Optimal WiFi Sensing Via Dynamic Programming

Rahul Vaze



Abhinav Kumar Sibi Pillai IIT-Bombay

Aditya Gopalan IISc Bangalore

Roaming Users









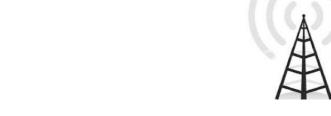








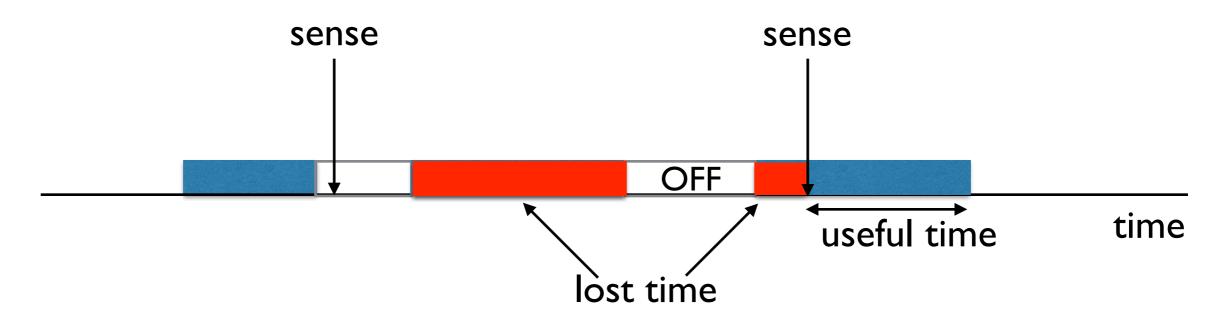








Setup

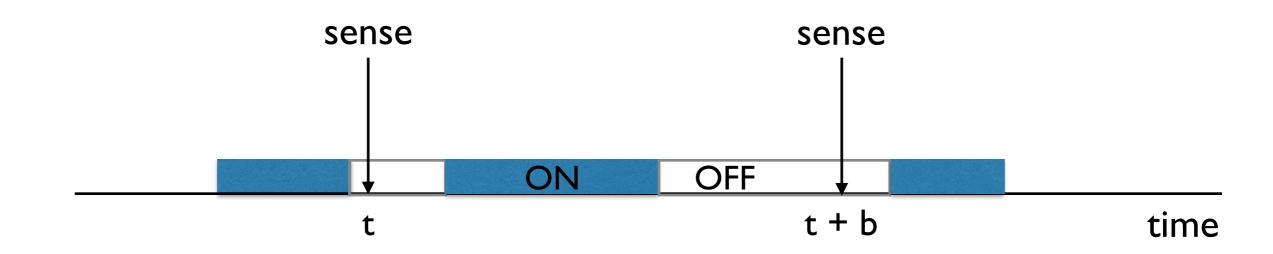


cost

- sensing
- · lost time

Problem: find optimal sensing durations to min cost

Issue

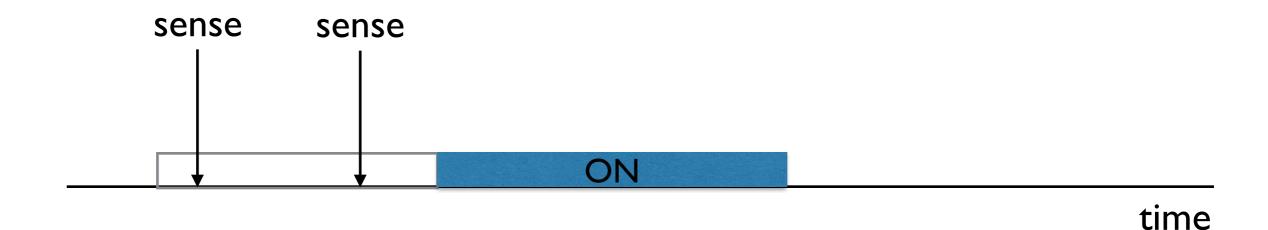


Non-Memoryless OFF time distribution

- algorithm may assume that OFF period is b, which is false

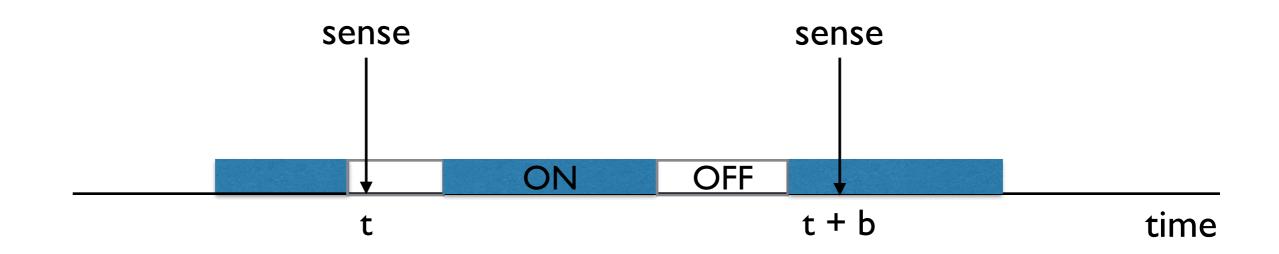
For general problem assume that OFF time ~ EXP

Context



General case of problem studied by Azad et al 2011 where ON period never expires

Earlier work



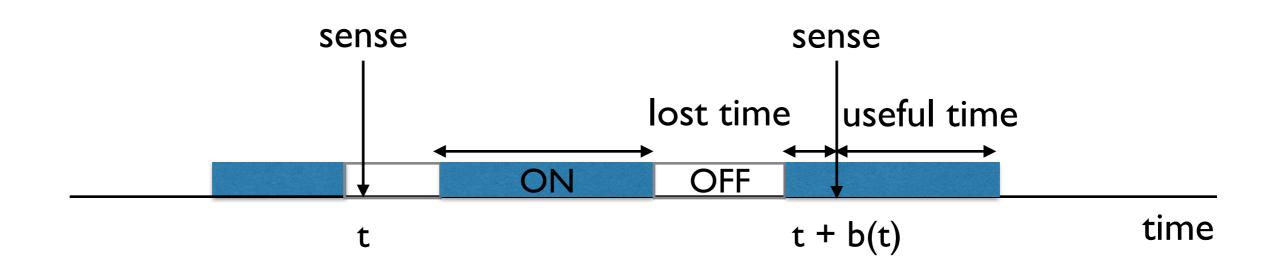
Exp OFF and Exp ON time distribution

- Kim et al, Infocom 2011

General OFF and ON time distribution - simpler cost

- Jeong et al, Infocom 2013

Problem Formulation - OFF time (~EXP)



COST
$$C(t,b(t)) = c_s + M(t,b(t))$$

- sensing c_s
- lost time M(t,b(t)) sensing at (t,t+b(t))

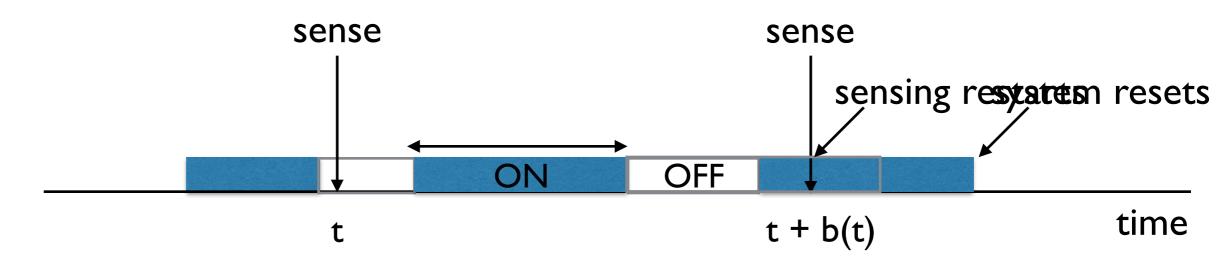
counting restarts

$$V(t) = \max_{b(t) \ge 0} \left[\mathbb{E} \{ C(t, b(t)) \} + P_{\text{off}}(t + b(t) | t \in \text{off}) V(t + b(t)) \right]$$

DP

Problem Formulation - OFF time (~EXP)

Two cases : sense is in ON



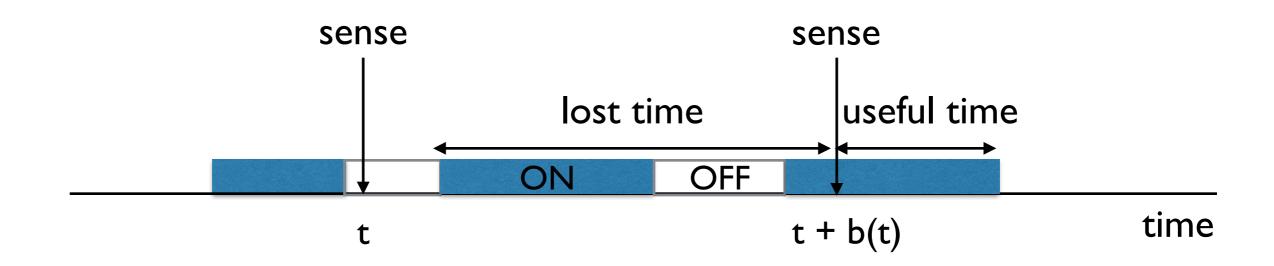
Two cases : sense is in OFF

Cost
$$C(t,b(t)) = c_s + M(t,b(t))$$

counting restarts

$$V(t) = \max_{b(t) \ge 0} \left[\mathbb{E} \{ C(t, b(t)) \} + P_{\text{off}}(t + b(t) | t \in \text{off}) V(t + b(t)) \right]$$

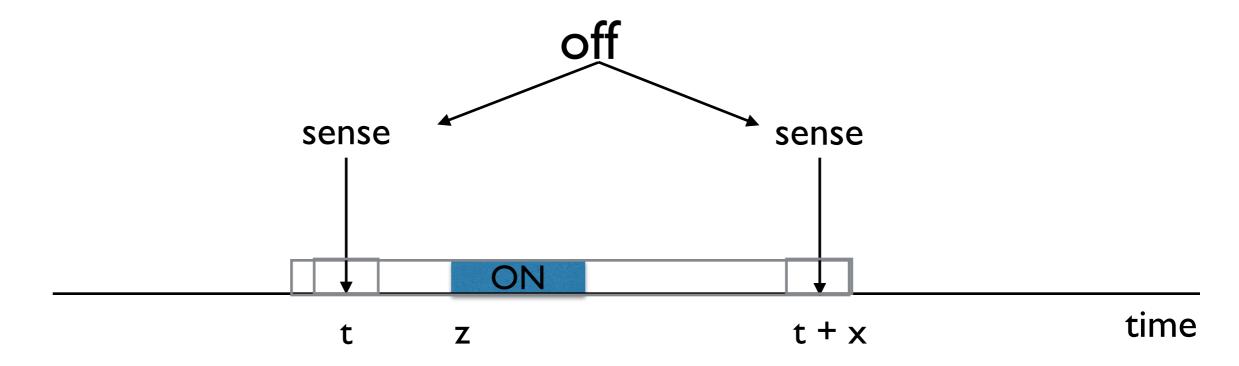
Simple Property



The optimal sensing duration b(t) is independent of t

Because of EXP OFF time, at time t, know nothing about leftover OFF time

Useful Recursions - OFF time (Exp)



either OFF is not over at t

or OFF → ON happened at z >t

$$P_{\text{off}}(t+x|t \in \text{off}) = P(\text{OFF}(t) > x) + \int_0^x f_d(z) P_{\text{off}}(t+x|z\uparrow) dz, z \ge t$$

$$P_{\text{off}}(t+x|t\uparrow) = \int_0^x f_c(w) P_{\text{off}}(t+x|w \in \text{off}) dw, w \ge t$$

Useful Recursions - OFF time (Exp)



Assume that ON \rightarrow OFF happens at 0,

then expected ON time between [0,t] is $M_{\downarrow}(t)=\int_0^t f_d(x)M_{\uparrow}(t-x)dx$

If OFF ightharpoonup ON happens at 0, then expected ON time between [0,t] is $M_{\uparrow}(t)$

$$\mathsf{M}_{\uparrow}(t) = t \int_{t}^{\infty} f_{c}(x) dx +$$

Solution

Use Laplace Transforms

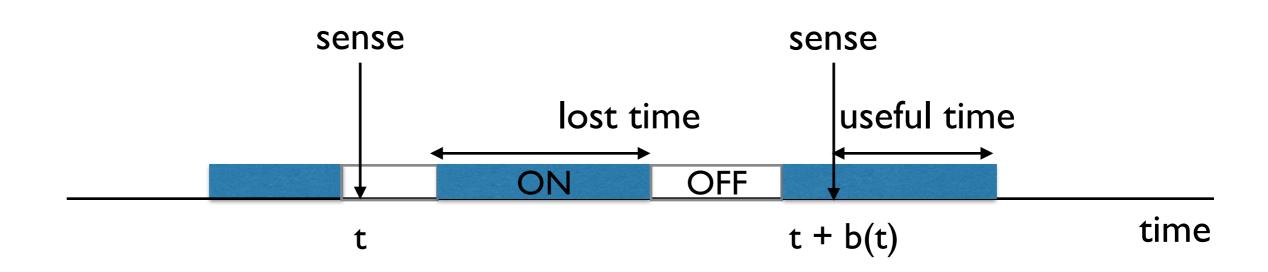
Assume that ON >> OFF happens at 0,

then expected ON time between [0,t] is $M_{\downarrow}(t)=\int_0^t f_d(x)M_{\uparrow}(t-x)dx$

If OFF >> ON happens at 0, then expected ON time between [0,t] is $M_{\uparrow}(t)$

$$M_{\uparrow}(t) = t \int_{t}^{\infty} f_c(x) + \int_{0}^{x} f_d(x) M_{\downarrow}(t-x) dx$$

Solution - OFF time (Exp)



$$Cost C(t,b(t)) = c_s + M(t,b(t))$$

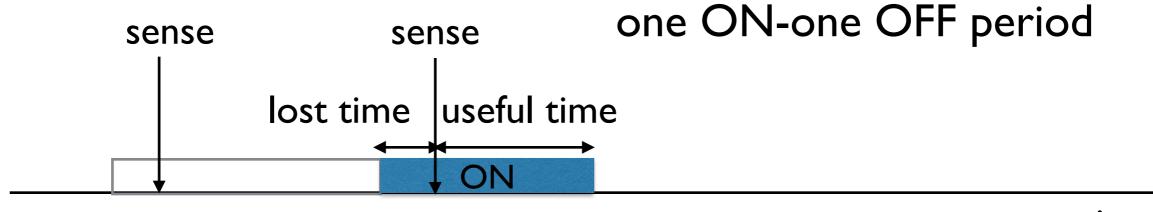
- -sensing c_s
- lost time $M(t,b(t)) = M_{\perp}(b(t))$

counting restarts

$$\mathsf{OP} \qquad V(t) = \max_{b(t) \ge 0} \left[\mathbb{E} \{ C(t, b(t)) \} + P_{\text{off}}(t + b(t) | t \in \text{off}) V(t + b(t)) \right]$$

What about Non-EXP
OFF time

Solution - OFF time (Non-Exp)



time

Critical Assumption

As soon as one full ON period is missed algorithm is notified

counting restarts

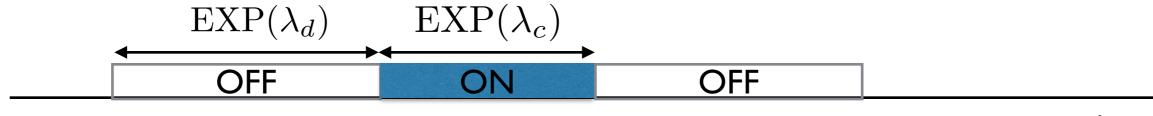
$$DP V(t) = \max_{b(t) \ge 0} \left[\mathbb{E} \{ C(t, b(t)) \} + P_{\text{off}}(t + b(t) | t \in \text{off}) V(t + b(t)) \right]$$

Results - OFF time (Non-Exp)

- Optimal Policy is deterministic
- Value/Policy Iterations converge to optimal
- If residual OFF period distribution converges in time, then the optimal sensing duration converges to a constant

Who gave you the distributions!

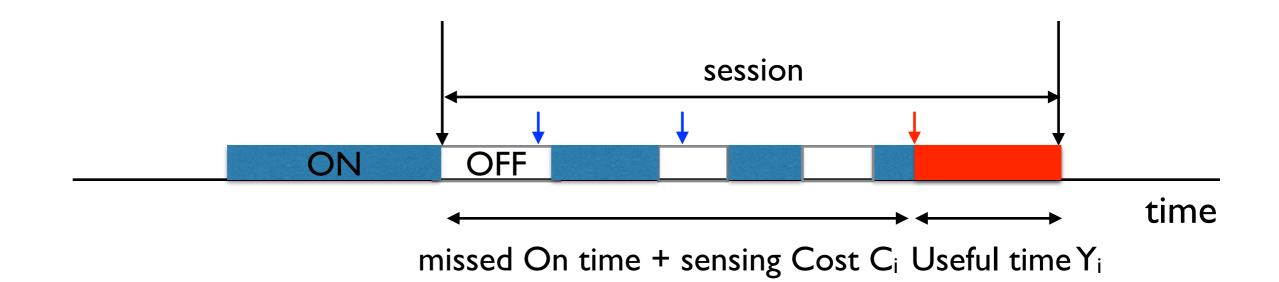
Learning Framework



time

- ON-OFF is EXP with unknown parameters

Session Definition

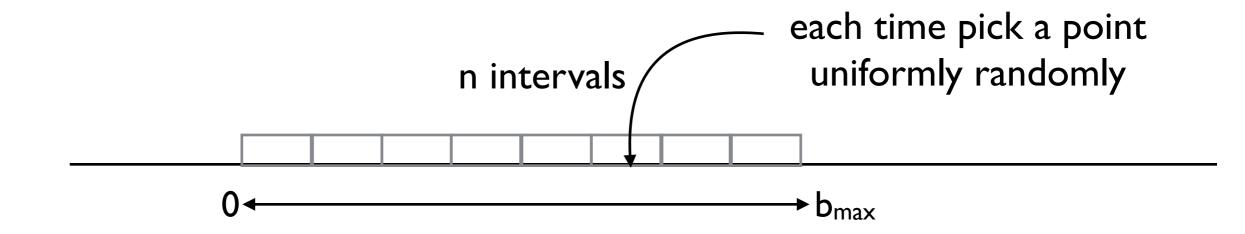


- session reward $U_i = Y_i C_i$
- optimal reward $U_i^* = Y_i^* C_i^*$

- Regret
$$R(T) = \sum_{i=1}^T U_i^* - \sum_{i=1}^T U_i$$

- Objective $\min_b \mathbb{E}\{R(T)\}$

Learning Algorithm



- Empirical reward for interval k until time t is $E_k(t)$

Find
$$k^* = \arg \max_{k=1,...,n} E_k(t) + \sqrt{\frac{2 \ln t}{t_k}}$$

 t_k is the number of times interval k is chosen until time t

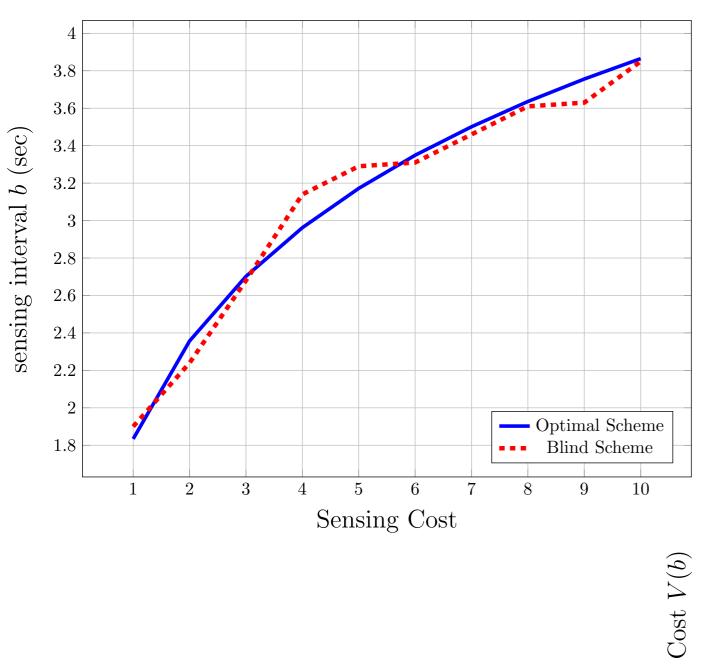
use a uniformly random point from interval k^*

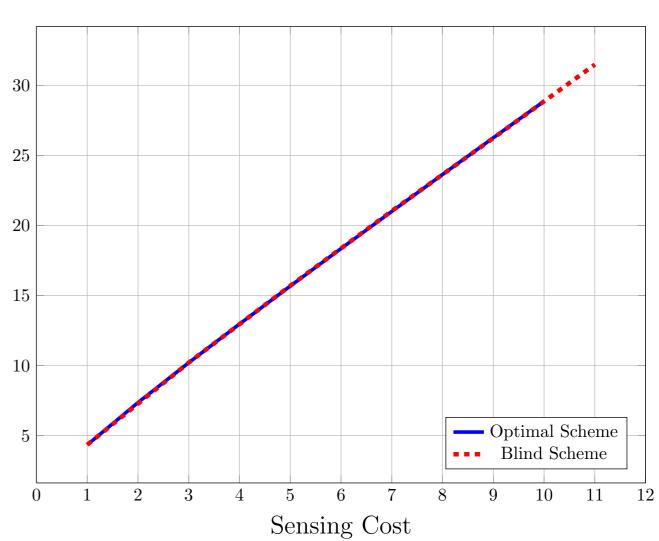
Result

If the number of intervals is $n = \left(\frac{T}{\ln T}\right)^{1/4}$

$$\mathbb{E}\{R(T)\} \le \mathcal{O}(\sqrt{T \ln T})$$

Result

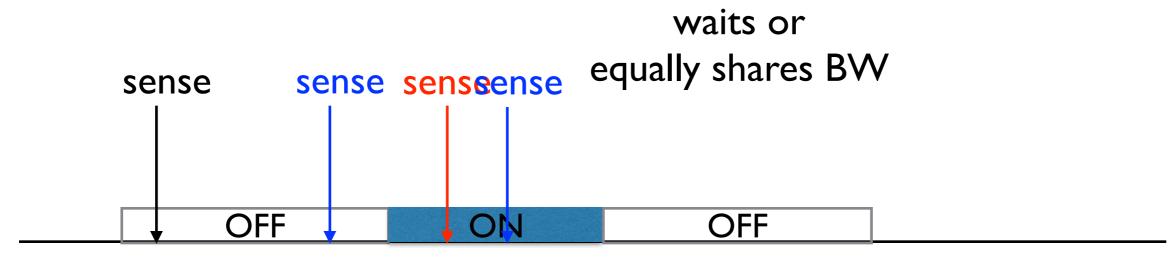




What next!

Multi-user problem with contention

Game Formulation



time







Rahul Vaze teaches at the School of Technology and Computer Science, Tata Institute of Fundamental Research, Mumbai. He obtained his PhD from the University of Texas at Austin. His research interests are in the areas of multiple antenna communication, ad hoc networks, and combinatorial resource allocation. He is the recipient of the Indian National Science Academy's young scientist award for the year 2013.

This book discusses the theoretical limits of information transfer in random wireless networks or ad hoc networks, where nodes are distributed uniformly random in space and there is no centralized control. Examples of ad hoc networks include sensor networks, military networks, and vehicular networks that have widespread applications. Decentralized nature of these networks makes them easily configurable, scalable, and inherently robust.

The author provides a detailed analysis of the two relevant notions of capacity for random wireless networks – transmission capacity and throughput capacity. The book starts with the transmission capacity framework that is first presented for the single-hop model and later extended to the multi-hop model with retransmissions. By reusing some of the tools developed for analysis of transmission capacity, few key long-standing questions about the performance analysis of cellular networks are also addressed for the benefit of students. To complete the throughput capacity characterization, the author finally discusses the concept of hierarchical cooperation that allows the throughput capacity to scale linearly with the number of nodes.

Rahul Vaze teaches at the School of Technology and Computer Science, Tata Institute of Fundamental Research, Mumbai

Cover image source: Kotkoa / Shutterstock





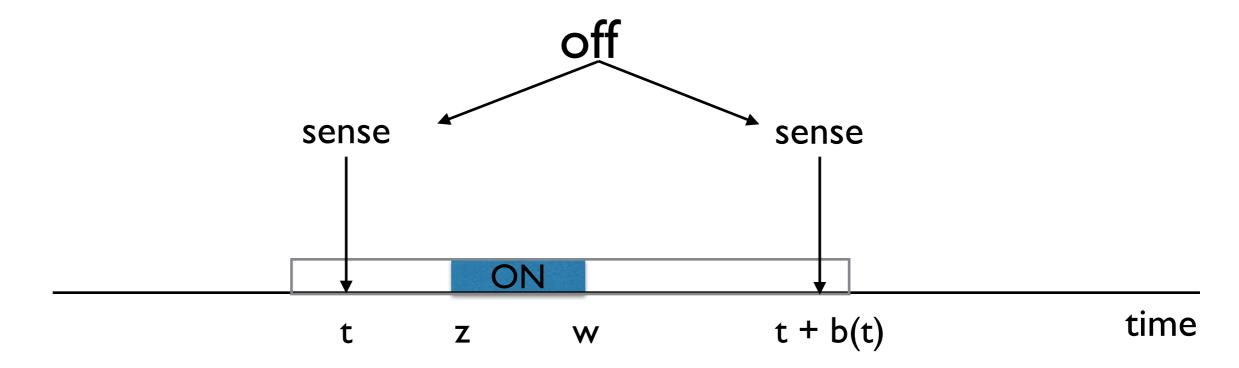
The optimal role of multiple antennas, ARQ protocols, and scheduling protocols in random wireless networks is identified using the transmission capacity paradigm. This book provides a holistic view of all relevant tools and concepts used to analyse random wireless networks. A conscious attempt is made to bring out the connections between transmission and throughput capacity, between percolation theory and throughput capacity, and stochastic geometry and cellular networks. For effective understanding, an extensive effort is made to explain the physical interpretation of all results.

Random Wireless Networks

An Information Theoretic Perspective

Rahul Vaze

Useful Recursions - OFF time (Exp)

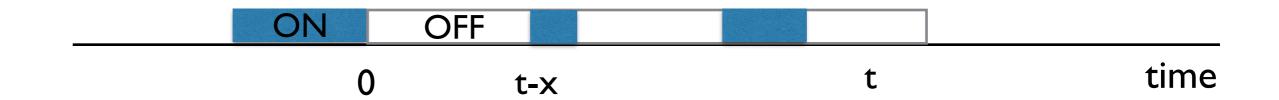


either OFF active at t is not over

or OFF >> ON happened at z >t

$$P_{\text{off}}(t+x|t \in \text{off}) = P(\text{OFF}(t) > x) + \int_0^x f_d(z) P_{\text{off}}(t+x|z\uparrow) dz, z \ge t$$
$$P_{\text{off}}(z+x|z\uparrow) = \int_0^x f_c(w) P_{\text{off}}(z+x|w\in \text{off}) dw, w \ge t$$

Useful Recursions - OFF time (Exp)



Assume that $ON \rightarrow OFF$ happens at 0,

then expected ON time between [0,t] is $M_{\downarrow}(t)=\int_0^t f_d(x)M_{\uparrow}(t-x)dx$

If OFF \rightarrow ON happens at 0, then expected ON time between [0,t] is $M_{\uparrow}(t)$

$$M_{\uparrow}(t) = t \int_{t}^{\infty} f_c(x) + \int_{0}^{t} f_d(x) M_{\downarrow}(t-x) dx$$