

Computational complexity : Lecture 5.

Agenda: Diagonalisation -

- ▷ Time hierarchy theorems
- ▷ Ladner's theorem.

Recap: - $P = \bigcup_{c \geq 0} \text{DTIME}(n^c)$.

- $NP = \bigcup_{c \geq 0} \text{NTIME}(n^c)$

- Also saw other classes like coNP , NEXP , EXP etc.

How do we show certain tasks are not in a class \mathcal{C} ?

Qn: Can you give me a task that cannot be solved in P ?

Halting

Qn: Can you give me a task that can be solved in $O(n^3)$ but cannot be solved in $O(n)$?

Task: on 1^n , print n^3 ones.

Qn: What about decision tasks? As languages,
is $\text{DTIME}(n) \subsetneq \text{DTIME}(\frac{2^n}{n^2})$

Diagonalisation :

- uncountability of reals

- ...

Time Hierarchy Theorem: Suppose $f: \mathbb{N} \rightarrow \mathbb{N}$ & $g: \mathbb{N} \rightarrow \mathbb{N}$ are time constructible and g is "sufficiently bigger" than f . Then

$$\text{DTIME}(f(n)) \subsetneq \text{DTIME}(g(n)).$$

$$*: f(n) \log f(n) = o(g(n))$$

We will assume $f(n) = n$ $g(n) = n^3$.

Candidate: $\{(\alpha, x) : M_\alpha \text{ accepts } x \text{ in } n^2 \text{ steps}\}$.

Pf: Idea:

	x_1	x_2	...
M_1	A	R	
M_2	A	A	
.	R	A	
.			
.			

$$D(i) = \neg M_i(x_i)$$

D : On input (α, x) :

Use the UTM for n^2 steps to simulate M_α on (α, x) .

Reject only if M_α accepts by then. Else, accept.

Claim 1: $L(D) \in \text{DTIME}(n^3)$

Claim 2: $L(D) \notin \text{DTIME}(n)$.

Recall: The UTM, on input $(\alpha, x, 1^t)$ can simulate M_α on x for t steps in time $c \cdot t \log t$.
 where c depends only on M_α 's alphabet size, #tapes.

Pf of Claim 1: Duh!

□.

Pf of Claim 2: Suppose, for contradiction S solves it in time n .

Let α be a description of S that is really long.

$|\alpha| = l$

What does S do on $(\alpha, 1^l)$?

S accepts $(\alpha, 1^l) \iff D$ accepts $(\alpha, 1^l)$

↓
↑

M_α rejects $(\alpha, 1^l)$

\iff UTM for n^2 steps saw M_α reject $(\alpha, 1^l)$

t steps of M_α can be sim in $c \cdot t \log t$ steps of UTM.

$\Rightarrow \exists n$ is large enough, $n^2 > c \cdot n \log n$. □.

What about with non-determinism?

If $f \ll g$, is $\text{NTIME}(f) \subsetneq \text{NTIME}(g)$?

Non-det time hierarchy thm: f, g time constructible with " $f \ll g$ ". Then $\text{NTIME}(f) \subsetneq \text{NTIME}(g)$.

Why doesn't the same proof work?

In non-determinism, flipping is expensive?

Recall NP vs coNP.

[AB] has a proof of this thm using "epochs".

We'll see a different proof by Fortnow-Santhanam.

Key: When we want to flip, we'll do det. simulation.

Pf: D: On input (x, α, y) :

▷ If $|y| < |\alpha| + |\alpha|$: Use the N. UTM for n^2 steps
simulate M_α on (x, α, y_0) & (x, α, y_1)
Accept if M_α accepts both.

▷ If $|y| \geq |\alpha| + |\alpha|$:
Simulate deterministically M_α on (x, α, ϵ)
by using y as the guesses.
Flip the answer.

Claim: $L(D) \in \text{NTIME}(n^3)$

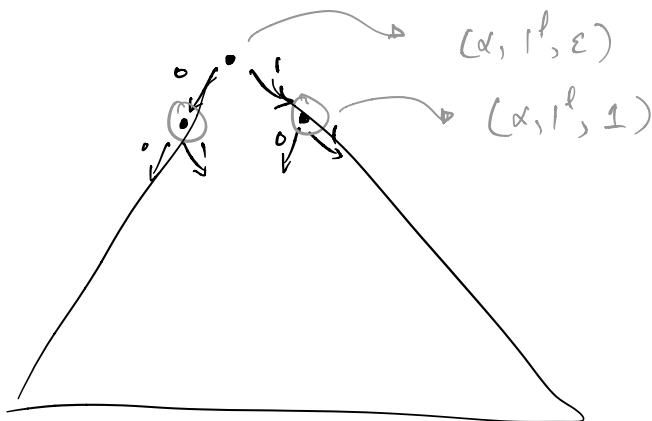
Pf: Duh!

Claim: $L(D) \notin \text{NTIME}(n)$.

Pf: Assume S is a N.TM that solves $L(D)$ in time n

Assume α is a long enough encoding of S so that UTM for n^2 steps completely simulates n steps of S . Let $|\alpha| = l$

We will fix α, l and vary y .



S acc (α, l^p, ϵ)
 \Downarrow
 D accepts (α, l^p, ϵ)
 \Downarrow
 D acc $(\alpha, l^p, 0)$
 & $(\alpha, l^p, 1)$
 \Downarrow
 \vdots

D accepts (α, l^p, y) \Leftrightarrow
 $\forall y: |y| \leq |\alpha| + l$
 \Downarrow

D accept (α, l^p, y)
 $\forall y: |y| < |\alpha| + l$

S , on guess y , rejects
 (α, l^p, ϵ)

$\Leftrightarrow S$ rejects $(\alpha, l^p, \epsilon) \quad \square$.

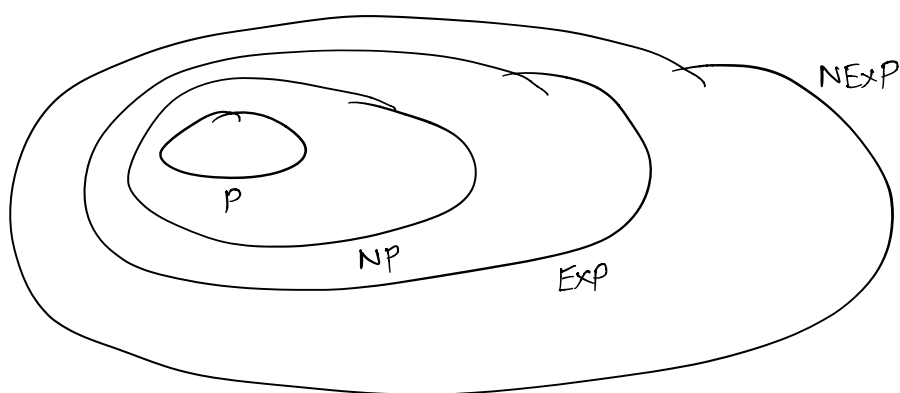
$\forall y: |y| \leq |\alpha| + l$.

Actual thm statement: f, g time-constructible with
 $f(n+1) = o(g(n))$, then $\text{NTIME}(f(n)) \subsetneq \text{NTIME}(g(n))$

Where is the log factor?!

Non-det UTM simulation only has a constant overhead.

(Ex 2.6 in Arora-Barak)



$$P \subsetneq EXP$$

$$NP \subsetneq NEXP$$

Another application of diagonalisation:

Let us assume we are in the world where $P \neq NP$.

Can it be the case that every problem not in P is actually NP-complete?

Or are there "NP-intermediate" languages?

Ladner's Theorem: Suppose $P \neq NP$. Then there are languages that are neither in P nor NP-complete.

Pf: Idea: How can we make SAT easier?

Give more time...

For $H: \mathbb{N} \rightarrow \mathbb{N}$, non-dec. function.

$$SAT_H = \left\{ (\varphi, \perp^n) : |\varphi| = n, \varphi \in SAT \right\}$$

SAT with the "right" padding.

Want to show: SAT_H is NP-hard $\Rightarrow P = NP$. How?!

$$SAT \leq_p SAT_H$$

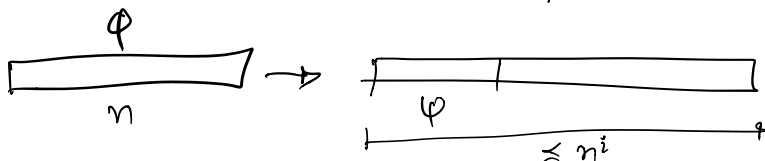
$$\varphi \mapsto (\varphi, \perp^{H(m)})$$

$m = |\varphi|$

Suppose $H(m) \rightarrow \infty$

\Rightarrow For large m ,

$$H(m) \geq 2i$$



$$\Rightarrow m^{H(m)} \leq n^i$$

$$m \leq n^{i/H(m)} \leq \sqrt[n]{n}$$

We also want $SAT_H \in NP$

$(\varphi, 1^{\ell}) \stackrel{?}{\in} SAT_H$ in NP?

If $H(n)$ can be computed in poly time, then $SAT_H \in NP$.

Want to show: $SAT_H \in P \Rightarrow P=NP$.

If it so happens that SAT_H is NP-complete, then
 $SAT_H \in P \Rightarrow P=NP$.

Suppose $H(n)$ is eventually constant,
i.e. $H(n) = i \quad \forall n \geq n_0$.

then
 $SAT \leq_p SAT_H: \quad \varphi \mapsto (\varphi, 1^{n^i})$

Cool Idea: We will cleverly choose H so that
 H is eventually constant if $SAT_H \in P$
 H is inc. otherwise.

Defn: $H(m)$:

The smallest $i \leq \log \log m$ st the machine
D.TM M_i solves SAT_H on inputs of length $\leq \log m$
in n^i time.

If no such i , then $H(m) = \log \log m$.

Ex: $H(m)$ is computable in poly(m) time.

Lemma: If $SAT_H \in P$, then H is eventually constant.

Pf: If $SAT_H \in P \Rightarrow SAT_H \in DTIME(n^i)$ for some i .

$\therefore SAT_H \in P \Rightarrow SAT_H$ is NP-hard $\Rightarrow P=NP$

$SAT_H \notin P \Rightarrow H$ is increasing.

\Rightarrow Any poly time redn from $SAT \rightarrow SAT_H$
gives a length-dec. redn from
 $SAT \rightarrow SAT$

$\Rightarrow SAT_H$ is NP-hard $\Rightarrow P=NP$. \square

Summary:

- Diagonalisation is a powerful tool.
 $P \subsetneq EXP$, $NP \subsetneq NEXP$

Next time: - What are some limitations of this technique?
- Can "such arguments" show $P \neq NP$?