

The ellipsoid method

Ellipsoids

Consider the unit ball in \mathbb{R}^n centered at 0.

$$\begin{aligned} B(0, 1) &= \left\{ x \in \mathbb{R}^n : x_1^2 + x_2^2 + \dots + x_n^2 \leq 1 \right\} \\ &= \left\{ x \in \mathbb{R}^n : x^T x \leq 1 \right\} \end{aligned}$$



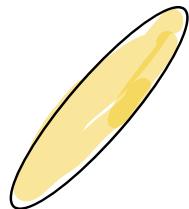
Let $A \in \mathbb{R}^{n \times n}$ be a non-singular matrix, $c \in \mathbb{R}^n$

The image of the ball under this transformation

$$x \mapsto Ax + c$$

is $\left\{ y : \underbrace{(y - c)^T (\bar{A})^T \bar{A}^{-1} (y - c)}_{\text{symmetric, positive definite}} \leq 1 \right\}$

symmetric, positive definite



An ellipsoid centered at c is a set of the form

$$\text{ell}(c, D) = \left\{ x \in \mathbb{R}^n : (x - c)^T D^{-1} (x - c) \leq 1 \right\}$$

D positive definite $\Leftrightarrow \begin{cases} D \text{ has an orthonormal basis of eigenvectors} \\ \text{All eigenvalues of } D \text{ are positive.} \end{cases}$

The outline

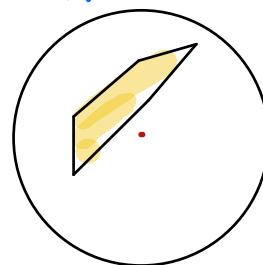
Assume: (i) The polyhedron $P := \{x : Ax \leq b\}$ is bounded and full-dimensional.
 $A \in \mathbb{R}^{m \times n}$
 $b \in \mathbb{R}^m$
(ii) Calculations can be done precisely.

Let $\nu = 4n^2\varphi$, where φ is the maximum row size of the matrix $[A | b]$.

Fact: Each vertex of P has size at most ν .

Initial radius: $R = 2^\nu$

$$P \subseteq B(0, R)$$



Khachian: Determine a sequence of ellipsoids

$$E_0, E_1, E_2, \dots, E_i, \dots \text{ s.t. } P \subseteq E_i$$

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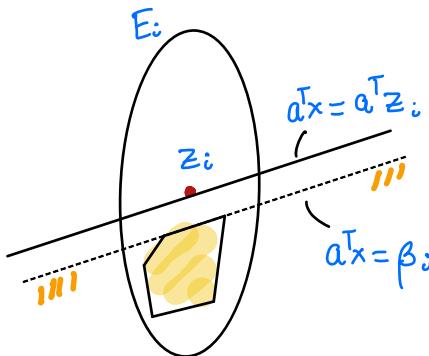
$$B(0, R) = E(z_0, D_0)$$

$$\begin{matrix} " \\ " \\ O \end{matrix} \quad \begin{matrix} u \\ R^2 \cdot I \end{matrix}$$

Iteration: Suppose z_i and D_i have been found such that

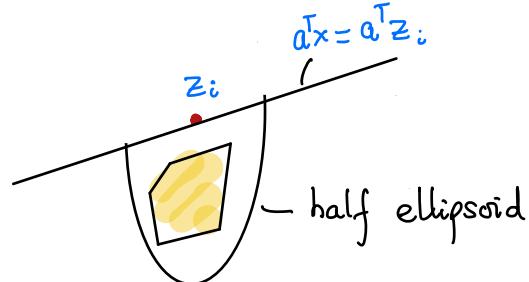
$$P \subseteq E(z_i, D_i)$$

- If $z_i \in P$, we have found a feasible solution. STOP.
- If $z_i \notin P$, then it violates an inequality of the form $a^T x \leq \beta$ in $Ax \leq b$.

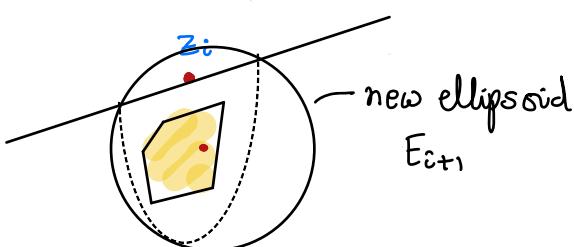


Locate such an inequality and consider

$$E_i \cap \{x : a^T x \leq \underbrace{a^T z_i}_{\text{scalar}}\}$$



$$\left(1 - \frac{1}{2^{n+2}}\right)$$



CLAIM 1: $\frac{\text{vol}(E_{i+1})}{\text{vol}(E_i)} < e^{-\frac{1}{2^{n+2}}}$

CLAIM 2: $\text{vol}(P) \geq 2^{-2n\sqrt{2}}$

Proof of CLAIM 1: Consider the special case.

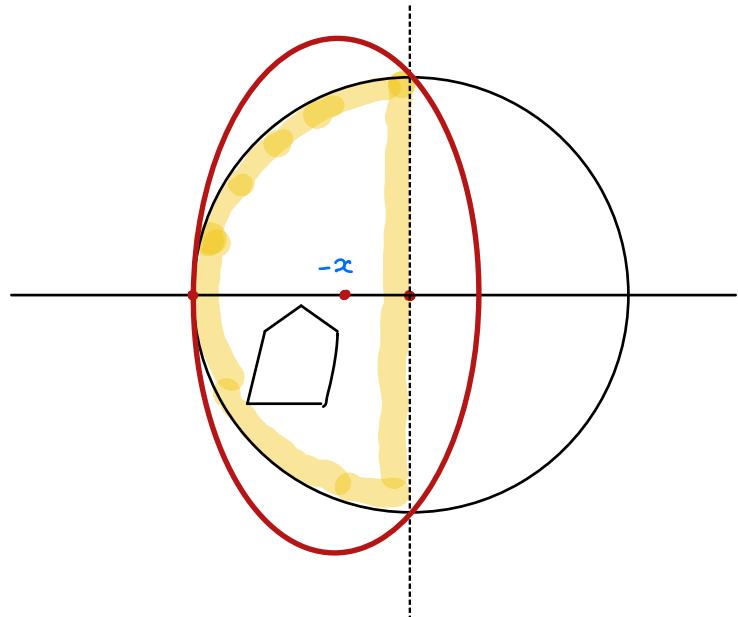
$$D_{\text{new}} = \begin{pmatrix} \lambda_1^2 & & \\ & \lambda_2^2 & \\ & & \lambda_n^2 \end{pmatrix}$$

$$\lambda_1^2 = (1-x)^2$$

$$\frac{x^2}{(1-x)^2} + \frac{1}{\lambda_2^2} = 1$$

$$\downarrow$$

$$\lambda_2^2 = \frac{(1-x)^2}{1-2x}$$



$$\frac{\text{vol(new)} }{\text{vol(old)}} = \lambda_1 \lambda_2 \dots \lambda_n$$

$$= \frac{(1-x)^n}{(1-2x)^{(n-1)/2}}$$

to minimize this choose

$$x = \frac{1}{n+1}$$

$$\frac{\text{vol(new)} }{\text{vol(old)}} = \left(\frac{n/n+1}{(n-1)/(n+1)} \right)^{(n-1)/2}$$

$$= \left(\frac{n}{n+1} \right) \left(\frac{n^2}{n^2-1} \right)^{\frac{n-1}{2}}$$

$$\leq \left(1 - \frac{1}{n+1} \right) \left(1 + \frac{1}{n^2-1} \right)^{\frac{n-1}{2}} \leq \exp\left(-\frac{1}{n+1}\right) \exp\left(\frac{n-1}{2(n+1)}\right)$$

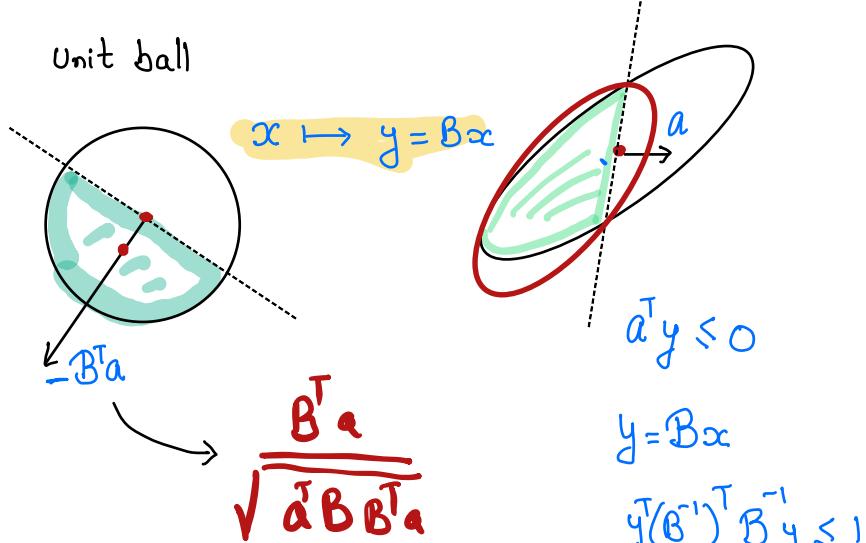
$$= \exp\left(\frac{-1}{2(n+1)}\right)$$

In general,

$$z_{\text{new}} = z - \frac{1}{n+1} \frac{\mathcal{D}a}{\sqrt{a^T \mathcal{D}a}}, \quad \mathcal{D}_{\text{new}} = \frac{n^2}{n^2-1} \left(\mathcal{D} - \frac{2}{n+1} \frac{\mathcal{D}aa^T \mathcal{D}}{a^T \mathcal{D}a} \right)$$

How?

Unit ball



$$a^T B x \leq 0$$

$$\text{i.e., } (B^T a)^T x \leq 0$$

$$z_{\text{new}} = -\frac{1}{n+1} \frac{B^T a}{\sqrt{a^T B B^T a}}$$

$$\frac{B^T a}{\sqrt{a^T B B^T a}}$$

$$y = Bx$$

$$\underbrace{y^T (B^{-1})^T B^{-1} y}_{\mathcal{D}^{-1}} \leq 1$$

$$\mathcal{D} = B B^T$$

$$= -\frac{1}{n+1} \frac{B^T a}{\sqrt{a^T \mathcal{D} a}} \quad \mapsto \quad -\frac{1}{n+1} \frac{B B^T a}{\sqrt{a^T \mathcal{D} a}}$$

$$= -\frac{1}{n+1} \frac{\mathcal{D} a}{\sqrt{a^T \mathcal{D} a}}$$

Check that a similar computation yields

$$\mathcal{D}_{\text{new}} = \frac{n^2}{n^2-1} \left(\mathcal{D} - \frac{2}{n+1} \frac{\mathcal{D} a a^T \mathcal{D}}{a^T \mathcal{D} a} \right)$$

Assumptions : (i) The polyhedron $P := \{x : Ax \leq b\}$ is bounded and full-dimensional.
 $A \in \mathbb{R}^{m \times n}$
 $b \in \mathbb{R}^m$

(ii) Calculations can be done precisely.

$$Ax \leq b$$

$$\tilde{A}\tilde{x} = b$$

$$x \geq 0$$

We may assume all coordinates of x are at most ν .
 $-R \leq x_i \leq R$

$$a^T x \leq \beta + \varepsilon$$

$$Ax \leq b + \begin{pmatrix} \varepsilon \\ \varepsilon \\ \vdots \\ \varepsilon \end{pmatrix}$$



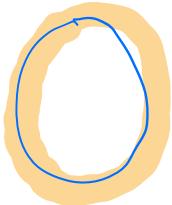
Approximations

Theorem (Approximating Ellipsoids)

$E = \text{ell}(z, D)$, eigenvalues of $D \in [\delta^2, S^2]$.

$$\epsilon > 0, p \geq 3n + |\log_2 S| + 2|\log_2 \delta| + |\log_2 \epsilon|$$

$(\tilde{z}, \tilde{D}) = (z, D)$ rounded to p bits of the fractional part (keeping \tilde{D} symmetric)



- (i) eigenvalues(\tilde{D}) $\in \left[\frac{1}{2}\delta^2, 2S^2\right]$
 - (ii) $E \subseteq B(\tilde{E}, \epsilon)$
 - (iii) $\frac{\text{vol}(\tilde{E})}{\text{vol}(E)} \leq 1 + \epsilon$
-

Theorem: $E = \text{ell}(z, D)$, eigenvalues $\in [\delta^2, 2S^2]$.

H an affine space containing z ; $\epsilon \geq 0$.

$$B(E, \epsilon) \cap H \subseteq B(E \cap H, \epsilon S / \delta)$$

