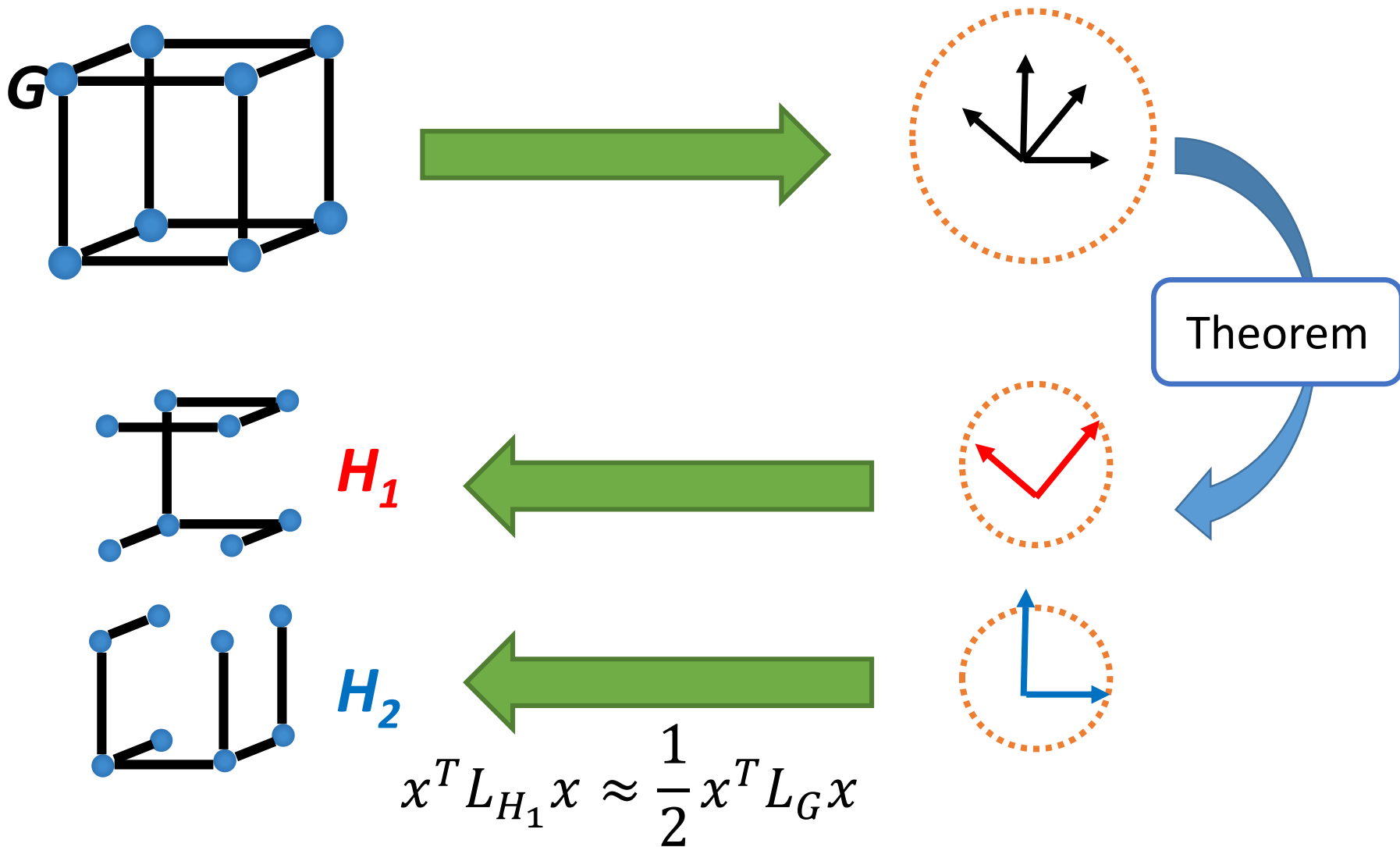
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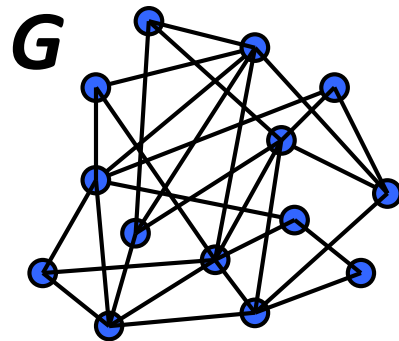


Application to Graphs



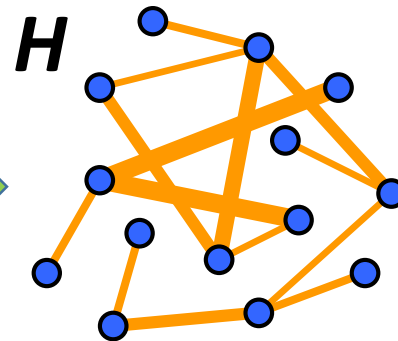
Recursive Application Gives:

1. Graph Sparsification Theorem [Batson-Spielman-S'09]: Every graph G has a *weighted* $O(1)$ -cut approximation H with $O(n)$ edges.



$O(n^2)$ edges

Unweighted

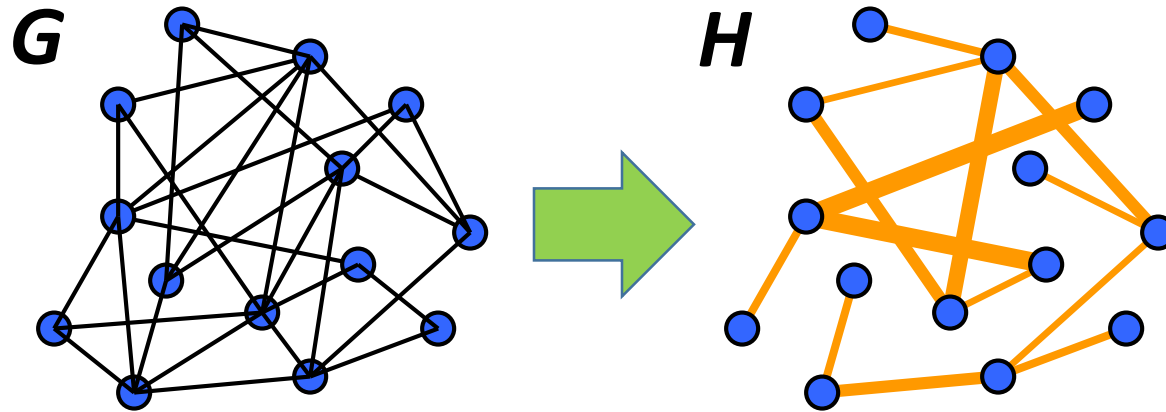


$O(n)$ edges

Weighted

Approximating One Graph by Another

Cut Approximation [Benczur-Karger'96]

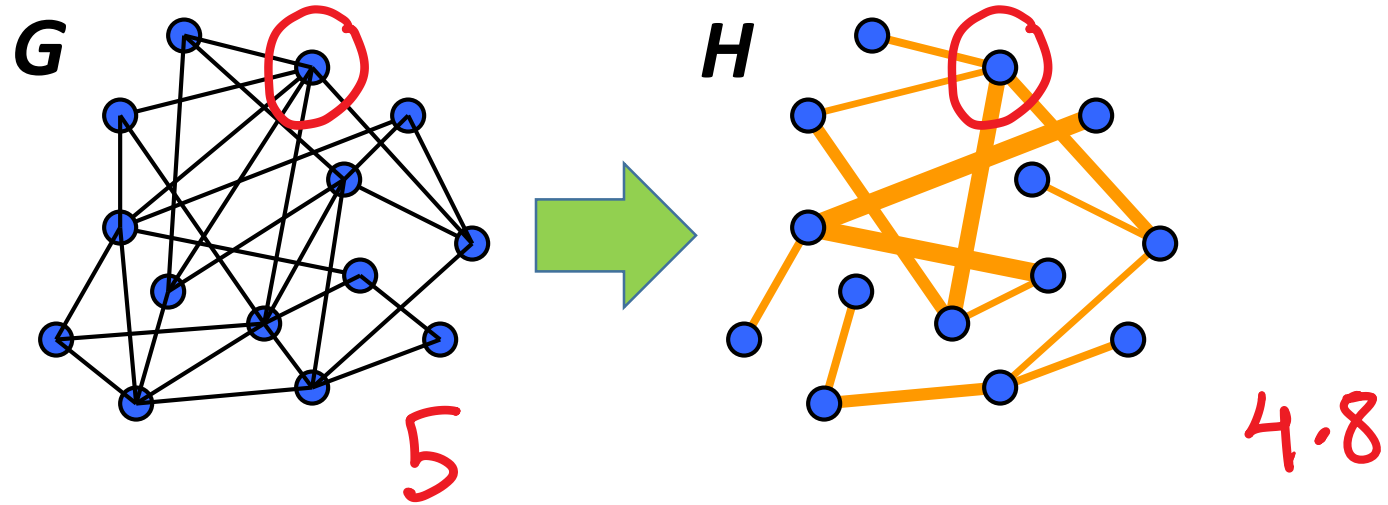


For **every** cut,

weight of edges in $\mathbf{G} \approx$ weight of edges in \mathbf{H}

Approximating One Graph by Another

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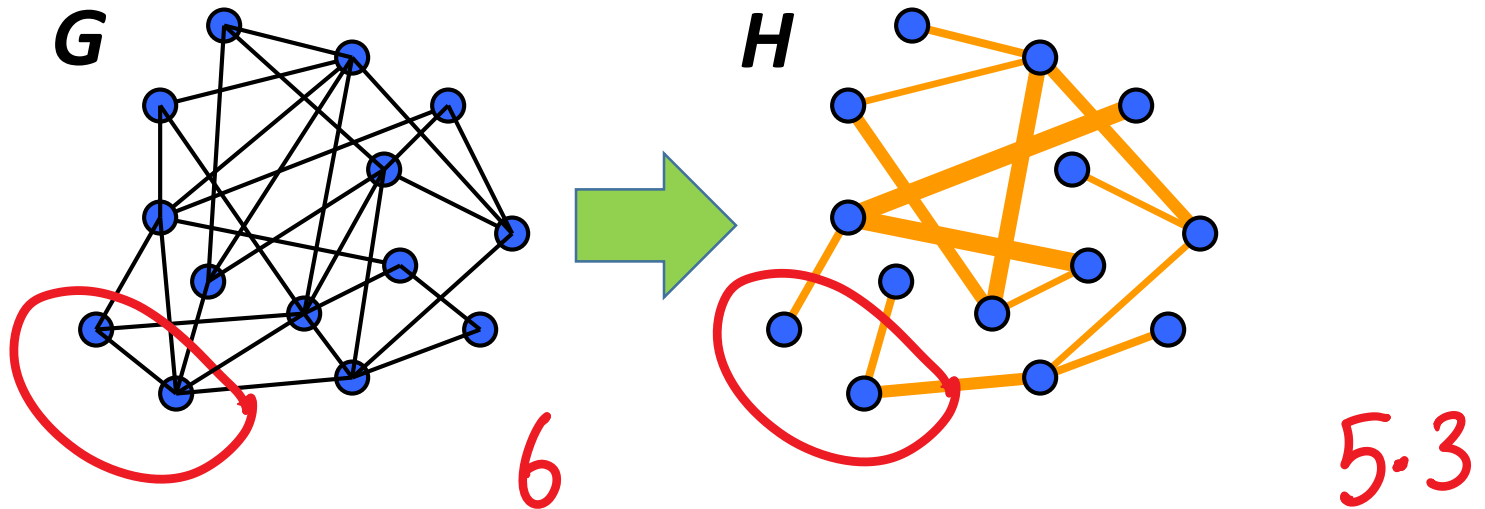


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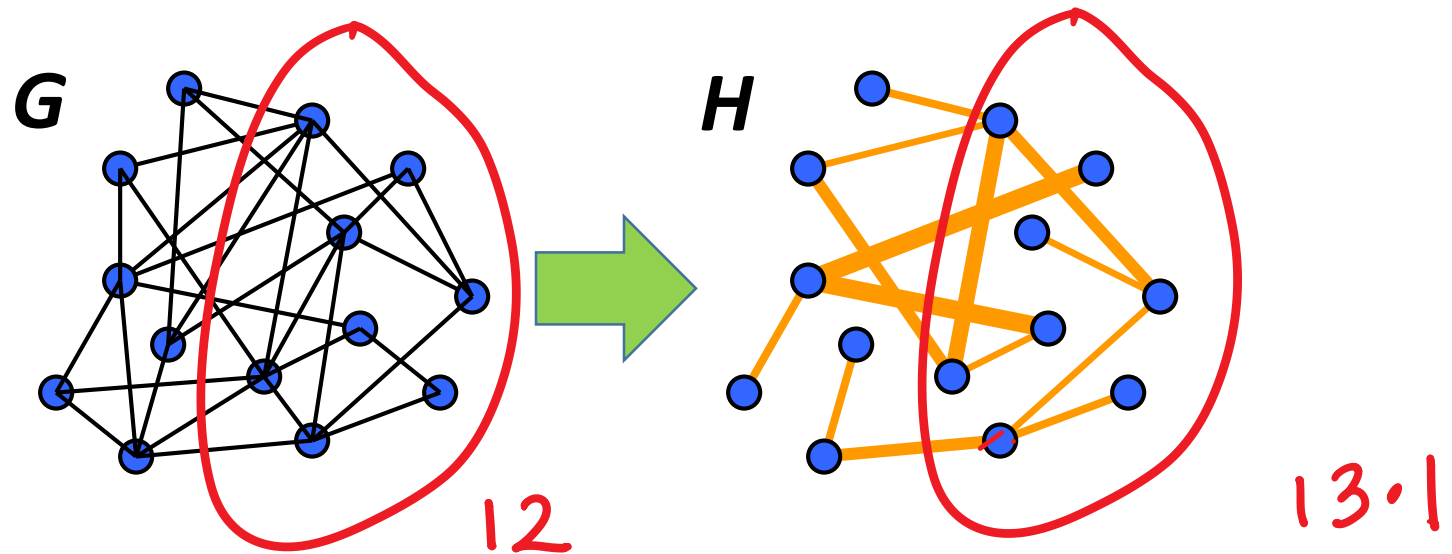


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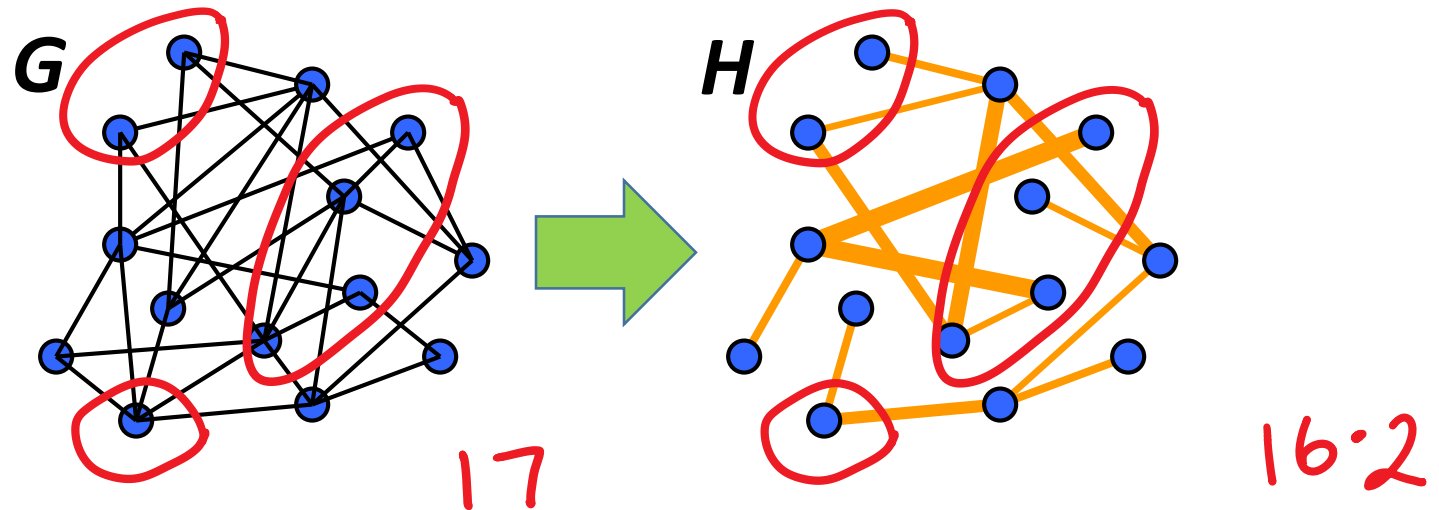


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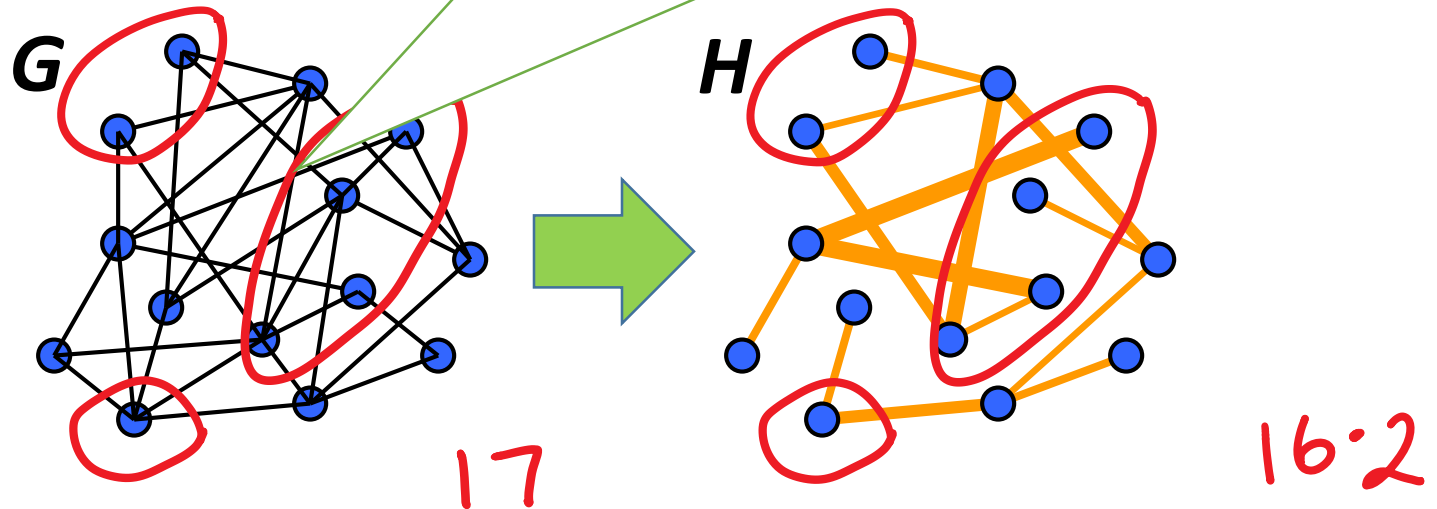
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Approximating One Graph by Another

Cut Approximation

G and H have same cuts. Equivalent for min cut, max cut, sparsest cut...

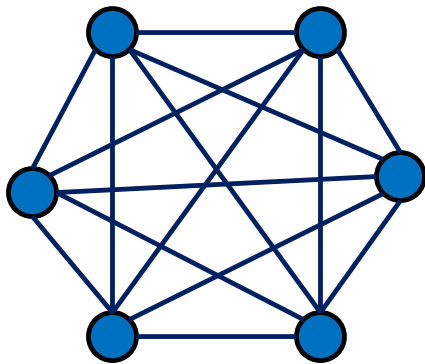


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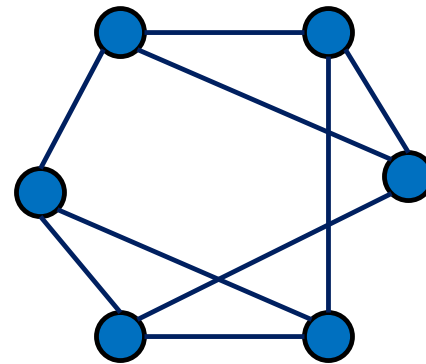
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Recursive Application Gives:

2. Unweighted Graph Sparsification Every transitive graph \mathbf{G} has an unweighted $O(1)$ -cut approximation \mathbf{H} with $O(n)$ edges.



K_n

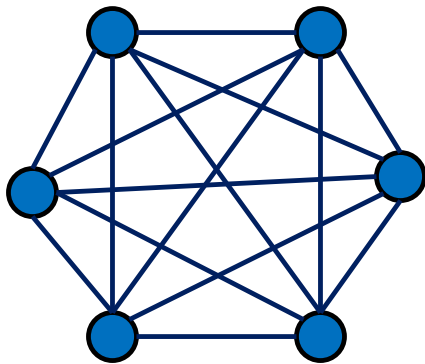


H

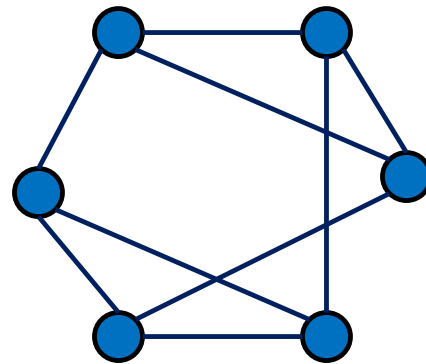
Expander graph

Recursive Application Gives:

2. **Unweighted Graph Sparsification** Every transitive graph **G** *can be partitioned into* $O(1)$ -cut approximations with $O(n)$ edges.



K_n

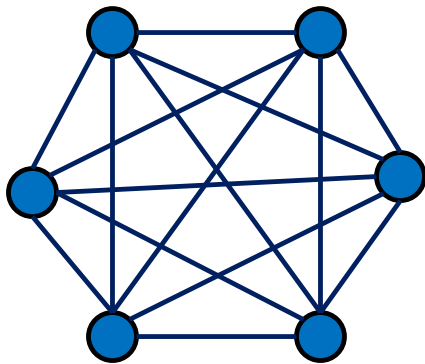


$H_1 \dots H_n$

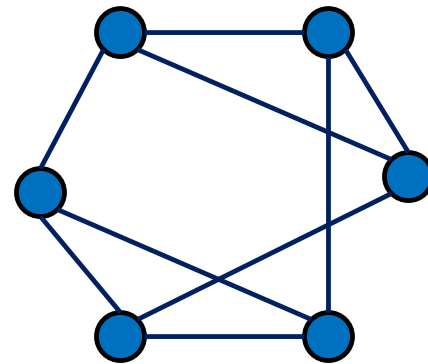
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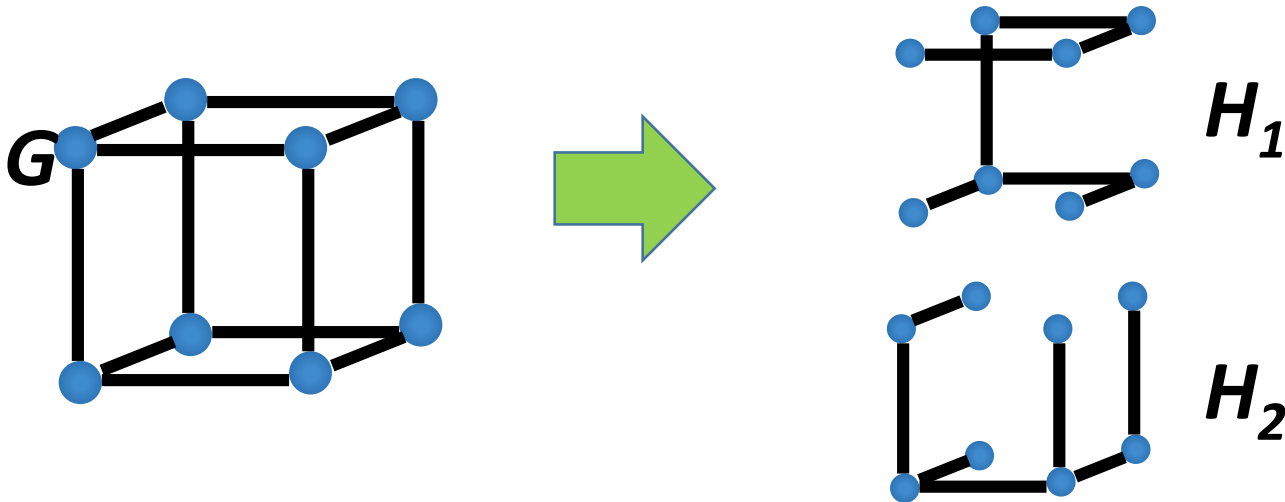
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Expander graphs

Generalizes [Frieze-Molloy]

Recursive Application Gives:

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Same cut structure



2. Uncertainty Principles

Signal $x \in \mathbb{C}^n$. Discrete Fourier Transform

$$\hat{x}(a) = \left\langle x, \left(\exp\left(-\frac{a2\pi ik}{n}\right) \right)_{k \leq n} \right\rangle$$

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If x is supported on $|S| = \sqrt{n}$ coordinates,

$$\text{supp}(\hat{x}) \geq \sqrt{n}$$

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Stronger Uncertainty Principle:

For every subset $|S| = \sqrt{n}$, there is a partition

$$[n] = T_1 \cup \dots \cup T_{\sqrt{n}}$$

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2. Uncertainty Principles

Proof.

Let $f_k = \left(\exp\left(-\frac{a2\pi ik}{n}\right) \right)_{k \leq n}$ be the Fourier basis.

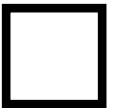
Fix a subset $S \subset [n]$ of \sqrt{n} coords.

The restricted norm is:

$$\|x|_S\|^2 = \sum_k \langle x|_S, f_k \rangle^2$$

a quadratic form in \sqrt{n} dimensions.

Apply the theorem.



2. Uncertainty Principles

Applications in analytic number theory,
harmonic analysis.

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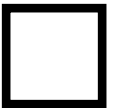
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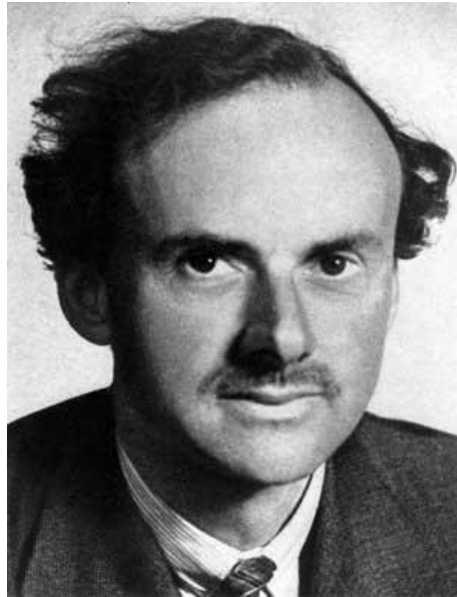
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3. The Kadison-Singer Problem

Dirac 1930's: Bra-Ket formalism for quantum states.

$$|\psi\rangle, |p\rangle \dots$$



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Von Neumann 1936: Theory of C^* algebras.

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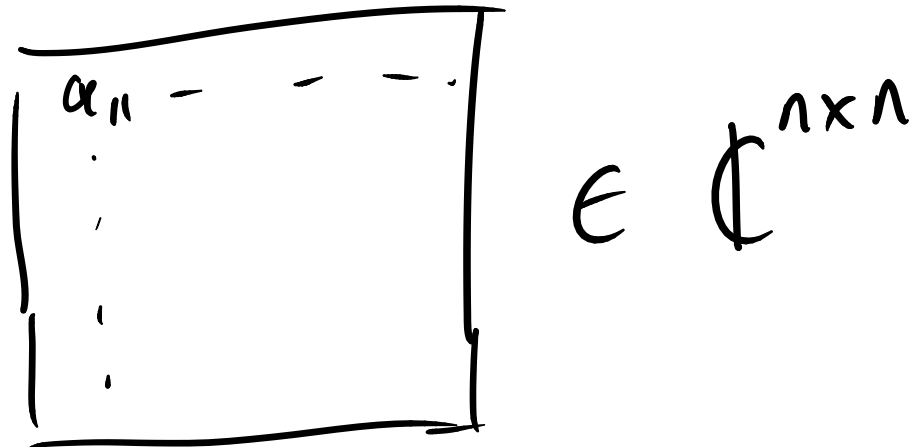
Conjecture: about ∞ matrices

A handwritten diagram enclosed in a large square frame. The top-left corner contains the entries a_{11} and a_{12} . Below a_{11} is a_{21} , and below a_{21} are three vertical dots. To the right of a_{11} and a_{21} are several horizontal dashes. A diagonal line of dashes extends from the top-right towards the bottom-left. In the bottom-right corner, there are two dots.

3. The Kadison-Singer Problem

Kadison-Singer 1959: Does this lead to a

Anderson 1979: Reduced to a question about finite matrices. “Paving Conjecture”



A hand-drawn diagram illustrating a matrix structure. On the left, a square box contains a diagonal element α_{11} at the top left, followed by three vertical dots. To the right of this box is a circled submatrix, and the entire expression is labeled $\in \mathbb{C}^{n \times n}$.

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Weaver 2002: Discrepancy theoretic formulation of the same question.

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In General

Anything that can be encoded as a quadratic form can be split into pieces while preserving certain properties.

Many different things can be gainfully encoded this way.

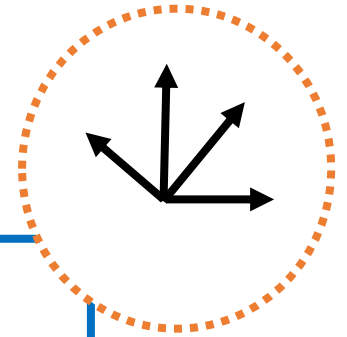
Proof

Main Theorem

Suppose $v_1, \dots, v_m \in \mathbf{R}^n$ are vectors

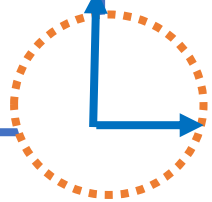
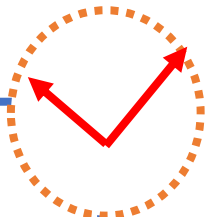
$\|v_i\|^2 \leq \epsilon$ and

$$\sum_i v_i v_i^T = I_n$$



Then there is a partition $T_1 \cup T_2$ such that

$$\left(\frac{1}{2} - 5\sqrt{\epsilon}\right) I \preceq \sum_{i \in T_j} v_i v_i^T \preceq \left(\frac{1}{2} + 5\sqrt{\epsilon}\right) I$$



Equivalent Theorem

Suppose $v_1, \dots, v_m \in \mathbf{R}^n$ are vectors

$\|v_i\|^2 \leq \epsilon$ and

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Then there is a partition $T_1 \cup T_2$ such that

$$\sum_{i \in T_j} v_i v_i^T \preceq \left(\frac{1}{2} + 5\sqrt{\epsilon} \right) I$$

Equivaler

$$\sum_{i \in T_1} v_i v_i^T = I - \sum_{i \in T_2} v_i v_i^T$$

Suppose v_1, \dots, v_m are vectors

$\|v_i\|^2 \leq \epsilon$ and

$$\sum_i v_i v_i^T = I_n$$

Then there is a partition $T_1 \cup T_2$ such that

$$\sum_{i \in T_j} v_i v_i^T \preceq \left(\frac{1}{2} + 5\sqrt{\epsilon} \right) I$$

Equivalent Theorem

Suppose $v_1, \dots, v_m \in \mathbf{R}^n$ are vectors

$\|v_i\|^2 \leq \epsilon$ and

$$\sum_i v_i v_i^T = I_n$$

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Idea 1: Random Partition

Choose $T_1 \cup T_2 = [m]$ randomly

Want:

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Trick: embed in blocks of $2n \times 2n$ matrix

$$\begin{bmatrix} \sum_{i \in T_1} v_i v_i^T & 0 \\ 0 & \sum_{i \in T_2} v_i v_i^T \end{bmatrix}$$

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Idea 1: Random Partition

Define independent random $v_1, \dots, v_m \in \mathbb{R}^{2n}$

$$v_i = \begin{cases} \begin{pmatrix} v_i \\ 0 \end{pmatrix} & \text{with prob } 0.5 \\ \begin{pmatrix} 0 \\ v_i \end{pmatrix} & \text{with prob. } 0.5 \end{cases}$$

Then

$$\mathbb{E} \left\| \sum_i v_i v_i^T \right\| = \mathbb{E}_T \max_j \left\| \sum_{i \in T_j} v_i v_i^T \right\|$$

The Matrix Chernoff Bound

$v_1, \dots, v_m \in \mathbb{R}^{2n}$ are independent,
 $\mathbb{E} \sum_i v_i v_i^T = \frac{I}{2}$ and $\|v_i\|^2 \leq \epsilon$

Tropp 2011

$$\mathbb{E} \left\| \sum_i v_i v_i^T \right\| \leq \frac{1}{2} + O(\sqrt{\epsilon \log n})$$

Analogous for the scalar Chernoff bound for sums of independent bdd random numbers.

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Main Theorem

$\exists v_1, \dots, v_m$ such that

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Then

$$\mathbb{P} \left[\left\| \sum_i v_i v_i^T \right\| \leq 1 + O(\sqrt{\epsilon}) \right] > 0$$

Idea 2: The Expected Polynomial

Just like yesterday,

$$\left\| \sum_i v_i v_i^T \right\| = \lambda_{max} \left(\det(xI - \sum_i v_i v_i^T) \right)$$

Consider

$$\mu(x) := \mathbb{E} \det \left(xI - \sum_i v_i v_i^T \right)$$

3-Step Plan

1. Show that there exist v_1, \dots, v_m with

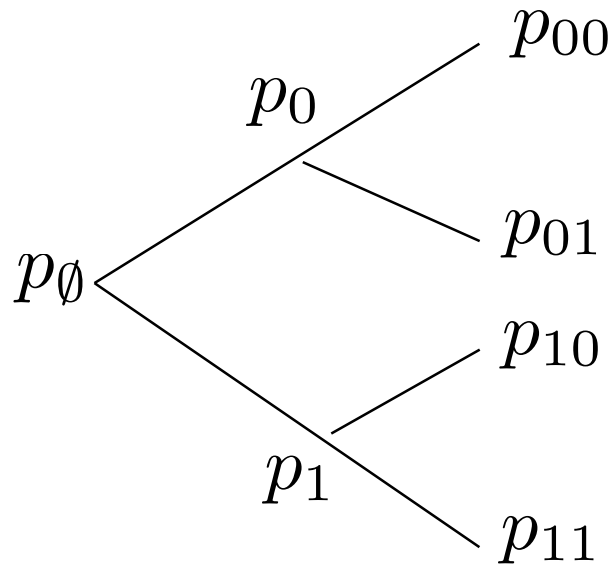
$$\lambda_{max} \chi \left(\sum_i v_i v_i^T \right) \leq \lambda_{max} \mathbb{E} \chi \left(\sum_i v_i v_i^T \right)$$

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$$\mathbb{E} \chi \left(\sum_i v_i v_i^T \right) = \prod_{i=1}^m \left(1 - \frac{\partial}{\partial z_i} \right) \det \left(xI + \sum_i z_i A_i \right) \Big|_{z_1 = \dots = z_m = 0}$$

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2. Calculate

$$\mathbb{E} \chi \left(\sum_i v_i v_i^T \right)$$

Central Identity

Suppose v_1, \dots, v_m are **independent** random vectors with $A_i := \mathbb{E}v_i v_i^T$. Then

$$\begin{aligned} & \mathbb{E} \det \left(xI - \sum_i v_i v_i^T \right) \\ &= \prod_{i=1}^m \left(1 - \frac{\partial}{\partial z_i} \right) \det \left(xI + \sum_i z_i A_i \right) \Big|_{z_1 = \dots = z_m = 0} \end{aligned}$$

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Need to bound the roots of

$$\prod_{i=1}^m (1 - \partial_{z_i}) \det \left(xI + \sum_i z_i A_i \right) \Big|_{z_1 = \dots = z_m = 0}$$

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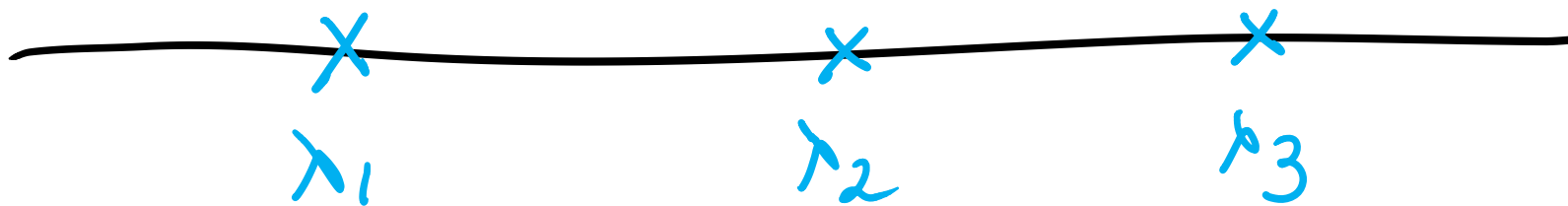
Answer: Interlacing

Consider $p(x) = (x - \lambda_1) \dots (x - \lambda_n)$ distinct

$$p'(x) = \sum_j \prod_{i \neq j} (x - \lambda_i)$$

Then $\frac{p'(x)}{p(x)} = \sum_i \frac{1}{x - \lambda_i}$ is a rational function with
 n poles.

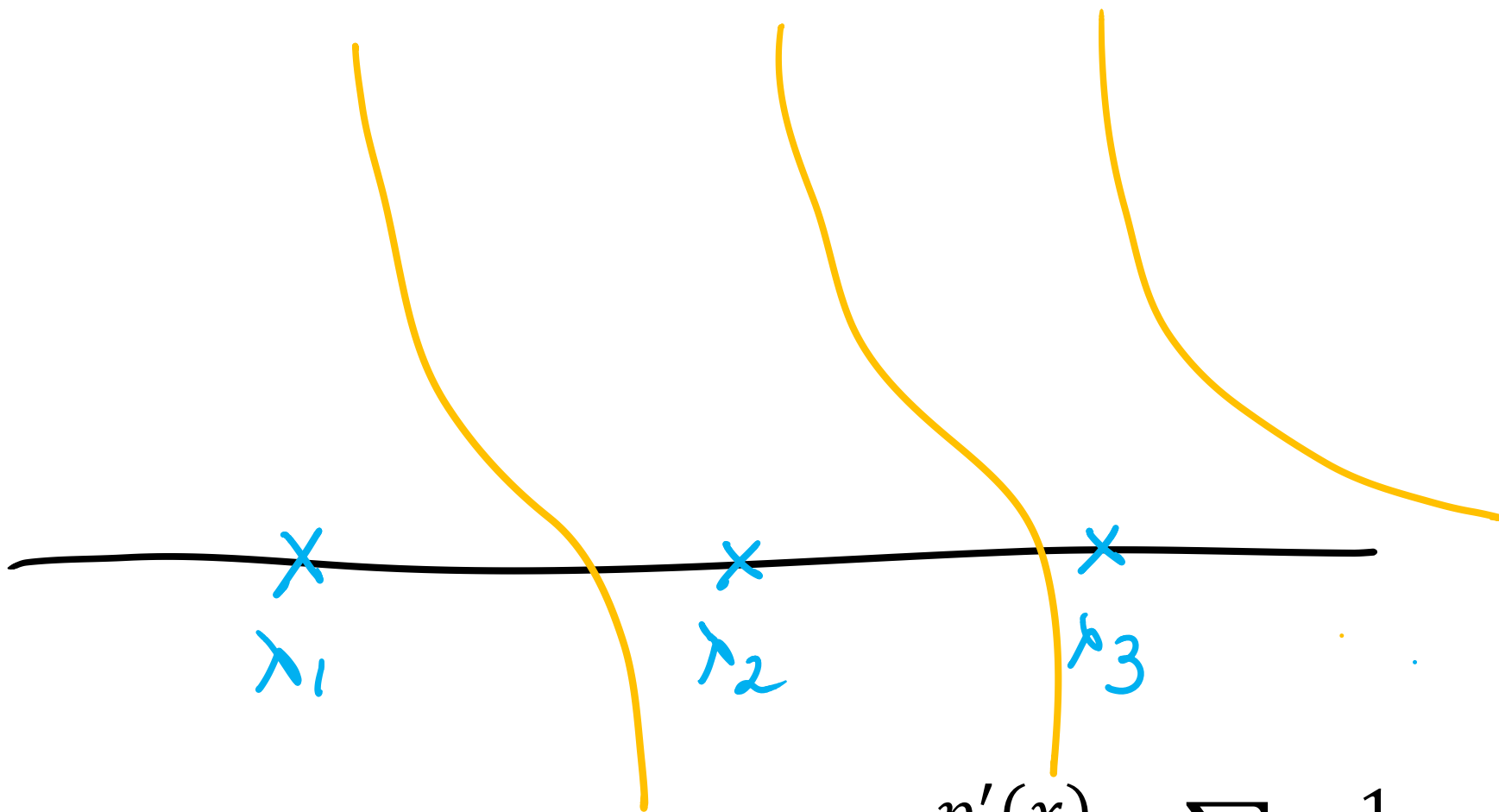
A Rational Function



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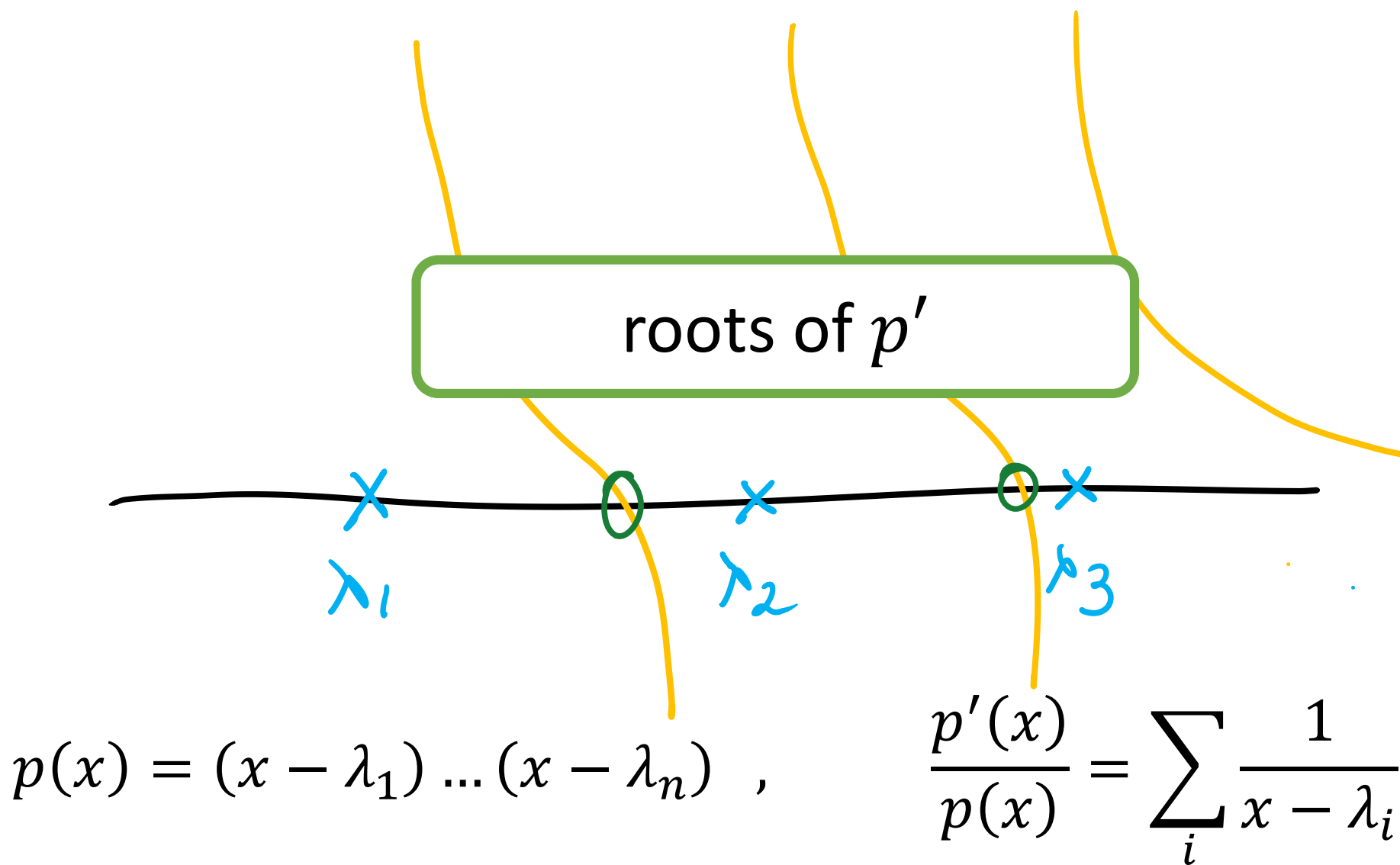
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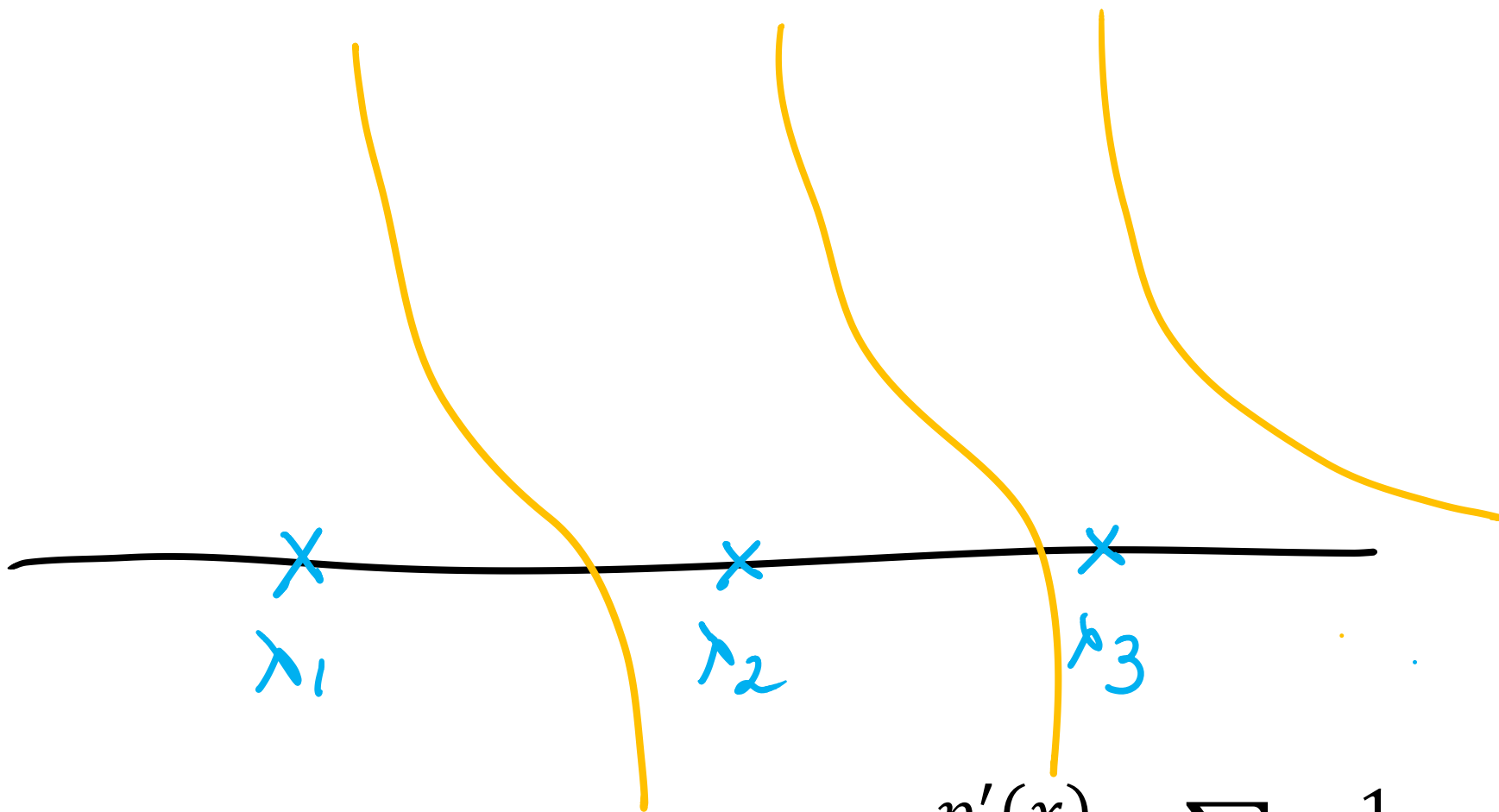
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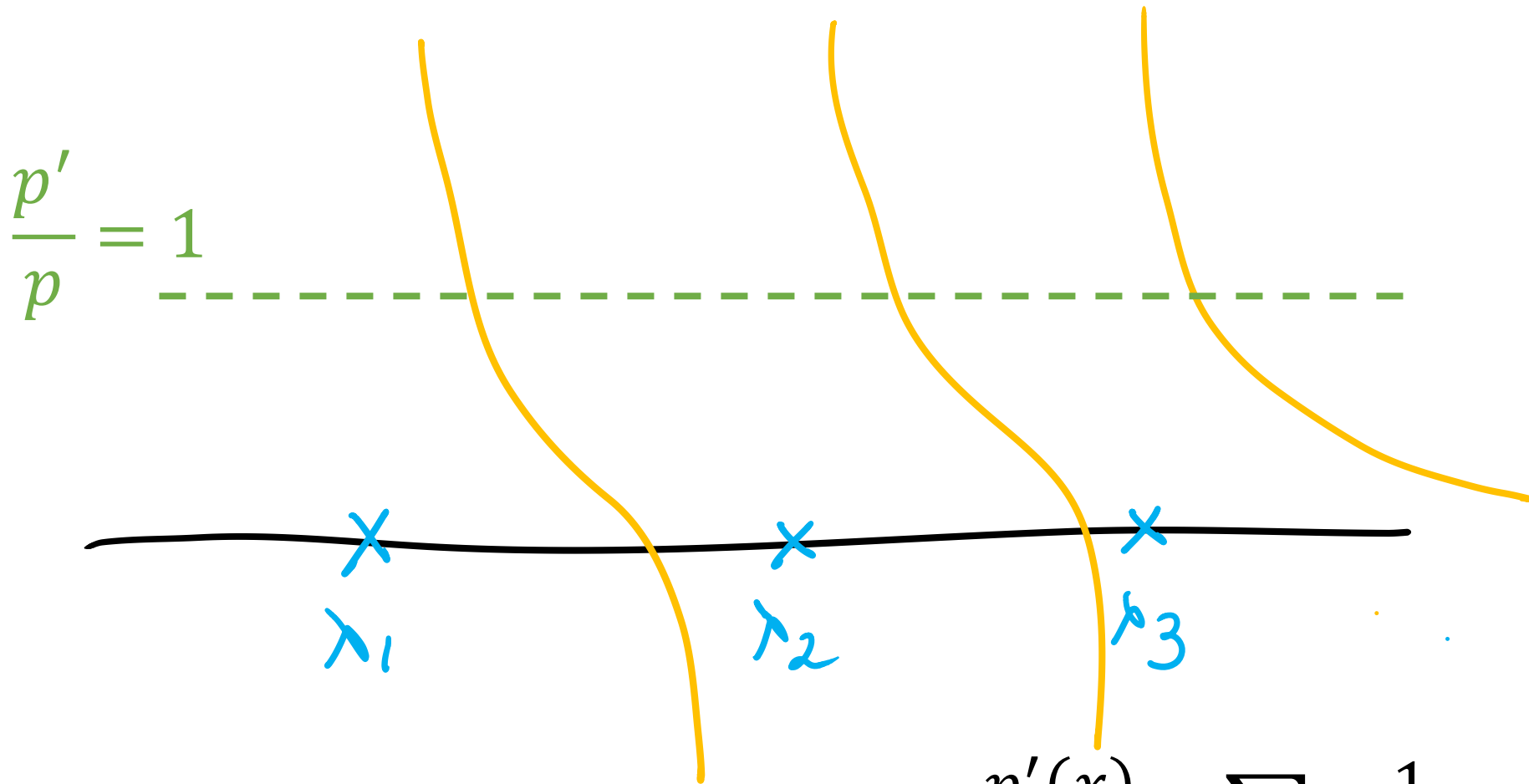
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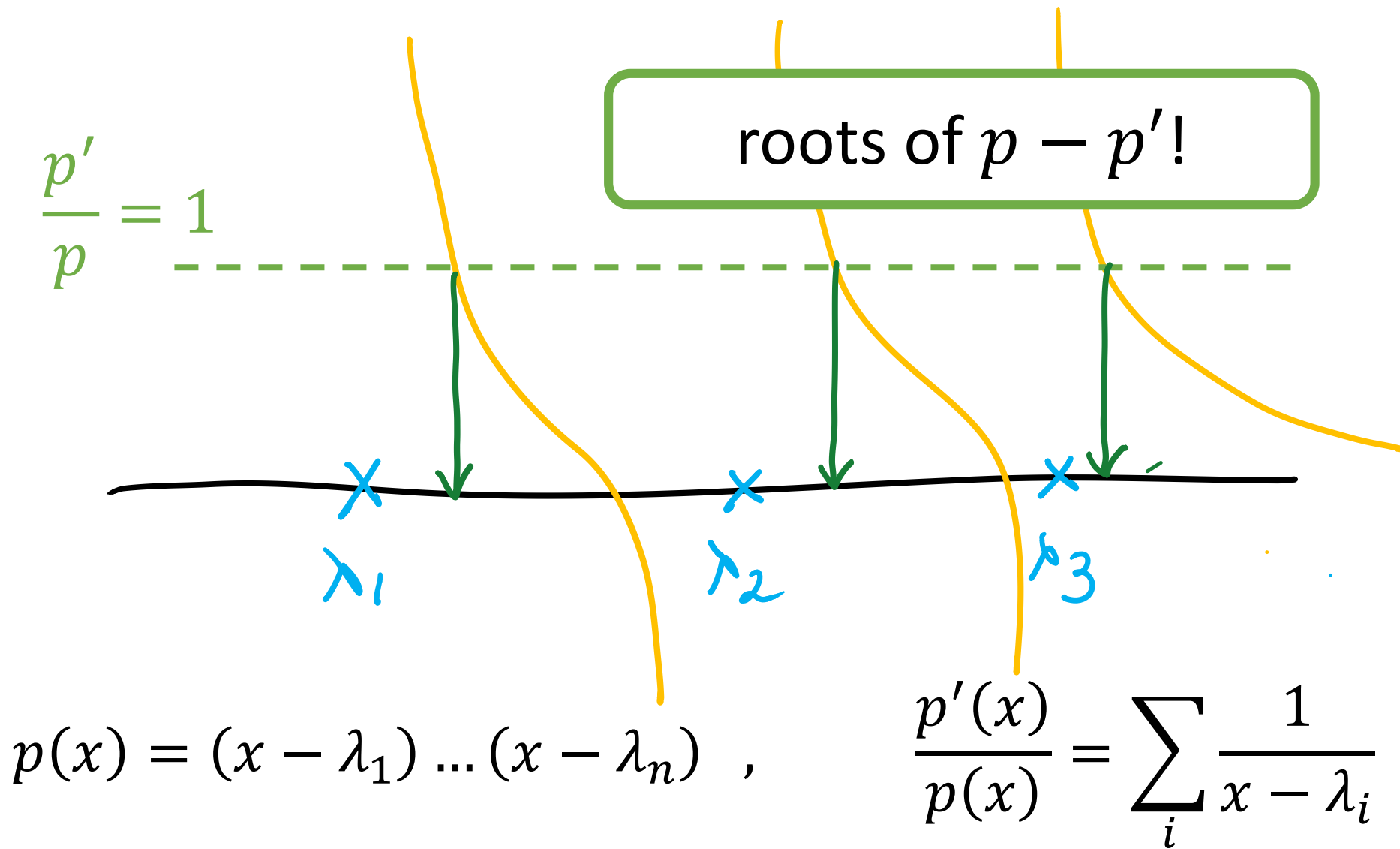
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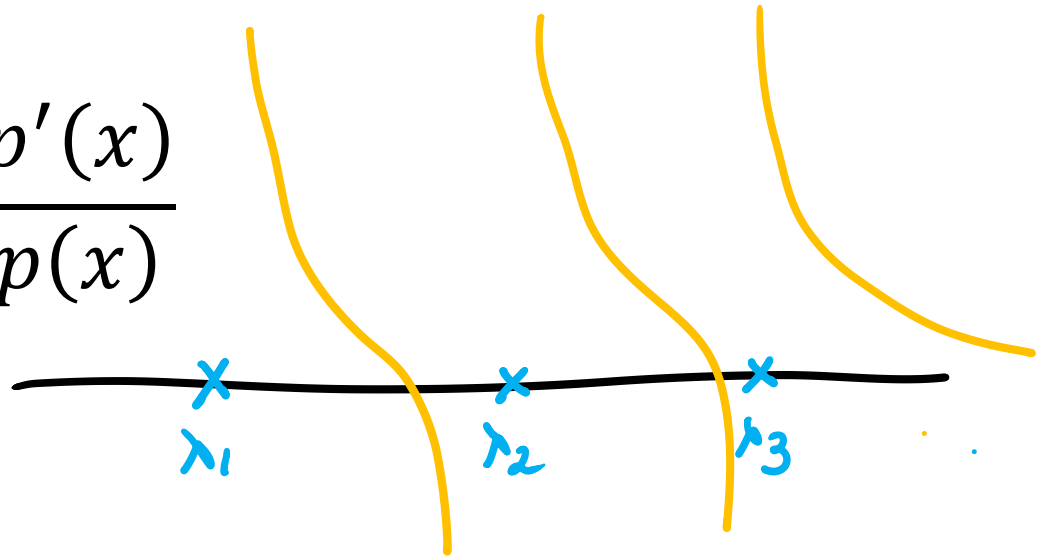
A Rational Function



The Barrier Function

Define:

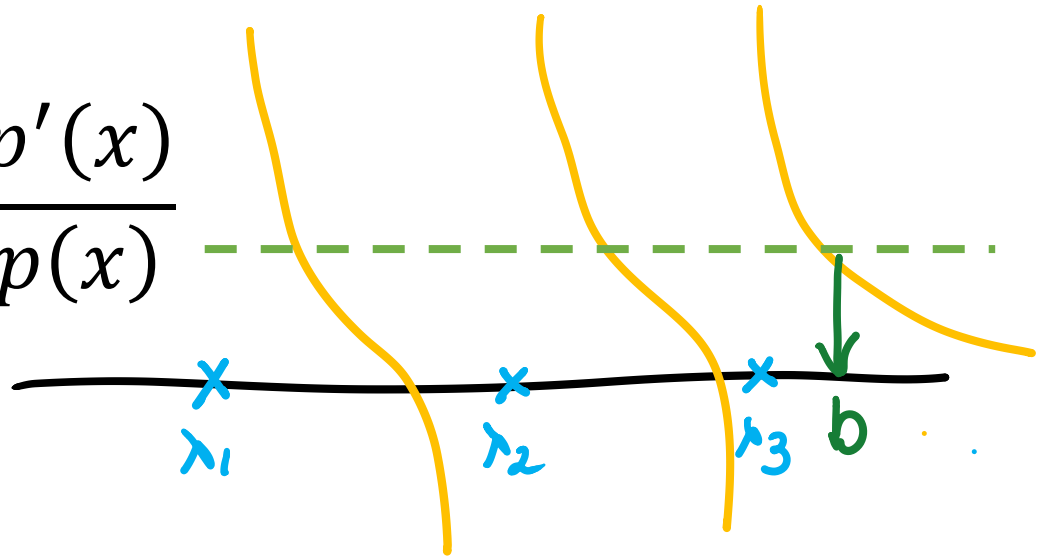
$$\Phi_p(x) = \frac{p'(x)}{p(x)}$$



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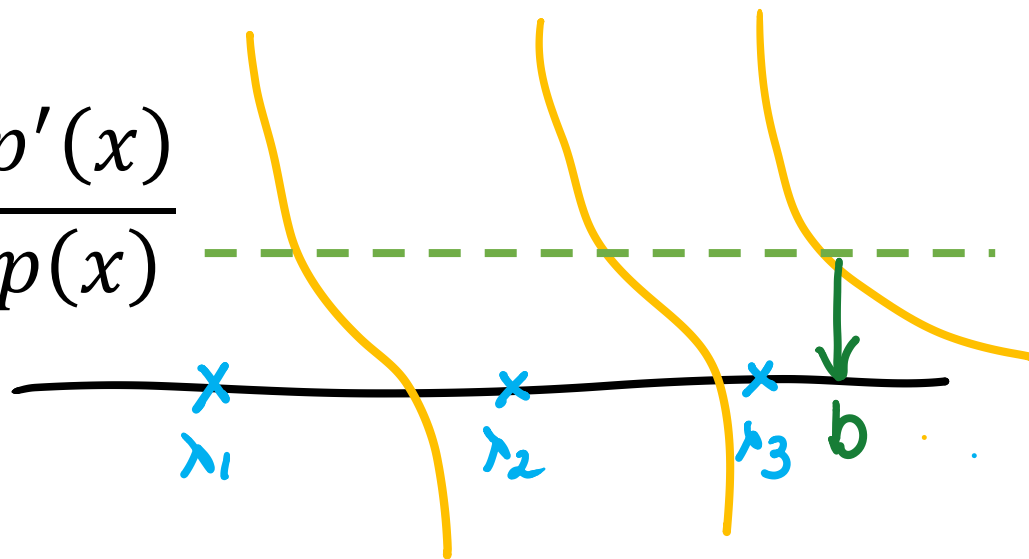


To bound roots of $p - p'$, find a point above the roots of p with $\Phi_p(b) < 1$.

The Barrier Function

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To bound roots of $p - p'$, find a point above the roots of p with $\Phi_p(b) < 1$.

Level sets $\{\Phi_p < 1\}$ contain no zeros of $p - p'$

The Barrier Method [BSS'09]

Theorem. If b is above the roots of p and

$$\Phi_p(b) \leq 1 - 1/\delta \quad \text{then}$$

$$\Phi_{p-p'}(b + \delta) \leq 1 - 1/\delta$$

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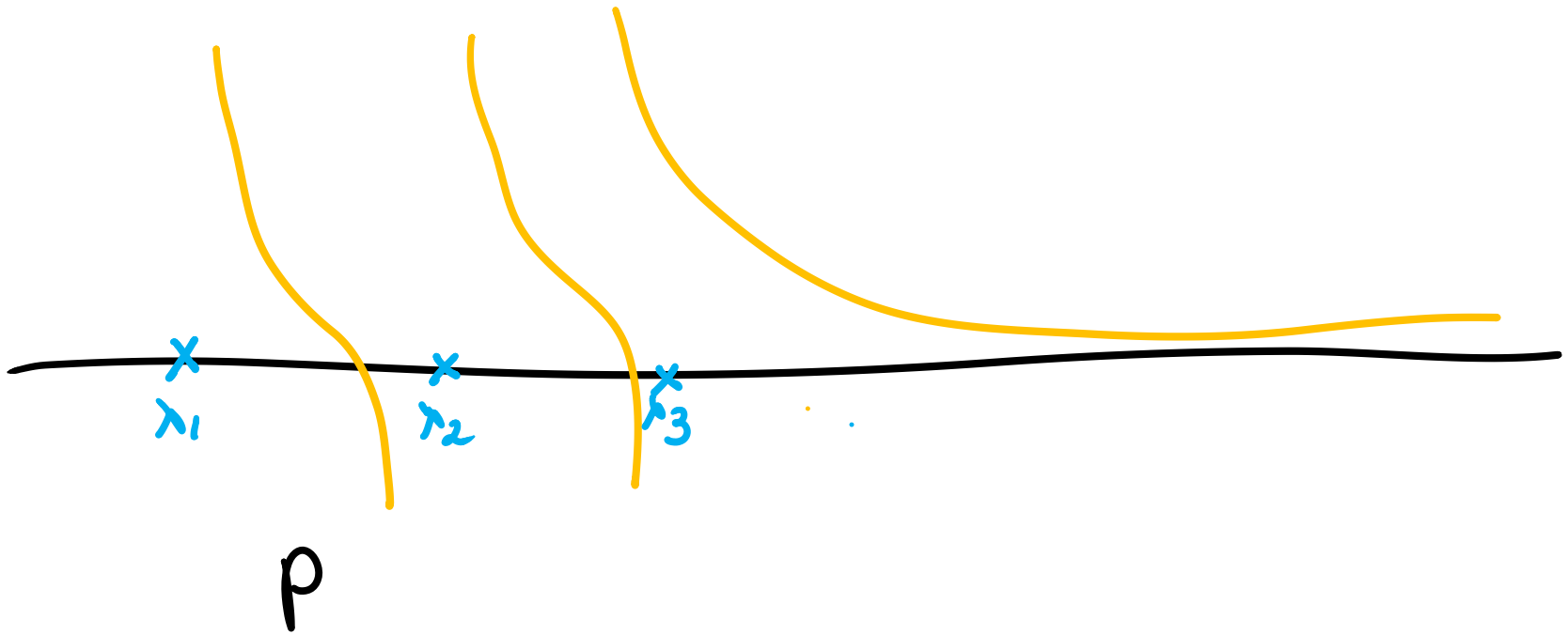
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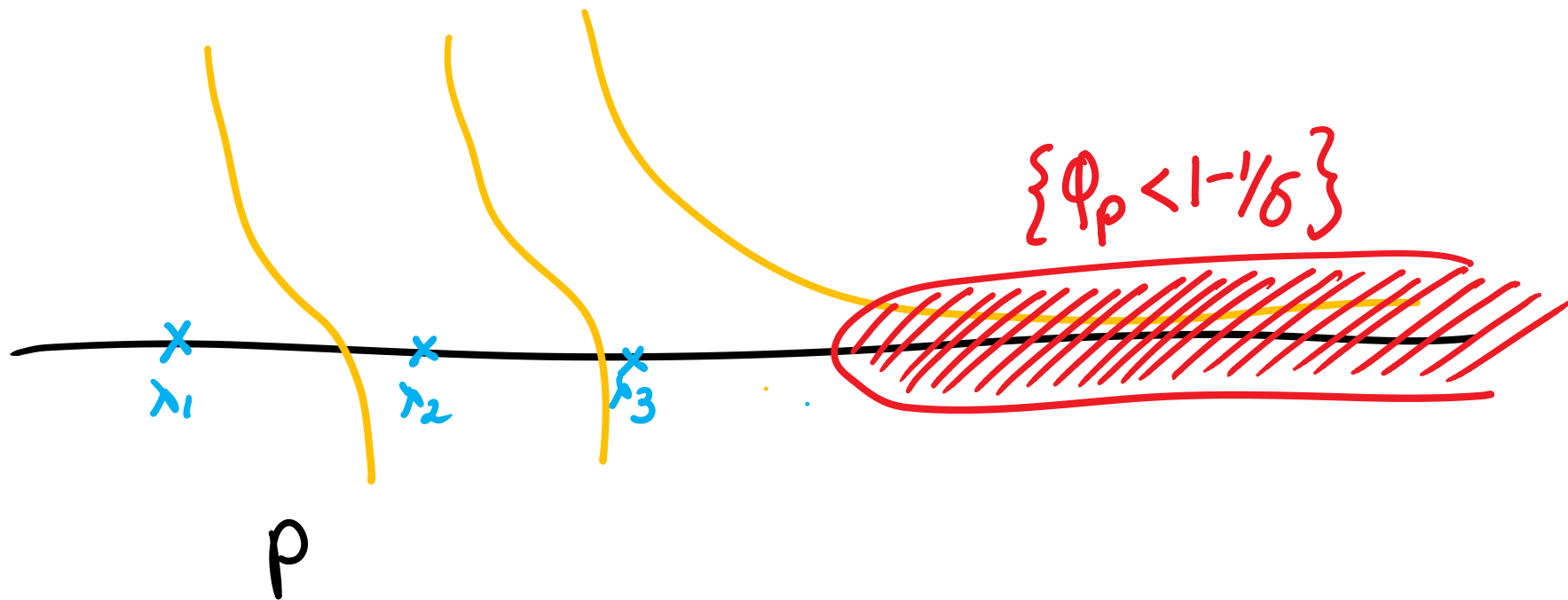
Relates level sets of Φ_p to level sets of $\Phi_{(1-\delta)p}$

Robust version of $\{\Phi_p < 1\}$ argument – can be iterated.

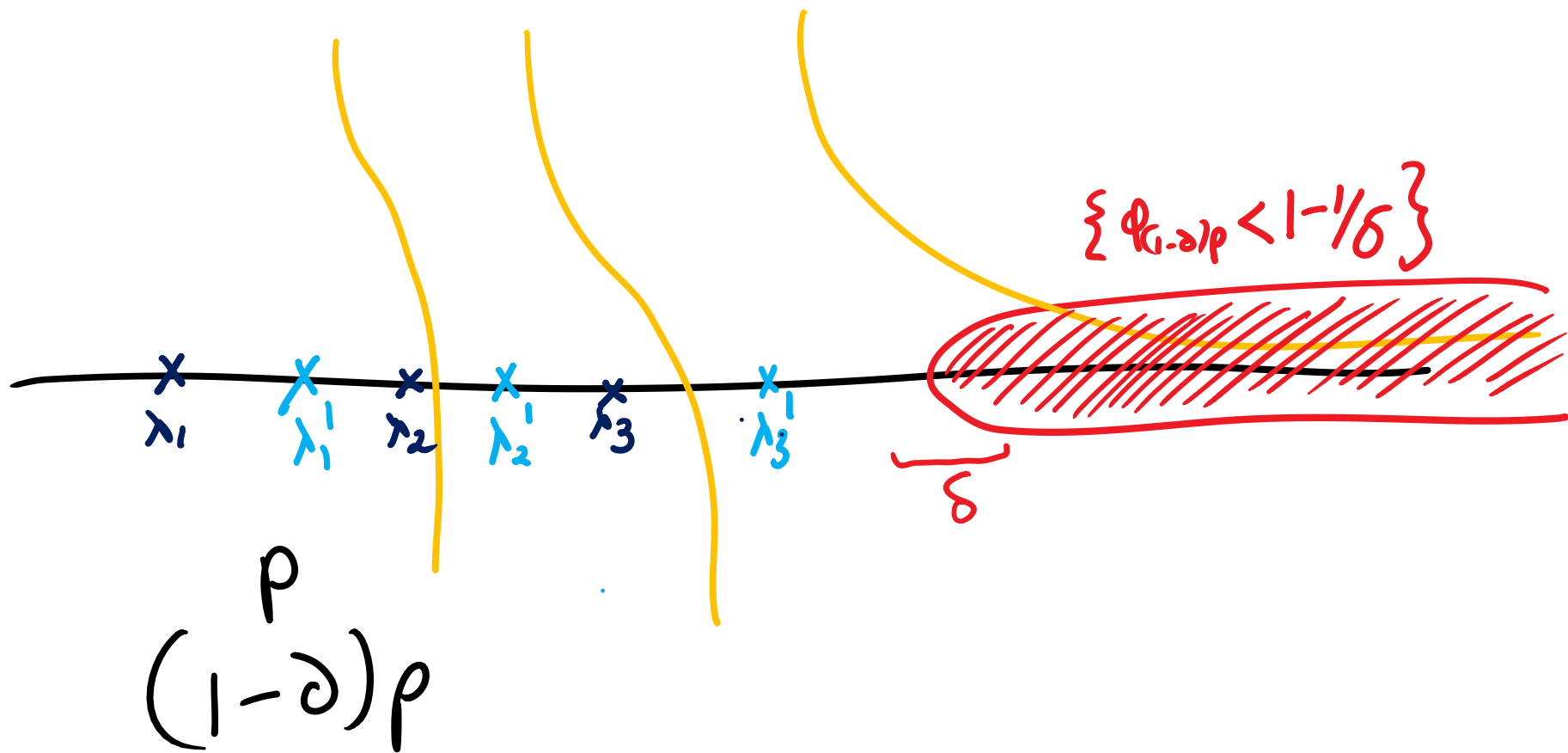
Evolution of level sets of Φ_p



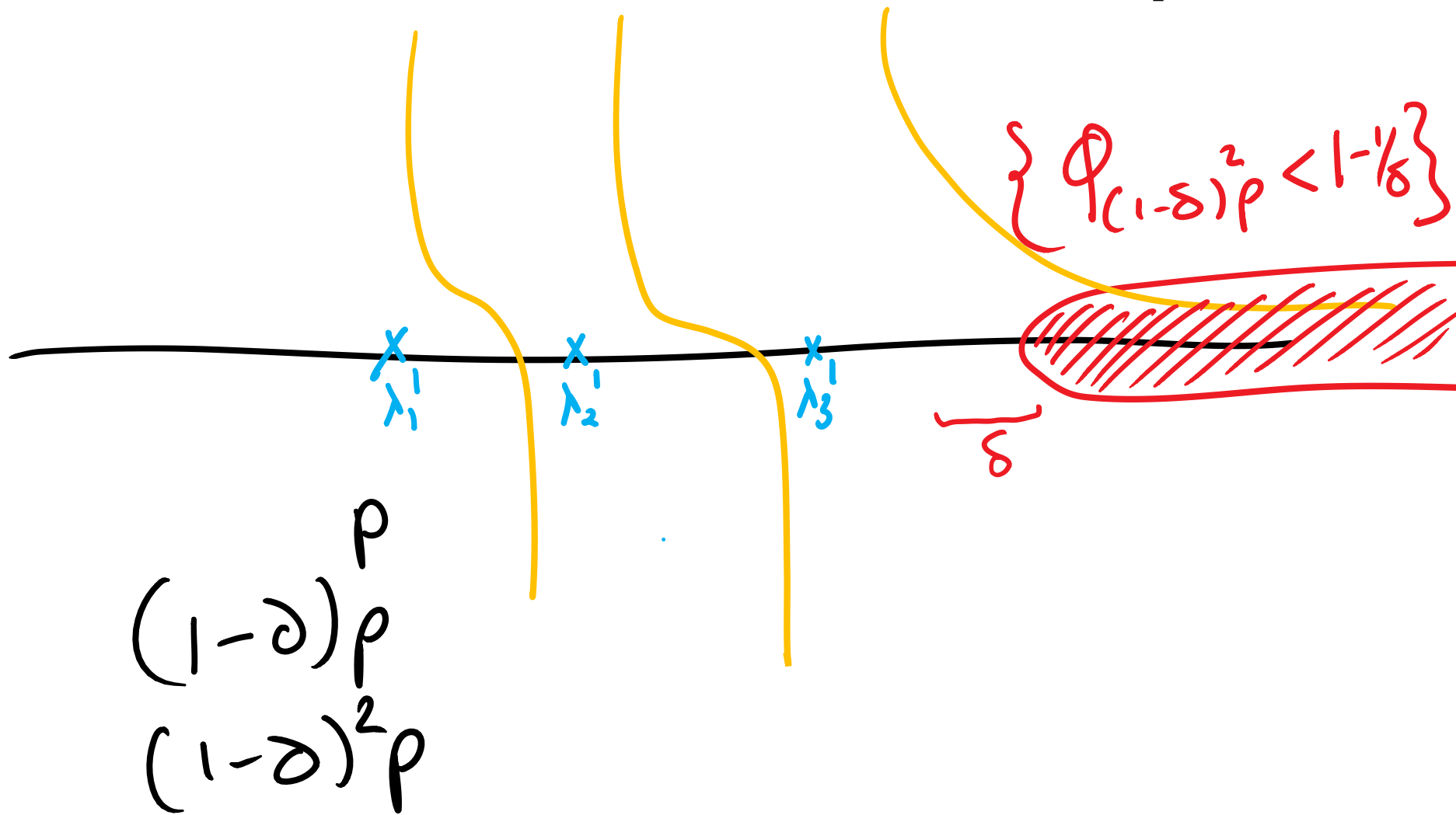
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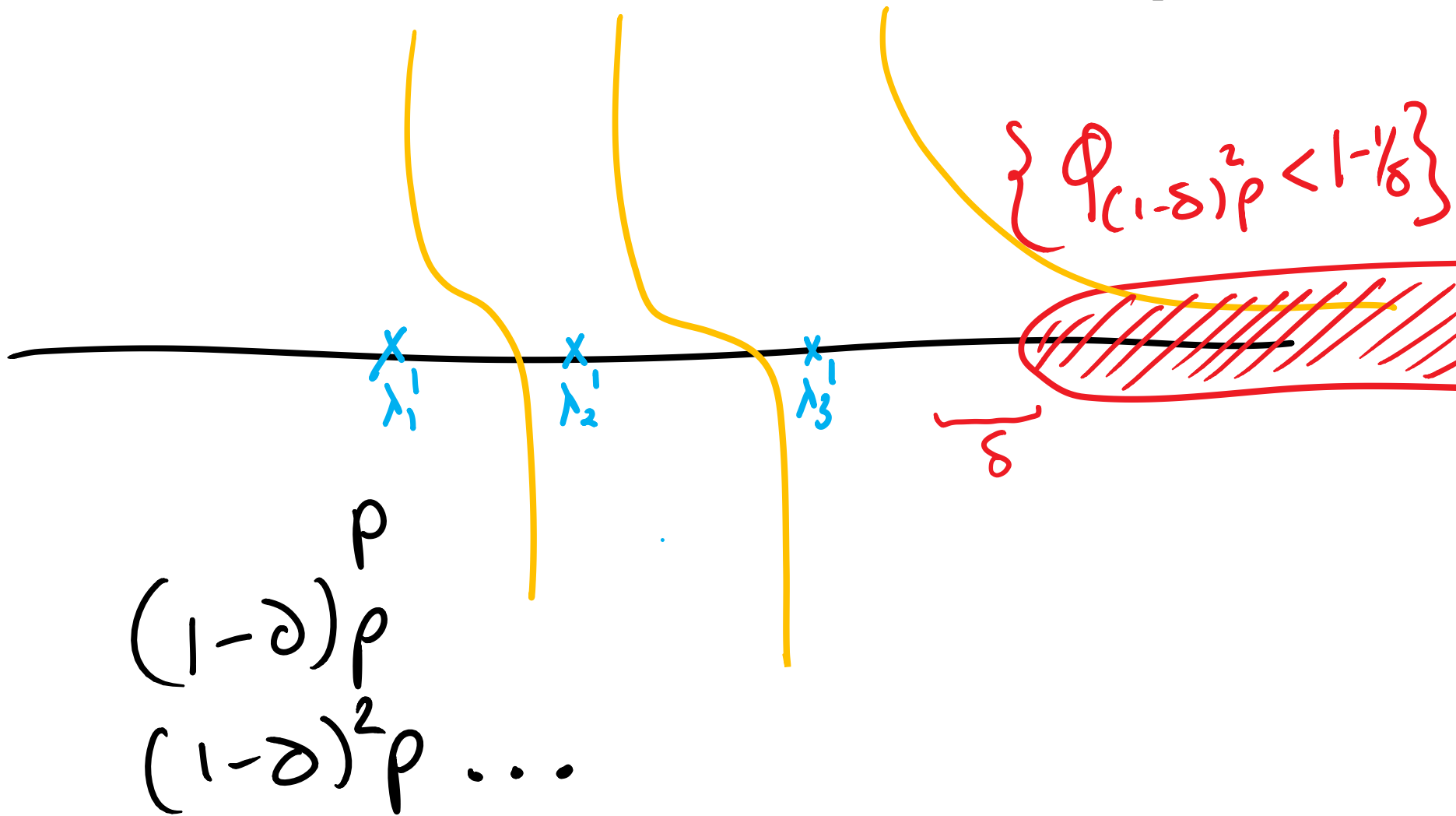
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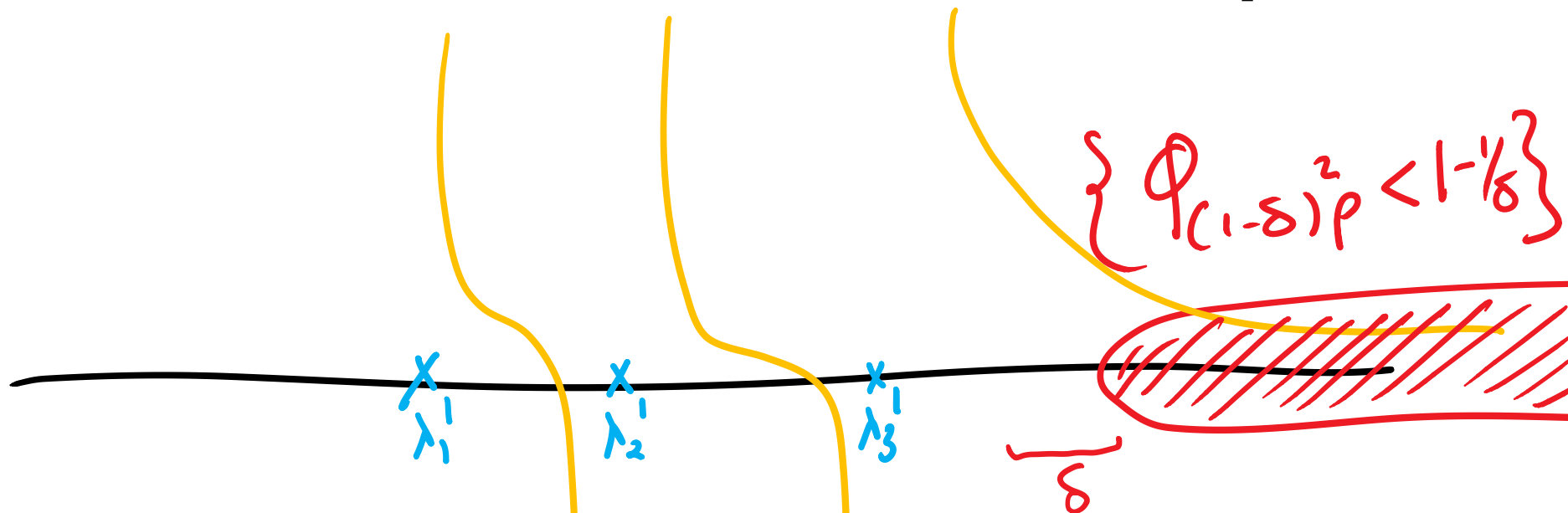
Evolution of level sets of Φ_p



Evolution of level sets of Φ_p



Evolution of level sets of Φ_p



$$\begin{aligned}
 & p \\
 & (1-\partial)p \\
 & (1-\partial)^2 p \dots
 \end{aligned}$$

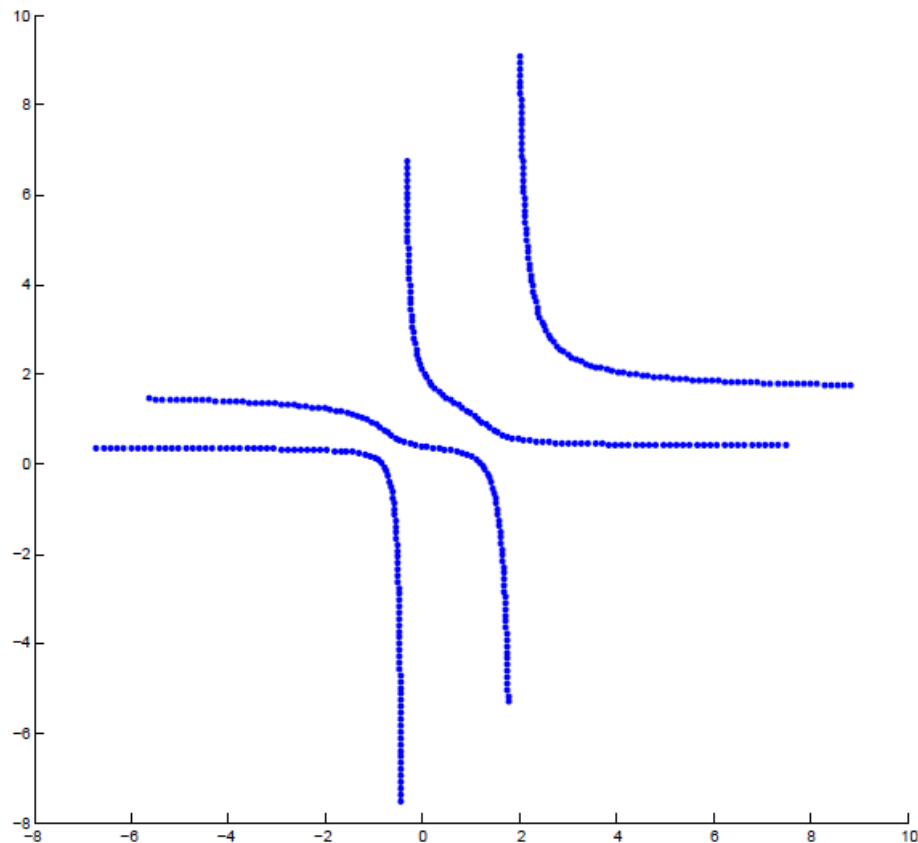
Gives bounds on $\lambda_m (1 - \partial)^k p(x)$

The Bivariate Case

Given $p(x, y)$, I want to bound the roots of
$$(1 - \partial_x)(1 - \partial_y)p(x, y)$$

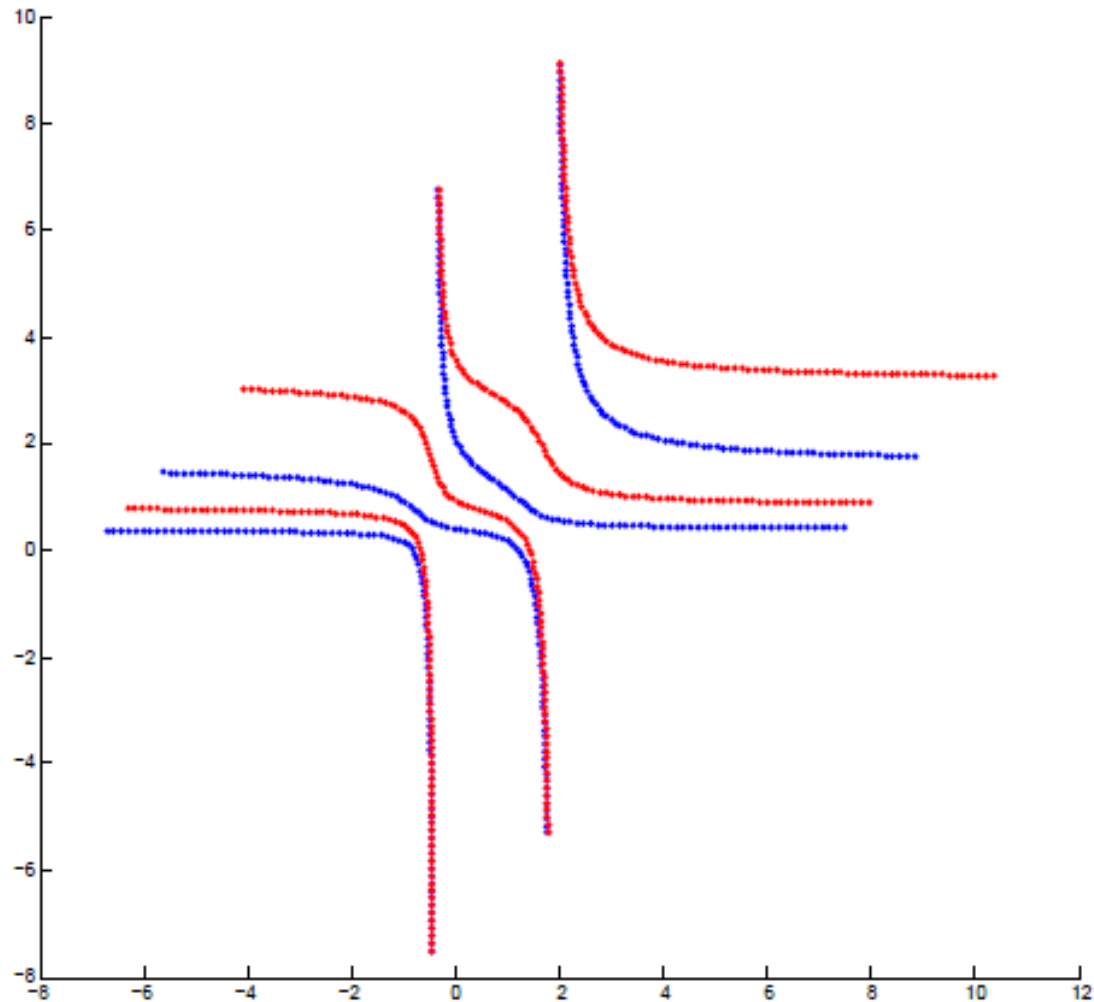
The Bivariate Case

Example: roots of $p(x, y)$ real stable.



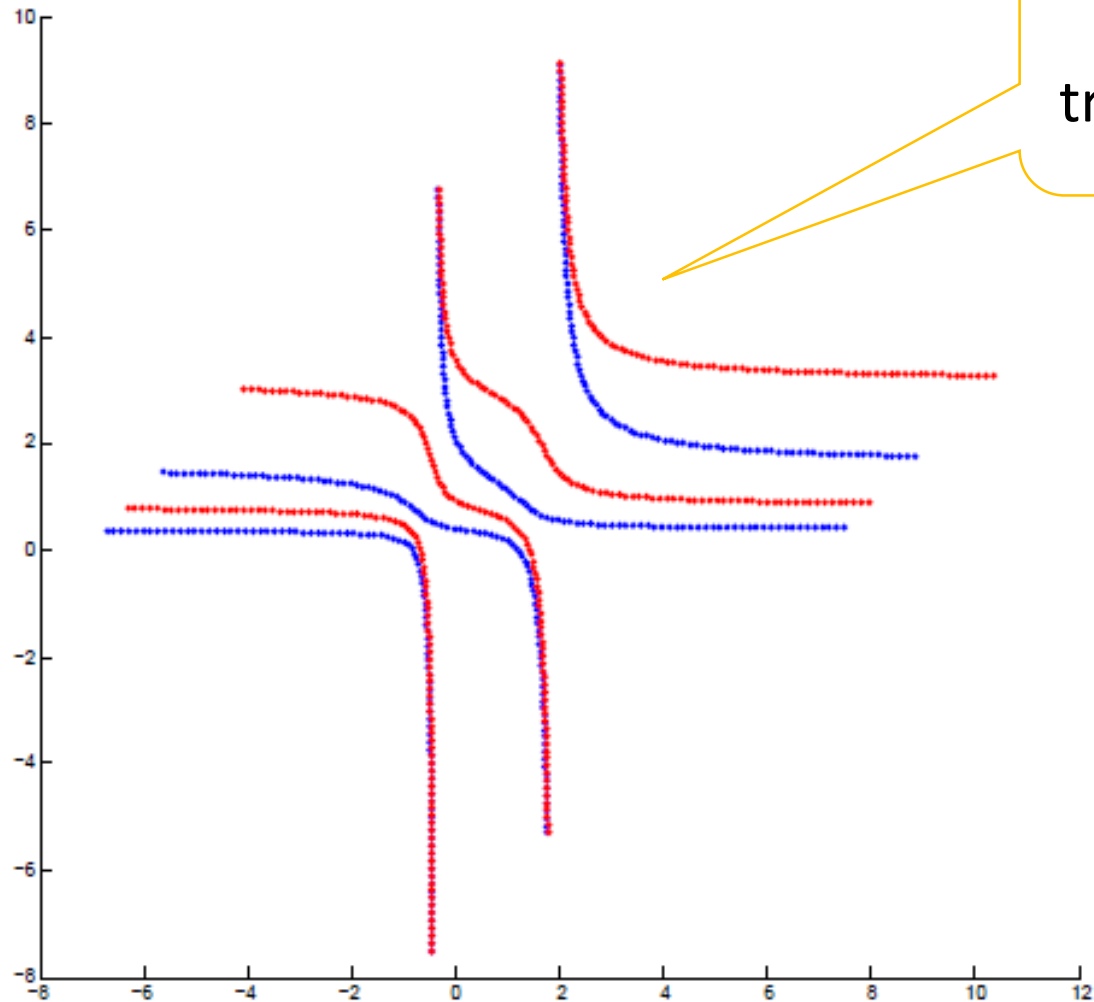
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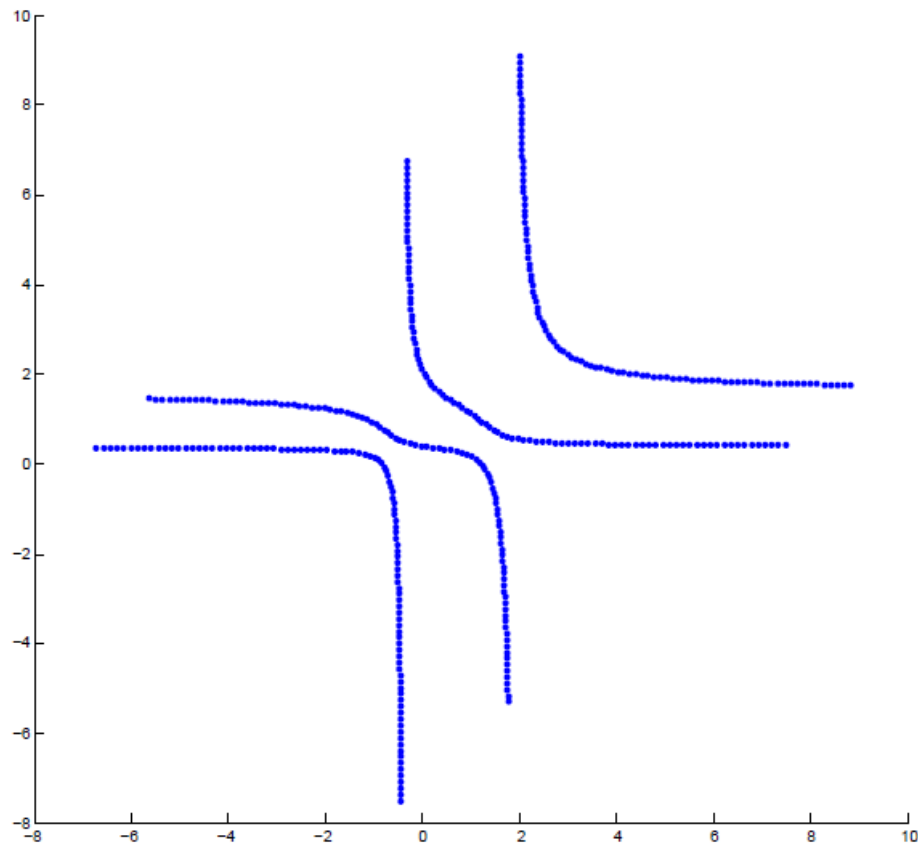
Given $p(x, y)$, I want to bound the roots of
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Define **bivariate barrier function**

$$\Phi_p(x, y) = \left(\frac{\partial_x p(x, y)}{p(x, y)}, \frac{\partial_y p(x, y)}{p(x, y)} \right)$$

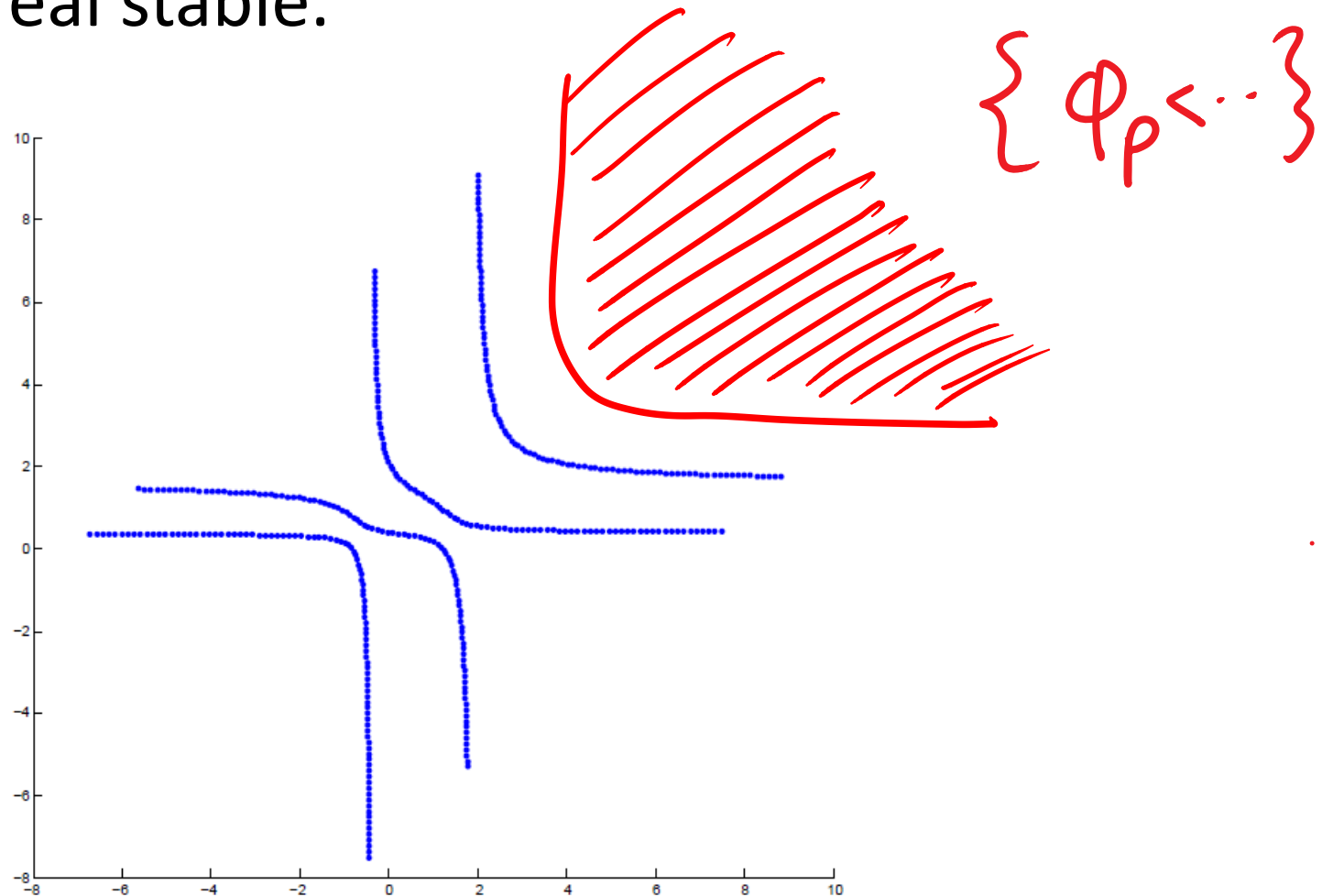
Evolution of Bivariate Φ Level Sets

$p(x, y)$ real stable.



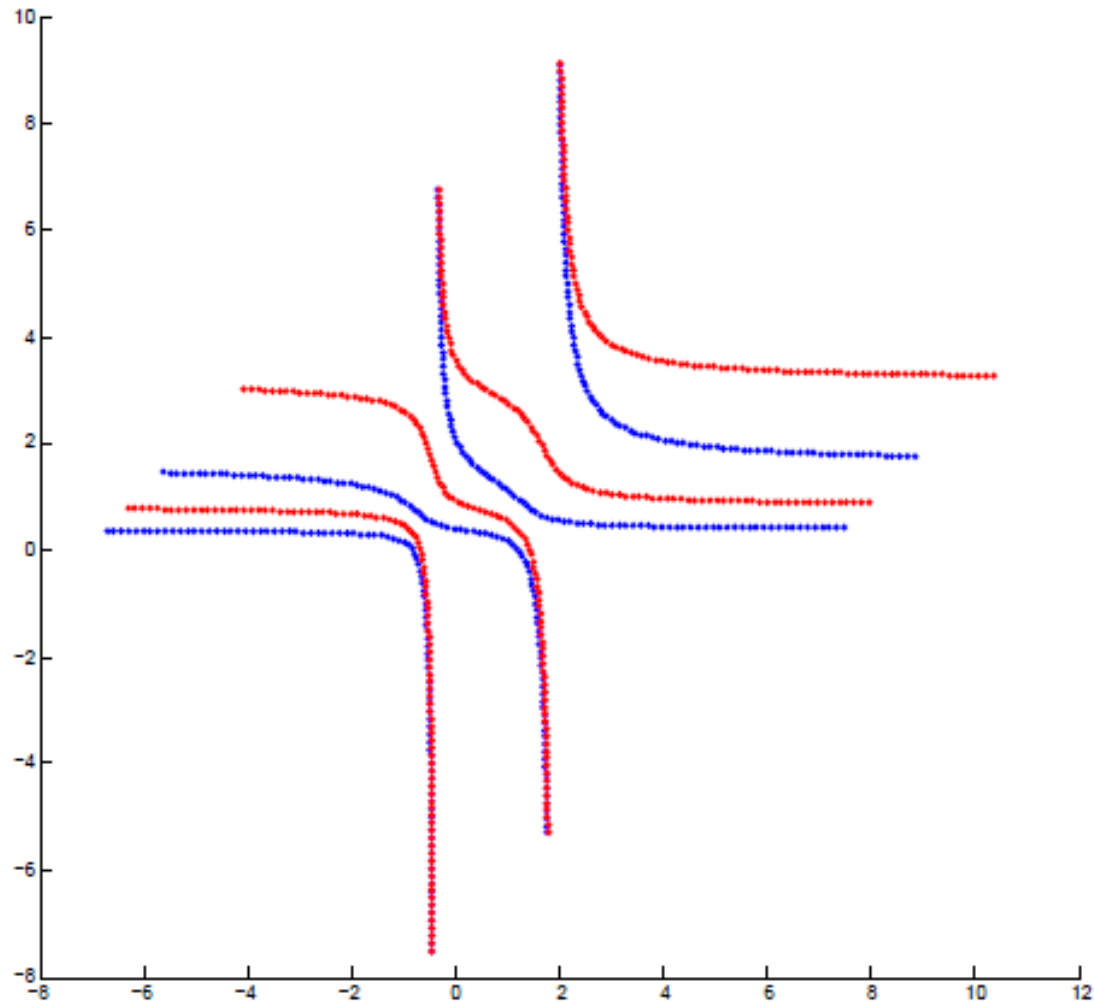
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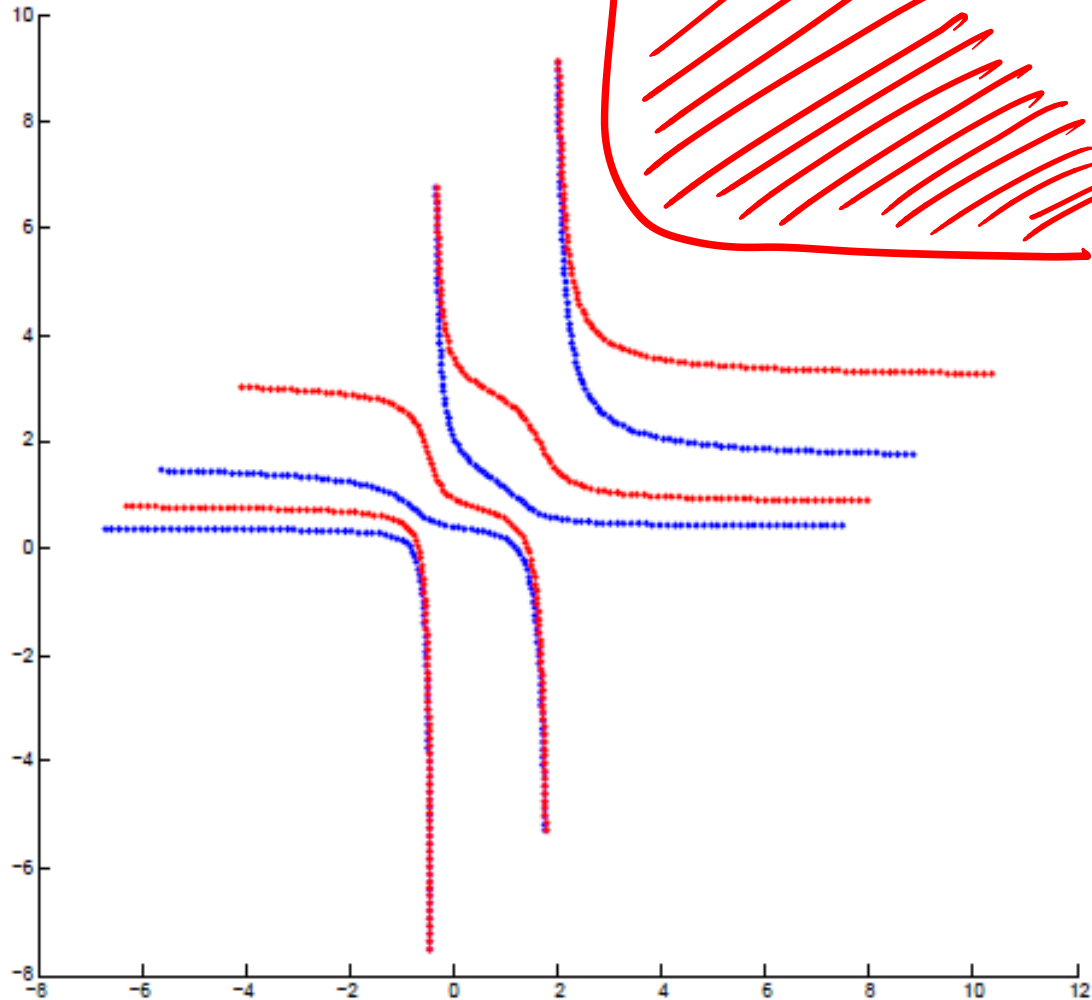
The Bivariate Case

$$(1 - \partial_y)p(x, y)$$



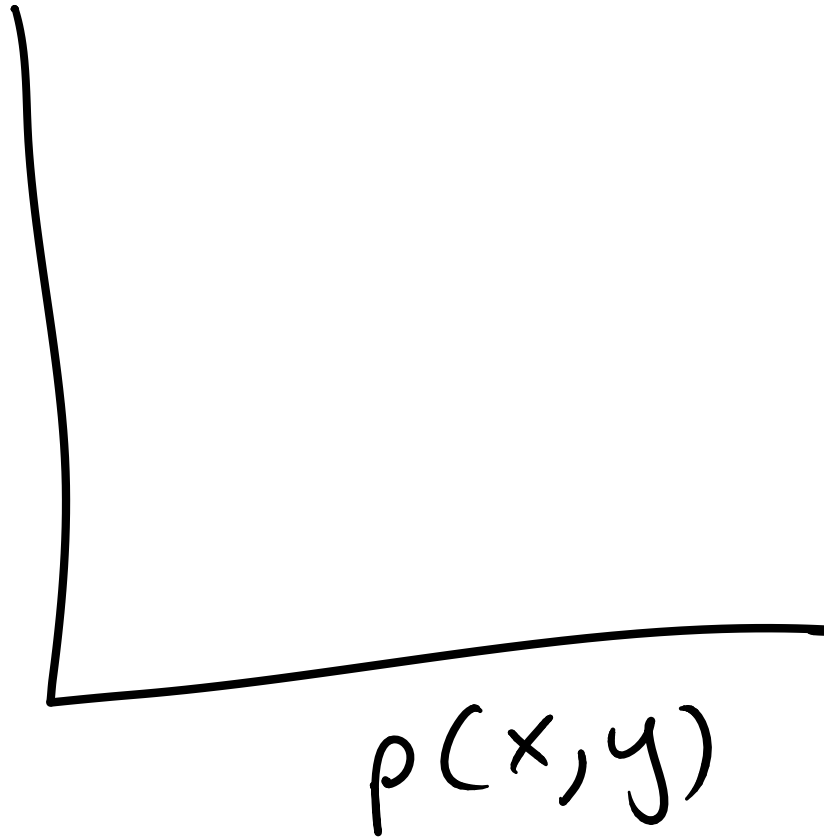
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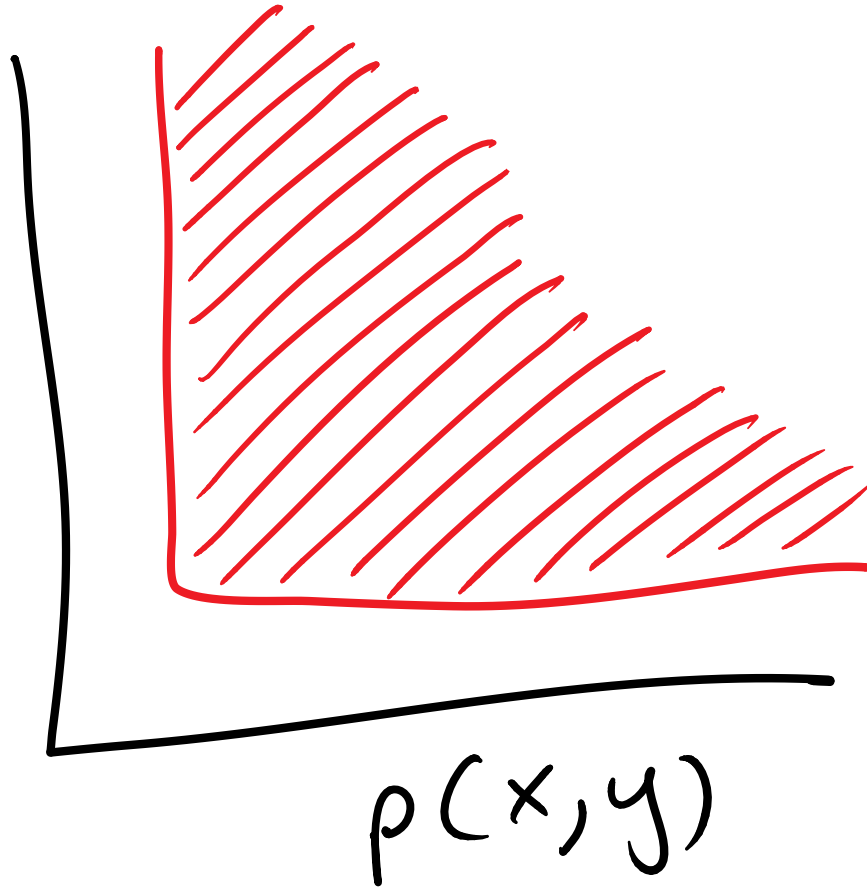


$$\left\{ \Phi_{(1-\partial_y)p} \leftarrow \dots \right\}$$

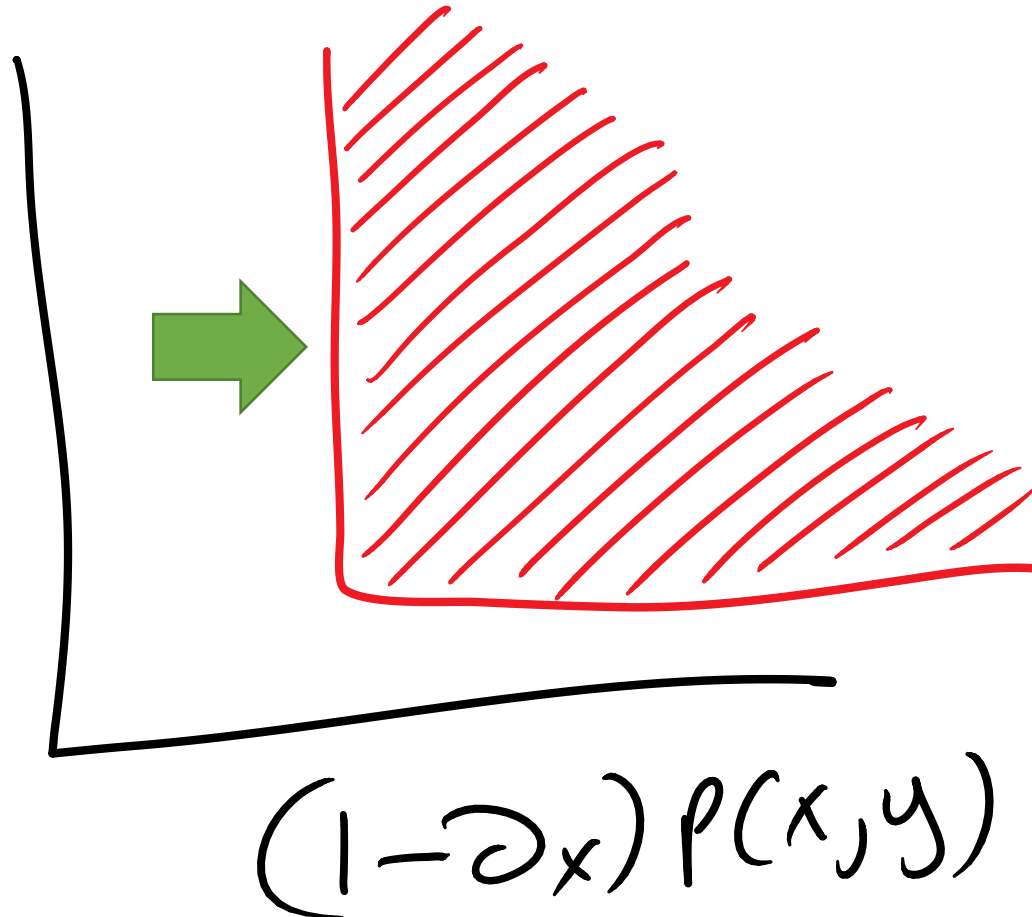
Several Perturbations



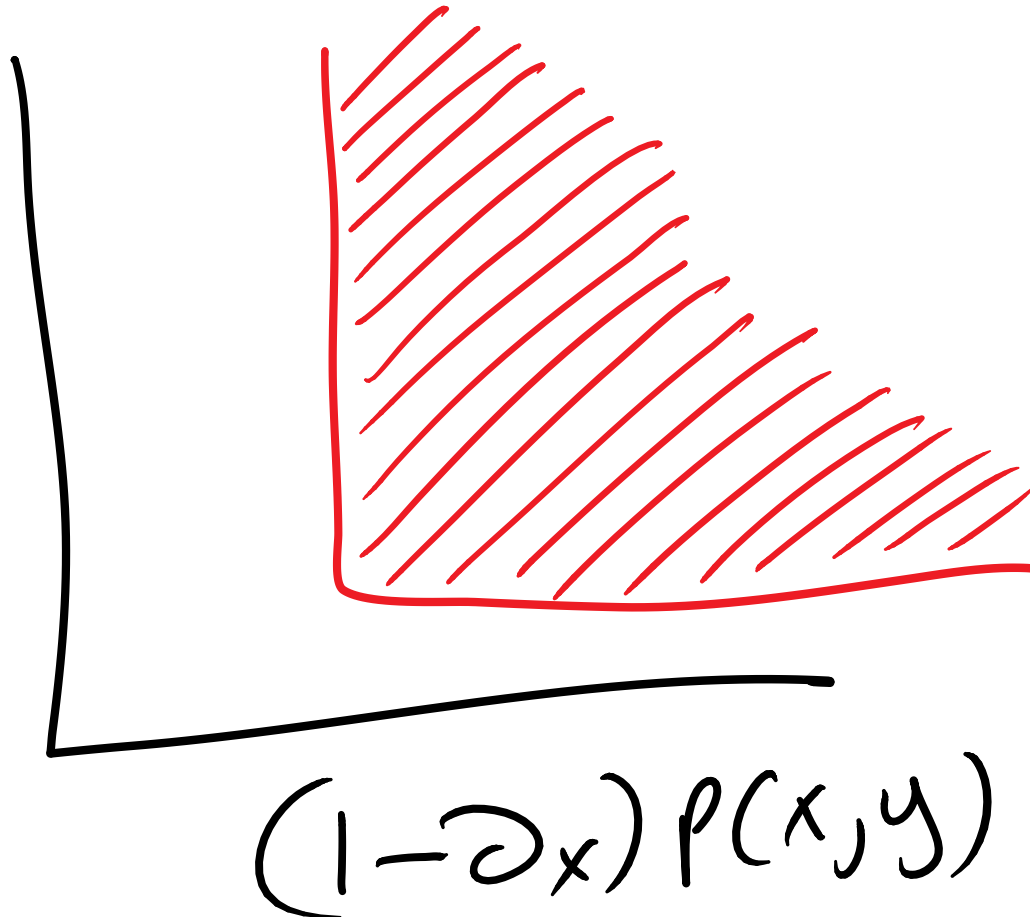
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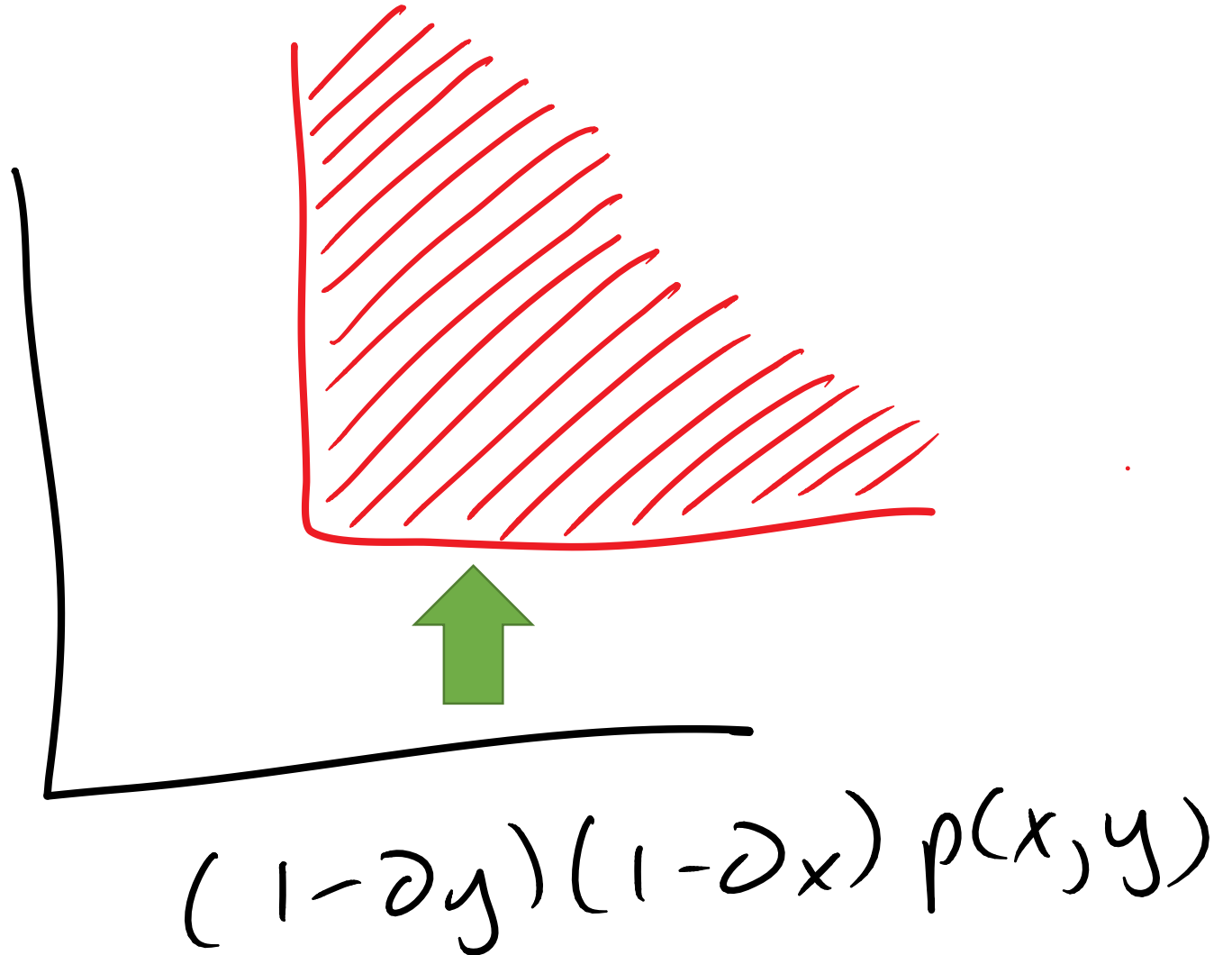
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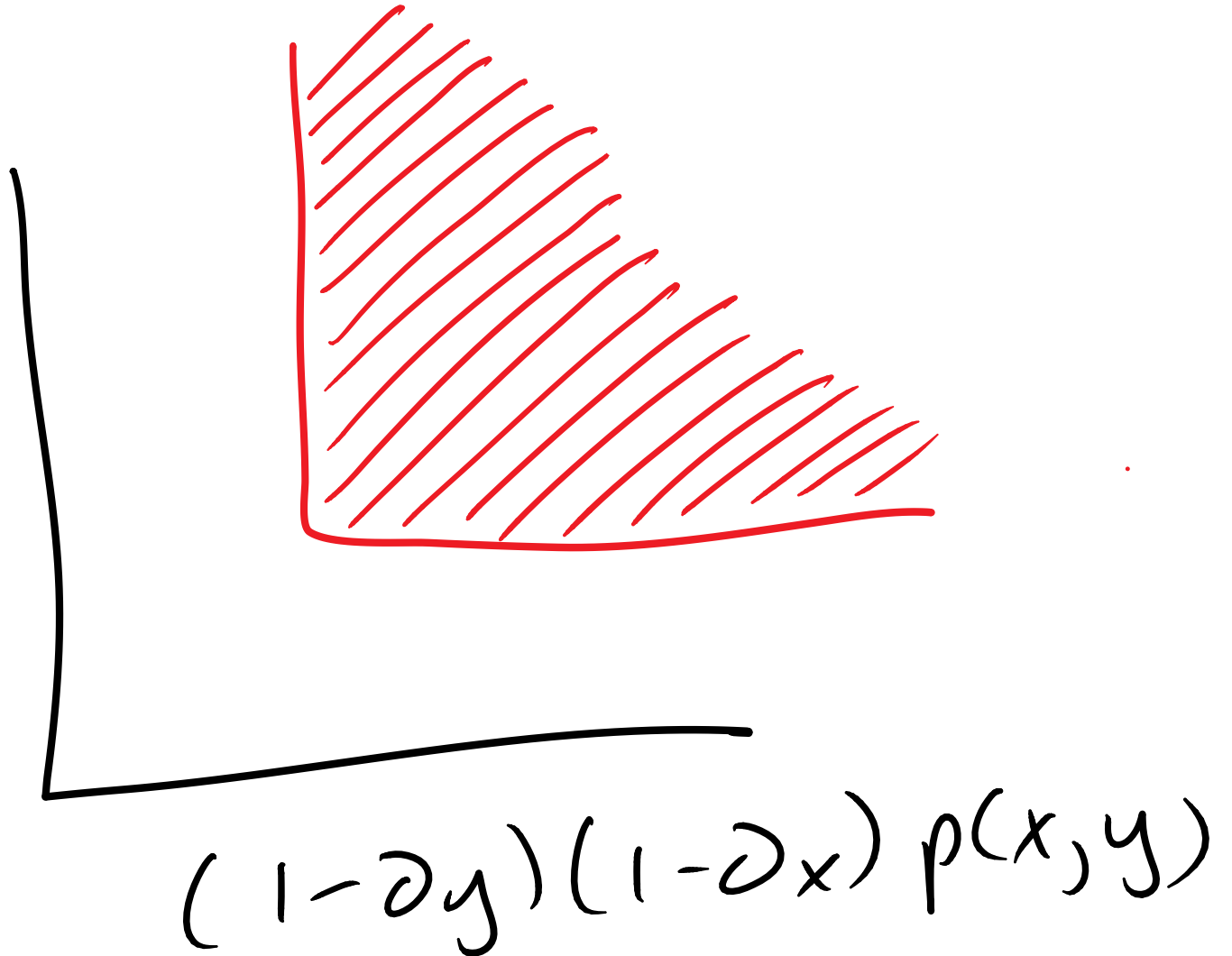
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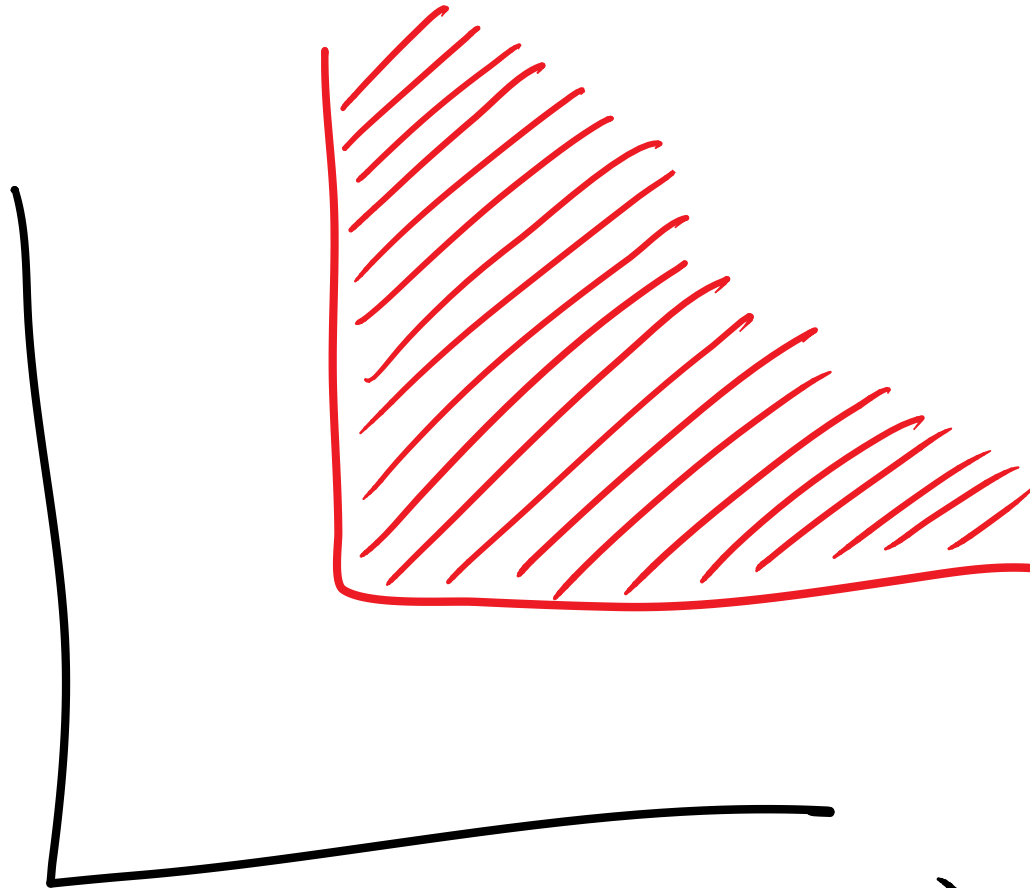
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$$(1 - \partial_y)(1 - \partial_x) p(x, y)$$

...

Key Ingredient

Helton-Vinnikov'92: All bivariate real stable polynomials are determinants:

$$p(x, y) = \det(xA + yB + C)$$

with $A \succcurlyeq 0, B \succcurlyeq 0$

This implies that the bivariate barrier has the same properties as the univariate one, and the old proof goes through.

Basic Principle

Can track the evolution of multivariate zeros under $(1 - \partial_z)$ operators by studying related rational functions.

A quantitative version of the stability preserving property.

End Result

If $\text{Tr}(A_i) \leq \epsilon$ and $\sum_i A_i = I$ then

$$\prod_{i=1}^m (1 - \partial_{z_i}) \det \left(xI + \sum_i z_i A_i \right) \Big|_{z_1 = \dots = z_m = 0}$$

Has roots bounded by $(1 + \sqrt{\epsilon})^2$

3-Step Plan

1. Show that there exist v_1, \dots, v_m with

$$\lambda_{max} \chi \left(\sum_i v_i v_i^T \right) \leq \lambda_{max} \mathbb{E} \chi \left(\sum_i v_i v_i^T \right) \quad \checkmark$$

2. Calculate

$$\mathbb{E} \chi =: \mu(x) = \prod_{i=1}^m (1 - \partial_{z_i}) \det \left(xI + \sum_i z_i A_i \right) \Big|_{z_1 = \dots = 0} \quad \checkmark$$

3. Bound the largest root $\lambda_{max} \mu(x) \leq 1 + \sqrt{\epsilon}$

$$\text{Assuming } \mathbb{E} \sum_i v_i v_i^T = I \text{ and } \|v_i\|^2 \leq \epsilon \quad \checkmark$$

Main Theorem

If $v_1, \dots, v_m \in \mathbb{R}^n$ are independent,

$$\mathbb{E} \sum_i v_i v_i^T = I \text{ and } \|v_i\|^2 \leq \epsilon$$

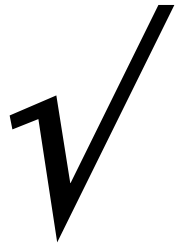
Then

$$\mathbb{P} \left[\left\| \sum_i v_i v_i^T \right\| \leq 1 + O(\sqrt{\epsilon}) \right] > 0$$

Spectral Discrepancy Theorem

Suppose $v_1, \dots, v_m \in \mathbf{R}^n$ are vectors $\|v_i\|^2 \leq \epsilon$ and

$$\sum_i v_i v_i^T = I_n$$



Then there is a partition $T_1 \cup T_2$ such that

$$\left(\frac{1}{2} - 5\sqrt{\epsilon}\right) I \preceq \sum_{i \in T_j} v_i v_i^T \preceq \left(\frac{1}{2} + 5\sqrt{\epsilon}\right) I$$

Open Questions

Quantitative analysis of other stability-preserving operators.

More applications of discrepancy theorem.

Algorithms.

Two Tools

Matrix-Determinant Lemma:

$$\begin{aligned}\det(M + vv^T) &= \det(M) \det(I + M^{-1}vv^T) \\ &= \det(M)(1 + v^T M^{-1}v)\end{aligned}$$

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Jacobi's Formula:

$$\begin{aligned}\partial_t \det(M + tA) &= \det(M) \partial_t (I + M^{-1}A) \\ &= \det(M) \operatorname{Tr}(M^{-1}A)\end{aligned}$$

$(1 - \partial_z)$ operators = rank-1 updates

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Proof of Central Identity

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