

# Deterministic Algorithms for Low Individual Degree Factors of Sparse Polynomials

Joint Work with Somnath Bhattacharjee [U of T],  
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**Points to Ponder:**

- ① How are we representing our polynomials?
- ② What does efficient mean?

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- We call  $f \in \mathbb{F}[x_1, \dots, x_n]$  a s-sparse polynomial if  $f$  has at most  $s$  monomials with non zero coefficients. Let  $\|f\|$  := Number of monomials with non zero coefficients.

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- Represent  $f$  by its monomials and coefficients. [Also called Sparse Representation]

- Example:  $f = 10x^{10}y^2 + 17x^3y^5 - 21$  ( $\|f\| = 3$ )  
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- **Question:** Given  $f \in \mathbb{F}[x_1, \dots, x_n]$  an  $s$ -sparse polynomial of degree  $d$ , can we output the list of all factors of  $f$  in time  $\text{poly}(s, n, d)$ ?

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  - ↳ notion of efficiency
- Are factors of  $f$   $\text{poly}(s, n, d)$ -sparse? **Sadly No!**

# Sparsity Blowup of Factors

- Let  $f(x_1, \dots, x_n) = \prod_{i=1}^n (x_i^d - 1)$

then  $\|f\| = 2^n$  and  $\deg(f) = d \cdot n$ .

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- Consider  $g(x_1, \dots, x_n) = \prod_{i=1}^n (1 + x_i + \dots + x_i^{d-1})$ , then  $g|f$

and  $\|g\| = d^n = \|f\|^{\log(d)}$  [GK'85]

- The above example works over fields of any characteristic.

# Sparsity Blowup of Factors

- let  $f(x_1, \dots, x_n) = x_1^p + \dots + x_n^p$  where  $f \in \mathbb{F}_p[x_1, \dots, x_n]$

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- let  $g(x_1, \dots, x_n) = (x_1 + \dots + x_n)^{p-1}$  then  $g \mid f$  and

$$\|g\| = \binom{n+p-1}{p} = \Theta(\|f\|^p) \quad [\text{BSV}'20]$$

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- In this work we consider two relaxations of the problem:

**Relaxation 1:**  $f$  be an  $s$ -sparse polynomial with bounded individual degree  $d$ .

- $f$  has individual degree at most  $d$  if  $\forall i \in [n] \text{ deg}_{x_i}(f) \leq d$ .
- Think  $d = O(1)$  for this relaxation.

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**Relaxation 1:**  $f$  be an  $s$ -sparse polynomial with bounded individual degree  $d$ .

**Relaxation 2:**  $f$  be an  $s$ -sparse polynomial and output all factors of  $f$  which have bounded individual degree  $d$ .

Again think  $d = O(1)$ .

# Bounded Ind. Deg Factorization

- We have  $f \in \mathbb{F}[\bar{x}_n]$  s.t.  $f$  is  $s$ -sparse and has individual degree at most  $d$ .
- [BSV'20]: For any  $g \mid f$ ,  $\|g\| \leq \underline{s^{O(d^2 \log n)}} \quad [\text{Factor Sparsity Bound}]$

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- [BSV'20]:  $s^{O(d^7 \log n)}$  algorithm that computes factorization of  $f$  into irreducible polynomials.
- The algorithmic result is closely tied to factor sparsity bound.
- [Vol'17] conjectured that  $\|g\| \leq \underline{s^{\text{poly}(d)}}$ . If the conjecture is true above algorithm runs in time  $s^{\text{poly}(d)}$

# Bounded Ind. Deg Factorization

- Recently Chuyoon and Shpilka made further progress on the algorithmic aspects.
- [CS'26] proved:
  - ①  $\exists \text{poly}(\underline{s^{d^2 \log n}}, n)$  algorithm which outputs the factorization of  $f$  into its irreducibles.

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②  $\exists \text{poly}(\underline{s^d, d}, n)$  algorithm which outputs all  $s$ -sparse factors\* of  $f$ .

\*  $\rightarrow$  factors not divisible by a monomial.

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- for small  $d$ , can we show  $\exists$  poly( $s^d, n$ ) algorithm to output all factors of  $f$ ?

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- One major hurdle is how to represent factors?
- If polynomial sparsity conjecture were true then we could represent using sparse representation. That is a big if :(

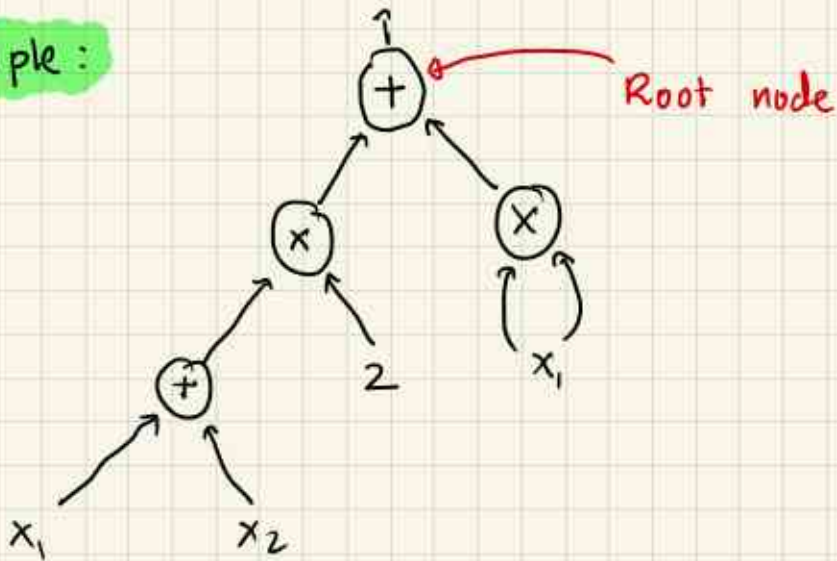
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- In this work, we output factors as constant depth algebraic circuits.

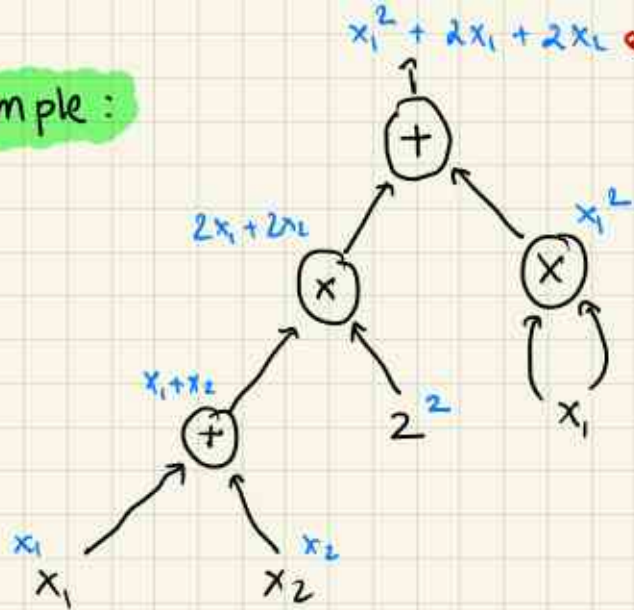
# Algebraic Circuits

- Internal Gates :  $\otimes$   $\rightarrow$  Multiplication Gates  
 $\oplus$   $\rightarrow$  Addition Gates
- Leaf Nodes : Variables, Constants.
- An algebraic circuit is a directed and rooted acyclic graph with internal gates and leaf nodes as defined above.
- No restriction of fan-in/fan-out

Example:



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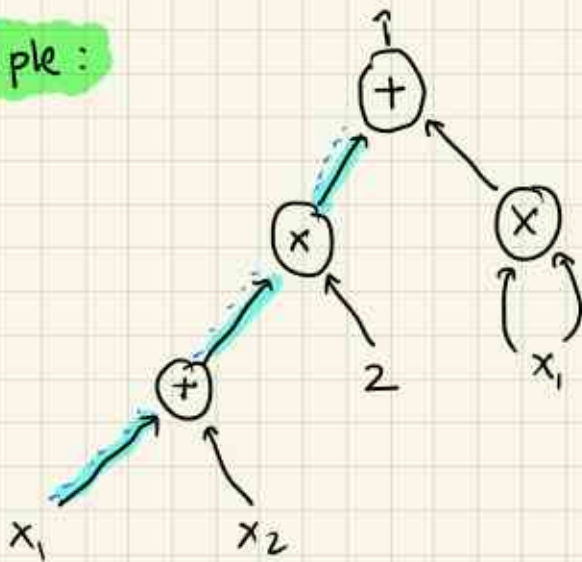
$x_1^2 + 2x_1x_2 + 2x_2^2$  ← Polynomial computed by the circuit.

- Some important measures for algebraic circuits:

\*  $\text{Size}(C) = \# \text{Leaf nodes} + \text{internal gates in the circuit.}$

\*  $\text{Depth}(C) = \text{Length of longest path from root to a leaf node.}$

Example:



Size  $\equiv 8$

Depth  $\equiv 3$

# Factors as Circuit

- Foundational works by Kaltofen [Kal'89], Kaltofen and Trager [KT'90] already gave a poly time randomized algorithm when we allow circuits! This works for general sparse polynomials

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- For general sparse polynomials the best known deterministic algorithms run in subexponential by the works of Bhattacharjee et al [BKRSS'25][BKRRSS'26]
- We believe efficient derandomization exists since this question is equivalent to PIT [VSS'15] (for general ckt)

# Our Results

- ① **Theorem 1:** Let  $f \in \mathbb{F}[\bar{x}_n]$  where  $\text{char}(\mathbb{F}) = 0$  or  $\text{char}(\mathbb{F}) > d$ ,  
be an  $s$ -sparse polynomial of individual degree at most  $d$ .  
There is a  $\text{poly}(sd, d!, n)$  time algorithm that outputs  
a list that contains all factors of  $f$  as constant depth cks. \*\*

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There is a  $\text{poly}(sd, d!, n)$  time algorithm that outputs  
a list that contains all factors of  $f$  as constant depth cts. <sup>\*\*</sup>

\* Factors that are not divisible by any monomial.

\* The list is of size at most  $sd$  and may contain spurious entries.

② **Theorem 2:** Let  $f \in \mathbb{F}[\bar{x}_n]$  be an  $s$ -sparse polynomial of individual degree at most  $D$  (unbounded).

Then  $\exists$   $\text{poly}(D^d \log s, s^d \log n)$  time algorithm that outputs a list containing all factors of  $f$  which have bounded individual degree at most  $d$  (bounded) as constant depth circuits. <sup>\*</sup><sub>\*</sub>

② **Theorem 2:** Let  $f \in \mathbb{F}[\bar{x}_n]$  be an  $s$ -sparse polynomial of individual degree at most  $D$  (unbounded).

Then  $\exists$   $\text{poly}(D \log s, s d^2 \log n)$  time algorithm that outputs a list containing all factors of  $f$  which have bounded individual degree at most  $d$  (bounded) as constant depth circuits. \*\*

\* Factors that are not divisible by a monomial

\* The list is of size at most  $\binom{D}{\leq d} \log s$  and may contain spurious entries.

$$\binom{D}{\leq d} = \sum_{i=0}^d \binom{D}{i}$$

# Technical Ideas

- Plan:
- ① Recap [BSV'20] algorithm for factoring
  - ② Recap new ideas used by [CS'26]
  - ③ Highlight what we did different.

# [BSV'20] Algorithm

- **Input:**  $f \rightarrow s$ -sparse polynomial of bounded individual degree  $\leq d$
- **Step 0:** Prove structural lemma about sparsity of factors of  $f$ .

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- **Step 0:** Prove structural lemma about sparsity of factors of  $f$ .
- **Step 1:** Normalize the Polynomial

• Let  $f(\bar{x}, y) = \sum_{i=0}^t f_i(\bar{x}) y^i$  where  $f_t \neq 0$

$$\hat{f}(\bar{x}, y) = f(\bar{x}, y/f_t) \cdot f_t^{t-1}$$

↑  
Normalization  
of  $f$

- $\|\hat{f}\| \leq s^{O(d)}$  and  $\hat{f}$  has ind. deg at most  $2d$ .

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- **Step 1:** Normalize the Polynomial
- **Step 2:** Factorize the normalized polynomial  $\hat{f}$  into irreducibles

# [BSV'20] Monic Factorization

- Let  $\hat{f}(\bar{x}, y) = h_1(\bar{x}, y)^{e_1} \cdots h_r(\bar{x}, y)^{e_r}$  be its irreducible factorization.
- We project  $\hat{f}$  to a low dimensional space that maintains the factorization pattern. [Takes time  $\text{poly}(s^{d^3} \log s^n)$ ]

Find  $\alpha \in \mathbb{F}^n$  s.t.  $\forall i \neq j, \gcd(h_i(\alpha, y), h_j(\alpha, y)) = 1$ .



$\text{Res}_y(h_i, h_j)(\alpha) \neq 0$ .

$\hat{f}(\alpha, y)$  is the low dimensional polynomial.

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- We project  $\hat{f}$  to a low dimensional space that maintains the factorization pattern.
- Factorize the low dimensional polynomial.  
Just use brute force factorization for this part

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- We project  $\hat{f}$  to a low dimensional space that maintains the factorization pattern.
- Factorize the low dimensional polynomial.
- Reconstruct the irreducible factorization from low dimensional factors.

# [BSV'20] Algorithm

- **Input:**  $f \rightarrow s$ -sparse polynomial of bounded individual degree  $\leq d$
- **Step 0:** Prove structural lemma about sparsity of factors of  $f$ .
- **Step 1:** Normalize the Polynomial
- **Step 2:** Factorize the normalized polynomial  $\hat{f}$  into irreducibles
- **Step 3:** Recursively factor  $f_t(\bar{x})$

[ Remember  $f = \sum_{i=0}^t f_i(\bar{x}) Y^i$  ]

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- **Step 0:** Prove structural lemma about sparsity of factors of  $f$ .
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- **Step 2:** Factorize the normalized polynomial  $\hat{f}$  into irreducibles
- **Step 3:** Recursively factor  $f_t(\bar{x})$
- **Step 4:** Using factorization of  $\hat{f}$  and  $f_t$ , find irreducible factorization of  $f$ . [This reduces to a sparse PIT]

# [CS'26] Optimizations

- Uses the same Step 0 - Step 4 ideas as [BSV'20]. However [CS'26] makes some changes in their implementation.

# [CS'26] Optimizations

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- Step 0: Same as [BSV'20]

- Step 1: Reverse normalize  $f$ .

$$f(\bar{x}, \gamma) = \sum_{i=0}^d f_i(\bar{x}) \gamma^i \quad \text{where } f_0(\bar{x}) \neq 0$$

$$\tilde{f}(\bar{x}, \gamma) = f(\bar{x}, \gamma \cdot f_0) / f_0$$



Reverse normalization of  $f$

$\|\tilde{f}\| = \mathcal{O}(d)$  and  $\tilde{f}$  has individual deg  $2d$ .

# [CS'26] Optimizations

- Step 0: Same as [BSV'20]
- Step 1: Reverse normalize  $f$ .
- Step 2: Find all sparse factors of  $\tilde{f}$ .

The projection to a low dimensional space is implemented differently.

# [CS'26] Optimizations

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- Step 1: Reverse normalize  $f$ .
- Step 2: Find all sparse factors of  $\tilde{f}$ .
- Step 3: Recursively factor  $f_0$
- Step 4: Using factorization of  $\tilde{f}$  and  $f_0$ , recombine them appropriately to find all sparse factors of  $f$ .

# Our Algorithm

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- Step 1: Depending on whether  $\|f_e\|$  is small or  $\|f_o\|$  is small normalize or reverse-normalize the polynomial.

CS's algorithm might need  $n$  layers of recursion but we are cutting it down to  $\log(s)$ .

# Our Algorithm

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- Step 1: Depending on whether  $\|f_e\|$  is small or  $\|f_o\|$  is small normalize or reverse-normalize the polynomial.
- Step 2: Factorize the normalized (or reverse-normalized) polynomial.

Here we again project down to a low dimensional space, but use Hensel lifting / Ruestenberg to find all factors.

Earlier algorithms used sparse reconstruction.

# Our Algorithm

- Step 0: Same as [BSV'20]
- Step 1: Depending on whether  $\|f_e\|$  is small or  $\|f_o\|$  is small normalize or reverse-normalize the polynomial.
- Step 2: Factorize the normalized (or reverse-normalized) polynomial.
- Step 3: Recursively factor  $f_e$  (or  $f_o$ )
- Step 4: Using factors of normalized (or reverse-normalized) polynomial and  $f_e$  (or  $f_o$ ) reconstruct all factors of  $f_o$ .

# Final Remarks

- The unbounded individual degree case also has same algorithmic structure but one major problem we face is that normalization can blow up the sparsity. We use ideas from [CS'26] to deal with the case.

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- The general sparse polynomial case also has same algorithmic structure but one major problem we face is that normalization can blow up the sparsity. We use ideas from [CS'26] to deal with the case.
- Our algorithm recovers the bounded ind. deg results from [CS'26] and [BSV'20].
- Our algorithm recovers the result of finding constant degree factors for general sparse polynomial from [KRS'24], [DST'24]. We prune our list using divisibility testing from [Forbes'15].

# Open Problems

- Can we prune our list of factors efficiently? In particular for an  $s$ -sparse polynomial  $f$  and multilinear polynomial  $g$ , test whether  $g|f$ ?
- Our algorithm does not work over low characteristic. Can we extend it to that setting?