

Today

- Space Complexity III
- Certificate defn of NL
- $NL = coNL$
- Ramprasad: PH

CSS.203.1

Computational
Complexity

- Lecture #9
- Instructor: (15 Mar '21)
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Recall: Space Complexity

L , NL , $PSPACE$

- Non-deterministic space can be simulated in det-space w/ at most a quadratic overhead (Barrington's Theorem)
- NL : logspace reductions (polynomial time reduction)
 $PATH$ is NL -complete

Today: $coNL$ / \overline{PATH}

NP : 2 defns

- { Non-deterministic TMs }
- { Verifier }

NL : - { Non-deterministic Space TMs }

- { Is there a verifier defn for NL ? }

NP: Verifier defn

$L \in NP$ if \exists a TM M & two poly p, q
st

$$x \in L \Leftrightarrow \exists y \in \{0,1\}^{p(|x|)}, M(x,y) = 1$$

& M runs in time at most $q(|x|)$.

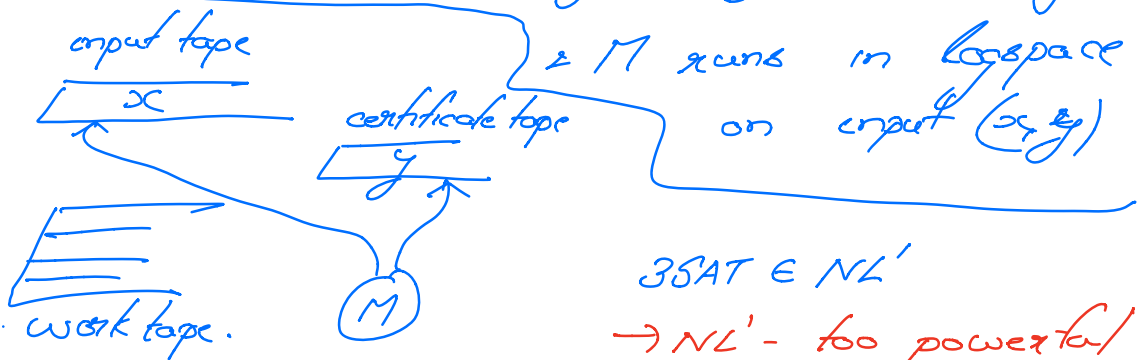
Similar verifier defn for NL.

Can the seq of non-deterministic guesses
serve as the certificate y ?

Attempt:

$A \in NL'$ if \exists a logspace TM M
& a poly $p()$

$$x \in A \Leftrightarrow \exists y \in \{0,1\}^{p(|x|)} \text{ st } M(x,y) = 1$$



$3SAT \in NL'$

$\rightarrow NL'$ - too powerful
Since it can access
the entire cert y at
any time.

Fix: Make certificate tape READ-ONCE

$A \in NL$ iff \exists a 2-input tape Machine M
 (1st input tape - standard read only c/p.
 (2nd input tape - read once certificate tape)

\exists a poly $p(\cdot)$ s.t.

$$x \in A \Leftrightarrow \exists y \in \{0,1\}^{p(|x|)} \\ M(x,y) = 1$$

$\hookrightarrow M$ runs in logspace.

$\overline{PATH} = \{(G, s, t) \mid G \text{ is a directed graph} \\ \wedge \text{there is no path} \\ \text{from } s \text{ to } t \text{ in } G\}$

Theorem [Immerman - Szepietowski]

$\overline{PATH} \in NL$

Hence, $NL = coNL$

Pf:

s - source vertex

t - target vertex

$C_i = \{v \in V(G) \mid \exists \text{ a path of length} \\ \text{at most } i \text{ from } s \text{ to } v\}$

$C_0 = \{s\}$, $C_n = \{v \mid s \rightsquigarrow v\}$

NL-certificate: " $t \notin C_n$ "

" $v \notin C_i$ " $\forall i \in \{0, \dots, n\}$ & $v \in V(G)$

(a) Assume $|C_i|$, then there exists an NL-certificate that " $v \notin C_i$ ".

(b) Assume $|C_{i-1}|$, there exists an NL-certificate for " $|C_i| = c$ ".

(a). Verifier knows $|C_i| = c$

$C_i = \{v_{i_1}, v_{i_2}, \dots, v_{i_c}\}$

NL-certificate for " $v \notin C_i$ " (given $|C_i| = c$)

Certificate for " $v \notin C_i$ "

$\left. \begin{array}{l} v_{i_1} \text{ - path } s \rightarrow v_{i_1} \\ v_{i_2} \text{ - path } s \rightarrow v_{i_2} \\ \vdots \\ v_{i_c} \text{ - path } s \rightarrow v_{i_c} \end{array} \right\}$ and the indices of v_{i_j} are increasing

$v \notin \{v_{i_1}, \dots, v_{i_c}\}$

(a). Given $|C_i|$, NL-certificate for " $v \notin C_i$ "

(6)' : Given $|C_i|$, NL-certificate for " $v \notin C_i$ "

Same as above except
check that $v \notin \{v_1 \dots v_n\}$
 v is not adjacent to
 $\{v_1 \dots v_n\}$.

(6) Given $|C_i|$, NL-certificate for " $|C_i|=c$ "

$v_1 \notin C_i$ - NL-cert

$v_2 \in C_i$ - NL-cert

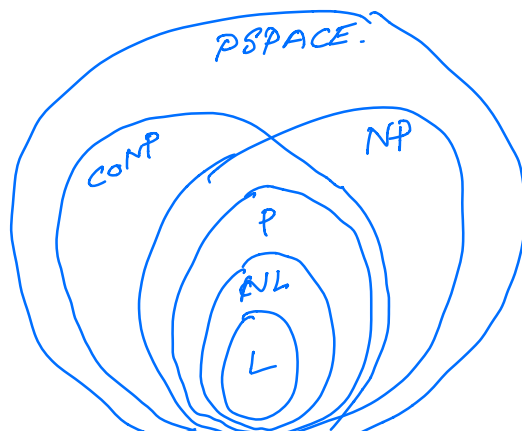
\vdots

$v_n \notin C_i$

Hence, $\overline{\text{PATH}} \in \text{NL}$.

$\text{coNL} = \text{NL}$.

For any \mathcal{C}
 $\text{co}\mathcal{C} \subseteq \mathcal{C}$
 $\mathcal{C} \subseteq \text{co}\mathcal{C}$



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