


Computational Complexity - Lecture 10.

- Agenda:
- More about the polynomial hierarchy
 - Defn via oracles
 - Alternating TMs.
 - Time-space tradeoffs for SAT.

Recap: $\Sigma_2^P = \{ L : x \in L \Leftrightarrow \exists y. \forall z. M(x, y, z) = 1 \}$.

$\Pi_2^P = \{ L : x \in L \Leftrightarrow \forall y \exists z. M(x, y, z) = 1 \}$
Similarly for other Σ_i^P, Π_i^P .

$\Sigma_i = \Pi_i \Rightarrow$ PH collapses to Σ_i / Π_i .

 Does not extend to PSPACE = Σ_i !

Σ_2^P and oracles:

Qn: Is $\Sigma_2^P = NP^{NP}$?

Attempt towards showing this:

\subseteq : $L \in \Sigma_2^P$:

$$x \in L \Leftrightarrow \exists y. \forall z. M(x, y, z)$$

NP^{SAT} :

Guess y .

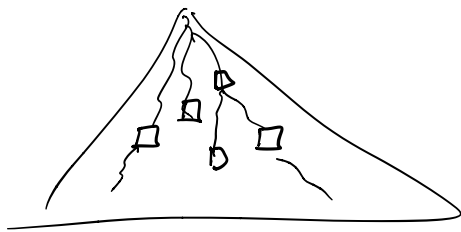
Ask oracle $\exists z. M(x, y, z) = 0$

If oracle says no, you accept.

∴ Main issue: NP^{NP} can make many queries...
 But Σ_2^P feels like a "single query"

Idea: Use the nondeterminism to guess answers when possible.

Let N be an NP^{SAT} machine accepting L .



- ▷ Guess a non-det path of N
- ▷ Guess answers to all queries.
- ▷ Guess assignments for "yes" answers.
- ▷ Confirm "no" answers.

$\exists u_1, \dots, u_m$ $\exists a_1, \dots, a_m$ $\exists r_1, \dots, r_m$ $\forall s_1, \dots, s_m$
 non-det choices of N . answers to oracle queries assignments to "yes" answers for the "TAUT" query

If we run N on the non-det path u_1, \dots, u_m
 and if oracle answers were a_1, \dots, a_m , does N accept x

and: for $i=1 \dots m$

$a_i = 1$ then r_i is a sat-ass. for the i^{th} query.
 $a_i = 0$ then s_i is a falsifying assignment for i^{th} query.

$\Rightarrow L \in \Sigma_2^P$.

□

Thm: $\Sigma_2^P = NP^{NP} = NP^{\Sigma_1^P}$
 For $i \geq 2$ $\Sigma_i^P = NP^{\Sigma_{i-1}^P}$ Which language?
What is a complete problem here?

Σ_2 -SAT = $\{ \text{"} \exists x \forall y \phi(x, y) \text{" : that are true} \}$

Obs: This is complete for Σ_2^P .

Qn: What is a complete problem for PH?

Say $L \in PH$ is a complete problem. $\Rightarrow L \in PH = \cup \Sigma_i^P$

\Rightarrow there is some i : $L \in \Sigma_i$ Any $L' \in PH$ $L' \leq_p L$

But Σ_{i+1} -SAT $\in \Sigma_{i+1} \subseteq PH$

$\Rightarrow \Sigma_{i+1}$ -SAT $\leq_p L \Rightarrow \Sigma_{i+1}^P = \Sigma_i^P$

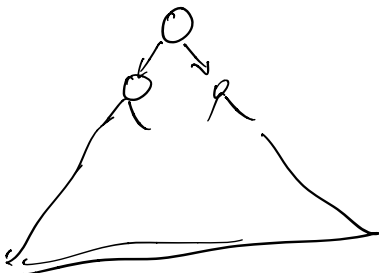
$\Rightarrow PH$ collapses.

If you believe PH does not collapse, then there are no complete problems.

Alternating TMs: (combining non-determinism & co-nondeterminism)

Non-det TM: Accepts an input if some path leads to accept.

Co-nondet TM: Accepts an input if every path leads to accept.

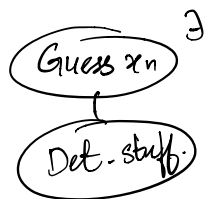
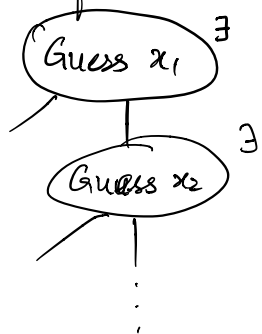


Machine state will determine if it is in a \exists mode or \forall mode.

Alternating TMs: Like regular TMs with potentially two transitions from each configuration. Every state except accept, reject is labelled with either \exists or \forall .

An ATM accepts an input w 

Eg. ATM for SAT.



ATM for TAUT

Replace all states with \forall

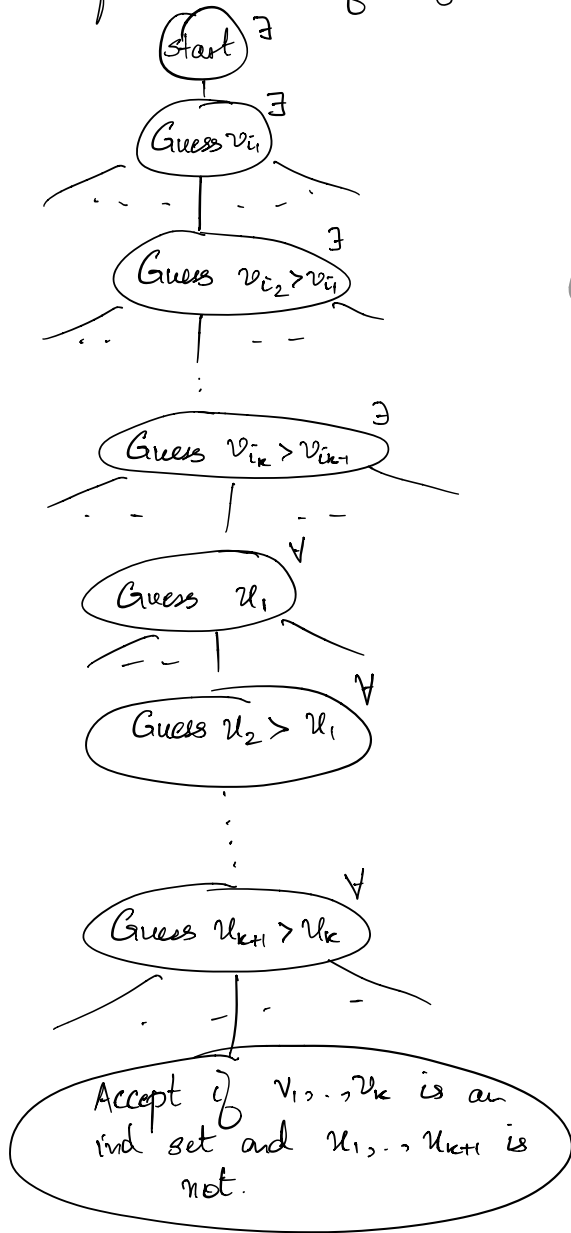
A configuration C is accepting if

▷ C is in Q_{accept} .

▷ If state labelled by \exists , then at least one of its children is accepting.

▷ If state is labelled by \forall , then all its children are accepting.

Eg: ATM for ind. set of size exactly k .



Can also write something similar for Σ_1^P .

$ATIME(t(n)) = \{ L : L \text{ accepted by an ATM running in time } O(t(n)) \text{ in every comp. path} \}$

$ASPACE(s(n)) = \{ L : \text{--- using space } O(s(n)) \text{ in every comp. path.} \}$

$\Sigma_i\text{-Time}(t(n)) = \{ L : \text{acc. by ATM in time } O(t(n)) \text{ but with at most } i \text{ alternations, \& states with } \Sigma \}$.

$$\Sigma_i^P = \bigcup_{c \geq 0} \Sigma_i\text{-TIME}(n^c)$$

(TOBF)

What can you say about $\text{ATIME}(\text{poly}(n))$? PSPACE!

Thm: $\text{NSPACE}(s(n)) \subseteq \text{ATIME}(s(n)^2) \subseteq \text{SPACE}(s(n)^2)$

Pf: \subseteq : Just do a DFS on the computation graph.

\subseteq : Similar to Savitch's theorem.



$\text{Reach}(\text{start}, \text{accept}, T)$

\triangleright Guess (\exists) mid.

\triangleright Guess (\forall) $\left\{ \begin{array}{l} (\text{start}, \text{mid}, T/2) \\ (\text{mid}, \text{accept}, T/2) \end{array} \right\}$

Verify $\text{Reach}(u, v, T/2)$

$$\begin{aligned} \text{AT}(s, T) &= O(s) + \text{AT}(s, T/2) \\ &= O(s \log T) = O(s^2). \end{aligned}$$

□

The connection goes the otherway too.

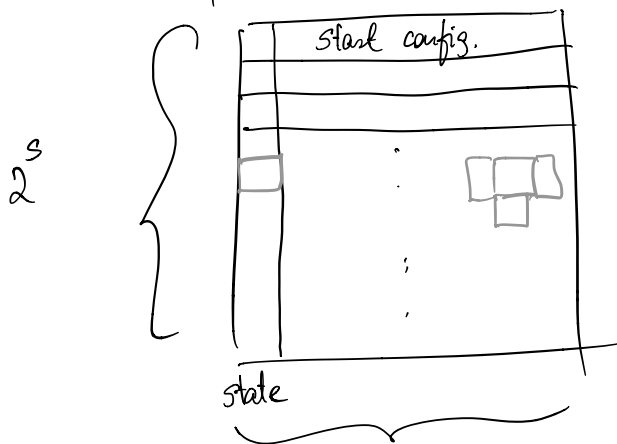
Thm: $\text{ASPACE}(s(n)) = \text{TIME}(2^{O(s(n))})$ if $s(n)$ -space constr.

Pf: \subseteq : Exactly like $\text{space}(s(n)) \subseteq \text{TIME}(2^{O(s(n))})$.

This is easy.

$$2: \text{TIME}(2^s) \subseteq \text{ASPACE}(O(s))$$

Computational Tableau:

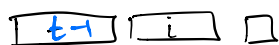


Check $(t, i, \sigma) : 2^s$ Is the i^{th} cell in the t^{th} row σ ?

▷ Guess $(\exists) q, \sigma_1, \sigma_2, \sigma_3$ $O(1)$

▷ Det. verify if $(q, \sigma_1, \sigma_2, \sigma_3) \mapsto \sigma$ $O(1)$

▷ For all: $\text{check}(t-1, 1, q)$ $\log t = s \text{ bits.}$



$\text{check}(t-1, i-1, \sigma_1)$

$\text{check}(t-1, i, \sigma_2)$

$\text{check}(t-1, i+1, \sigma_3)$

How much space are we using? $O(s)$.

◦ $\text{TIME}(2^s) \subseteq \text{ASPACE}(O(s))$.

□.

Given classes like ATIME , ASPACE etc, is there a hierarchy from here?

Yes: If $f(n+1) = o(g(n))$, time const. then

$$\Sigma_k\text{-TIME}(f) \subsetneq \Sigma_k\text{-TIME}(g).$$

Pf exactly the same.

An easier thing to prove:

$$\forall k \geq 1. \quad \Sigma_k\text{-TIME}(f(n)) \not\subseteq \Pi_k\text{-TIME}(o(f(n))).$$

"No complementary speed-up".

An application: Time-space tradeoffs.

Is $\text{NP} = \text{L}$? Probably no.

Does SAT take superpolynomial time? Probably yes.

Suppose I force the TM to only use $\log^2 n$ space.

Can we prove time lower bounds here?

$$\text{TISP}(t(n), s(n)) = \left\{ L : \begin{array}{l} \text{accepted by a TM that with} \\ \text{time bound } t(n) \text{ \& \; space bound } s(n) \end{array} \right\}$$
$$\text{NOT } \text{TIME}(t(n)) \cap \text{SPACE}(s(n))$$

Thm: $\text{NTIME}(n) \not\subseteq \text{TISP}(n^{1.4}, n^{0.01}) \rightarrow$ Next class!

Current best of this type: $\text{NTIME}(n) \not\subseteq \text{TISP}(n^{1.8\dots}, n^{o(1)})$
[Williams].